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**A Computer Program to Fit a Hyperellipse
to a Set of Phase-Space Points
in as Many as Six Dimensions**

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A COMPUTER PROGRAM TO FIT A HYPERELLIPSE TO A SET OF
PHASE-SPACE POINTS IN AS MANY AS SIX DIMENSIONS

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ABSTRACT

We have written and tested a computer program that will fit a hyperellipse to a set of phase-space points in as many as 6 dimensions. The weight assigned to the phase-space points can be varied as a function of their distance from the centroid of the distribution. By varying the weight, we can determine whether there is a difference in ellipse orientation between inner and outer particles. This program should be useful in studying the effects of longitudinal and transverse phase-space couplings.

I. DERIVATION OF THE EQUATIONS

The equation of a hyperellipse in n dimensions can be written as¹

$$X^T B X = (V_n / K_n)^{2/n} \quad (1)$$

where B is an $n \times n$ dimensional, symmetric matrix having unit determinant, X is the n -dimensional vector of the hyperellipse coordinates, V_n is the n dimensional hyperellipse volume, and K_n is the constant (Γ is the gamma function)

$$K_n = \frac{\pi^{n/2}}{\Gamma(\frac{n}{2} + 1)} \quad (2)$$

Given a set of k phase-space points, we wish to find the shape parameters of a hyperellipse that characterizes the phase-space distribution; that is, the elements of matrix \underline{B} . Define the function

$$\begin{aligned}
 I &= \sum_{i=1}^k \left(v_i / K \right)^m + \frac{nm}{2} \lambda (|B|^{-1}) \\
 &= \sum_{i=1}^k \left(X_i^T B X_i \right)^{nm/2} + \frac{nm}{2} \lambda (|B|^{-1}) \quad (3)
 \end{aligned}$$

The subscript i denotes the i th phase-space point, m is an arbitrary power of the volume, and λ is a Lagrange multiplier. The matrix \underline{B} is symmetric and its determinant is denoted by $|B|$.

Minimize I with respect to λ and the elements of B (B_{jk} with $j \leq k = 1, \dots, n$).

$$\frac{\partial I}{\partial B_{jk}} = \frac{nm}{2} \left[\sum_i \left(X_i^T B X_i \right)^{\frac{nm}{2} - 1} X_i^j X_i^k \left(2 - \delta_{jk} \right) + \lambda \left(\frac{\partial |B|}{\partial B_{jk}} \right) \right] = 0 \quad (4)$$

$$\frac{\partial I}{\partial \lambda} = \frac{nm}{2} (|B|^{-1}) = 0 \quad (5)$$

A vector component of X is denoted by superscripts.

The derivative of the determinant of a matrix by one of its elements is the cofactor of that element.

$$\frac{\partial |B|}{\partial B_{jk}} = C_{jk} + \left(1 - \delta_{jk} \right) C_{kj} = \left(2 - \delta_{jk} \right) C_{jk}$$

where C_{jk} is the cofactor of B_{jk} and is symmetric with respect to an interchange of the indices j and k (because $B_{jk} = B_{kj}$, $C_{jk} = C_{kj}$).

Delta (δ) is the Kronecker delta symbol.

Define

$$b_i = X_i^T B X_i \quad (6)$$

then,

$$\partial I / \partial B_{jk} = \frac{nm}{2} (2 - \delta_{jk}) \left[\sum_i b_i \frac{nm}{2}^{-1} x_i^j x_i^k + \lambda c_{jk} \right] \quad (7)$$

$$\partial I / \partial \lambda = \frac{nm}{2} (|B| - 1) \quad (8)$$

where ($j \leq k = 1, \dots, n$ because of the symmetry of \underline{B}).

We eliminate λ by using the equation for $j = k = 1$

$$\lambda = - \frac{1}{c_{11}} \sum_i b_i \frac{nm}{2}^{-1} (x_i^1)^2 \quad (9)$$

Define

$$J_{jk} = \frac{c_{11}}{\frac{nm}{2} (2 - \delta_{jk})} \partial I / \partial B_{jk} \quad (10)$$

$$J_\lambda = \frac{1}{nm/2} \partial I / \partial \lambda \quad (11)$$

then,

$$J_{jk} = \sum_i b_i \frac{nm}{2}^{-1} \left[c_{11} x_i^j x_i^k - c_{jk} (x_i^1)^2 \right] \quad (12)$$

$$J_\lambda = |B| - 1 \quad (13)$$

where $j \leq k = 1, \dots, n$ and $j + k \neq 2$.

Iterate to solve these equations, using Newton's method. Given the results for the t th iteration, find the results for the $(t+1)$ th.

$$J_{jk}^{t+1} = J_{jk}^t + \sum_{r \leq s=1}^n \partial J_{jk} / \partial B_{rs} \left(B_{rs}^{t+1} - B_{rs}^t \right) \quad (14)$$

$$J_\lambda^{t+1} = J_\lambda^t + \sum_{r \leq s=1}^n \partial J_\lambda / \partial B_{rs} \left(B_{rs}^{t+1} - B_{rs}^t \right) \quad (15)$$

Find new values for the B matrix elements by setting J_{jk}^{t+1} and J_{λ}^{t+1} to zero. We therefore solve the set of equations

$$\sum_{r \leq s=1}^n \left. \frac{\partial J_{jk}}{\partial B_{rs}} \right|_{\substack{B_{rs}^{t+1} \\ B=B^t}} = \sum_{r \leq s=1}^n \left. \frac{\partial J_{jk}}{\partial B_{rs}} \right|_{\substack{- J_{jk}^t \\ B=B^t}} \quad (16)$$

$$\sum_{r \leq s=1}^n \left. \frac{\partial J_{\lambda}}{\partial B_{rs}} \right|_{\substack{B_{rs}^{t+1} \\ B=B^t}} = \sum_{r \leq s=1}^n \left. \frac{\partial J_{\lambda}}{\partial B_{rs}} \right|_{\substack{- J_{\lambda}^t \\ B=B^t}} \quad (17)$$

for B^{t+1} .

Define

$$C_{jk,rs} = \frac{\partial C_{jk}}{\partial B_{rs}},$$

which is the rs cofactor of C_{jk} . Because B is symmetric, we can interchange the row and column indices ($C_{jk,rs} = C_{kj,rs}$) but note that in general $C_{jk,rs} \neq C_{jk,rs}$. We calculate the derivatives in Eqs. (16) and (17) using Eqs. (12) and (13)

$$\frac{\partial J_{jk}}{\partial B_{rs}} = \left(\frac{nm}{2} - 1\right)(2 - \delta_{rs}) \sum_i b_i^{\frac{nm}{2} - 2} x_i^r x_i^s \left[C_{11} x_i^j x_i^k - C_{jk} (x_i^1)^2 \right] \quad (18)$$

$$+ \sum_i b_i^{\frac{nm}{2} - 1} \left[(2 - \delta_{rs}) C_{11,rs} x_i^j x_i^k - (C_{jkrs} + (1 - \delta_{rs}) C_{jksr}) (x_i^1)^2 \right]$$

$$\frac{\partial J_{\lambda}}{\partial B_{rs}} = (2 - \delta_{rs}) C_{rs} \quad (19)$$

Define the matrix \underline{A} and vectors U and V by

$$\underline{A} = \begin{bmatrix} \partial J_{jk} / \partial B_{rs} \\ \partial J_{\lambda} / \partial B_{rs} \end{bmatrix} \quad (20)$$

$$U = \begin{bmatrix} B_{rs} \end{bmatrix} \quad (21)$$

$$V = \begin{bmatrix} J_{jk} \\ J_{\lambda} \end{bmatrix} \quad (22)$$

where $j \leq k = 1, \dots, n$, $j + k \neq 2$ and $r \leq s = 1, \dots, n$. For \underline{A} , jk is a row index and rs a column index. For U and V , both jk and rs are row indices. Equations (16) and (17) can be written as the matrix equations.

$$A^t U^{t+1} = A^t U^t - V^t \quad (23)$$

where the superscripts denote the iteration. Solve these equations by multiplying Eq. (23) on the left by the inverse of A^t , $(A^t)^{-1}$.

$$U^{t+1} = U^t - (A^t)^{-1} V^t \quad (24)$$

Figure 1 contains the computer listing that solves this problem. This routine requires the subroutine COFAC, which is listed in Figure 2.

Case $\frac{nm}{2} = 1$

If we force $nm/2$ to equal 1 in Eq. (3), the problem simplifies considerably. Equations (12) and (13) become

$$J_{jk} = \sum_i \left[C_{11} X_i^j X_i^k - C_{jk} \left(X_i^1 \right)^2 \right] \quad (25)$$

$$J_{\lambda} = |B| - 1 \quad (26)$$

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SUBROUTINE HELIPS(NP,NS,AREXP,X,B,E,XO)
C
C   WRITTEN BY E.A.WADLINGER 8-78
C   UPDATED BY E.A.W. 10/79, TO FIT ARBITRARY POWERS
C   OF THE VOLUME
C
C   FIT A HYPERELLIPSE TO A SET OF PHASE SPACE POINTS
C   MINIMIZE THE SUM  $\sum (X(I, J)B(I, K)X(K, J))^{(AREXP+NS/2)}$ 
C   -  $(E/K)^{AREXP}$ , WITH  $DET(B) = 1$ .
C   SEE IEEE TRANS ON NUCLEAR SCIENCE,
C   VOL. NS-26, NO. 3, P3511, (1979).
C   MAXIMUM OF 6 DIMENSIONS IN HYPERSPACE AND 2000 PARTICLES
C
C   INPUT PARAMETERS
C   NP - NO OF POINTS
C   NS - DIMENSION OF HYPERSPACE
C   X - COORDINATES OF POINTS; DIMENSION X(NS,NP)
C   AREXP - POWER OF THE VOLUME USED IN THE FIT
C   - 0.0, POWER = 2/NS
C   SEE STARRED SECTION FOR LOGIC
C
C   OUTPUT PARAMETERS
C   B - ELLIPSE DEFINING MATRIX
C   E - VOLUME OF THE ELLIPSE
C   XO - CENTROID OF THE DISTRIBUTION
C
C   SUBROUTINES REQUIRED
C   COFAC - PARTIAL DERIVATIVES OF A DETERMINANT
C   DETERM - DETERMINANT OF A MATRIX
C   MATINV - MATRIX INVERSION
C
C   DIMENSION X(6,2000),B(6,6),XO(6)
C   DIMENSION AJ(21),BB(6,6),BX(2000),BXX(2000)
C   DOUBLE PRECISION A(21,21)
C
C   DETERMINE THE CENTROID XO OF THE DISTRIBUTION
C   SHIFT THE PHASE POINTS BY XO
C   DO 10 I = 1,NS
C   SUM = 0.
C   DO 20 J = 1,NP
C   SUM = SUM + X(I,J)
C   20 X0(I) = SUM / NP
C   DO 30 I = 1,NP
C   DO 30 J = 1,NS
C   30 X(I,J) = X(I,J) - X0(I)
C
C   DETERMINE THE STARTING VALUES
C   DO 110 I = 1,NS
C   DO 110 J = 1,NS
C   B(I,J) = 0.0
C   B(J,I) = 0.0
C   110 CONTINUE
C   E0LO = 0.0
C
C   *****
C   SOME OF THE NEXT SEVERAL STEPS ARE FOR PROGRAM PROTECTION
C   SEE STATEMENT LABELED BY 2000
C   WE AVOID THE POSSIBILITY OF RAISING A NEGATIVE NUMBER TO A
C   REAL POWER DURING AN INTERMEDIATE STEP IN THE SEARCH
C   NTST = NS*AREXP - 2.0
C   IF (AREXP .EQ. 0.0) NTST = 0
C   POWR = (NS*AREXP - 4.0) * 0.5
C   IF (POWR .LT. 0.0) POWR = 0.0
C   NPOWR = POWR
C   IF (NTST .NE. 0.0) NTST = (NPOWR + 1)*2
C   *****
C
C   NOW FIT
C   200 IJ = 0
C   CALCULATE THE SUM(K,L) OF  $X(K, I)B(K, L)X(L, I)$ 
C   IF (NTST .EQ. 0) GO TO 405
C   DO 410 I = 1,NP
C   SUM = 0.0
C   DO 420 K = 1,NS
C   DO 420 L = 1,NS
C   420 SUM = SUM + X(K, I)*B(K, L)*X(L, I)
C   2000 BX(I) = SUM**NPOWR
C   410 BXX(I) = BX(I) * SUM
C   GO TO 4
C   405 DO 425 I = 1,NP
C   425 BXX(I) = 1.0
C   CALCULATE A AND AJ
C   415 IJ = 0
C   SUM1 = 0.0
C   DO 435 M = 1,NP
C   435 SUM1 = SUM1 + BXX(M)*X(I, M)*X(I, M)**2
C   C11 = COFAC(NS, I, I, B, 0, 0, 1)
C   DO 430 I = 1,NS
C   DO 430 J = 1,NS
C   FIRST EQUATION WAS USED TO ELIMINATE LAMBDA
C   IF (I .NE. J) .EQ. 2) GO TO 430
C   IJ = IJ + 1
C   C1J = COFAC(NS, I, J, B, 0, 0, 1)
C   SUM2 = 0.0
C   DO 445 M = 1,NP
C   445 SUM2 = SUM2 + BXX(M)*X(I, M)*X(J, M)
C   KL = 0
C   DO 440 K = 1,NS
C   DO 440 L = K,NS
C   KL = KL + 1
C   C1KL = COFAC(NS, I, I, B, K, L, 2)
C   C1JL = COFAC(NS, I, J, B, K, L, 2)
C   IF (K .NE. L) C1KL = 2.0*C1KL
C   IF (K .NE. L) C1JL = 2.0*C1JL
C   A(IJ, KL) = C1KL*SUM2 - C1JL*SUM1
C   IF (NTST .EQ. 0) GO TO 470
C   SUM3 = 0.0
C   SUM4 = 0.0
C   DO 450 M = 1,NP
C   SUM = BX(M)*X(K, M)*X(L, M)
C   SUM3 = SUM3 + SUM*X(I, M)*X(J, M)
C   450 SUM4 = SUM4 + SUM*X(I, M)**2
C   SUM = C11*SUM3 - C1J*SUM4
C   IF (K .NE. L) SUM = 2.0*SUM
C   A(IJ, KL) = A(IJ, KL) + 0.5*SUM*NTST
C   470 CONTINUE
C   440 CONTINUE
C   AJ(IJ) = C11*SUM2 - C1J*SUM1
C   K = IJ + 1
C   A(KL, K) = C1J
C   IF (I .NE. J) A(KL, K) = A(KL, K) + 2.0
C   430 CONTINUE
C   IJ = IJ + 1
C   DO 235 I = 1,NS
C   DO 235 J = 1,NS
C   235 BB(I, J) = B(I, J)
C   AJ(IJ) = DETERM(BB, NS) - 1.0
C   A(IJ, I) = C11
C   INVERT THE A MATRIX
C   CALL MATINV(A, IJ, SUM1)
C   NEW ELLIPSE PARAMETER MATRIX
C   KL = 0
C   DO 240 I = 1,NS
C   DO 240 J = 1,NS
C   SUM = 0.
C   KL = KL + 1
C   DO 250 K = 1,IJ
C   SUM = SUM + A(KL, K) * AJ(KI)
C   B(I, J) = B(I, J) - SUM
C   240 B(I, J) = B(I, J)
C   CALCULATE THE NEW VOLUME
C   SUM = 0.
C   DO 310 I = 1,NS
C   DO 310 J = 1,NS
C   DO 310 K = 1,NP
C   310 SUM = SUM + X(I, K)*B(I, J)*X(J, K)
C   ENEW = SUM
C   IF (ENEW .LT. 0.0) GO TO 200
C   TST = 1.0
C   IF (E0LO .EQ. 0.0) GO TO 320
C   TST = (E0LO - ENEW) / ENEW
C   IF (ENEW .GT. E0LO) TST = (ENEW - E0LO) / E0LO
C   320 E0LO = ENEW
C   IF (TST .GT. .001) GO TO 200
C   E = ENEW / NP
C   AN = NS / 2.0
C   E = E**AN
C   IF (NS .EQ. 2) E = 3.142 * E
C   IF (NS .EQ. 3) E = 4.189 * E
C   IF (NS .EQ. 4) E = 4.935 * E
C   IF (NS .EQ. 5) E = 5.264 * E
C   IF (NS .EQ. 6) E = 5.168 * E
C   RETURN THE PHASE SPACE POINTS BACK TO
C   THE ORIGINAL VALUES
C   DO 40 I = 1,NP
C   DO 40 J = 1,NS
C   40 X(I, J) = X(I, J) + XO(I)
C   RETURN
C   END

```

Fig. 1. Program listing of HELIPS

```

FUNCTION COFAC(N,I,J,A,K,L,MODE)
  WRITTEN BY E.A.WADLINGER 8-78
C
C
C   MODE = 1, DETERMINE THE VALUE OF THE DERIVATIVE OF THE DETERMINANT
C   OF THE MATRIX A WRT A(I,J). THIS IS THE COFACTOR OF THE
C   ELEMENT A(I,J)
C   MODE = 2, DETERMINE THE VALUE OF THE DERIVATIVE OF THE COFACTOR OF
C   A(I,J) WRT THE ELEMENT A(K,L)
C   N = ORDER OF MATRIX A; DIMENSION A(N,N)
C   I,J = SUBSCRIPT FOR A(I,J)
C   K,L = SUBSCRIPT FOR A(K,L)
C
C   SUBROUTINE REQUIRED DETERM = DETERMINANT OF A MATRIX
C   DIMENSION A(6,6),B(6,6)
C
C   IF(MODE=2)10,100,10
C
C   MODE = 1 (NOT 2)
C
10 M = N - 1
   I2 = 0
   DO 20 I1 = 1,N
     IF(I1 .EQ. I)GO TO 20
     I2 = I2 + 1
     I3 = 0
     DO 30 I4 = 1,N
       IF(I4 .EQ. J)GO TO 30
       I3 = I3 + 1
       B(I2,I3) = A(I1,I4)
30 CONTINUE
20 CONTINUE
   I1 = I + J
   COFAC = (-1.)**I1 * DETERM(B,M)
   RETURN
C
C   MODE = 2
C
100 IF(I1 .EQ. K .OR. J .EQ. L)GO TO 200
   M = N - 2
   IF(M .EQ. 0)GO TO 210
   I2 = 0
   DO 120 I1 = 1,N
     IF(I1 .EQ. I .OR. I1 .EQ. K)GO TO 120
     I2 = I2 + 1
     I3 = 0
     DO 130 I4 = 1,N
       IF(I4 .EQ. J .OR. I4 .EQ. L)GO TO 130
       I3 = I3 + 1
       B(I2,I3) = A(I1,I4)
130 CONTINUE
120 CONTINUE
   I1 = I + J + K + L
   IF(I1 .LT. K)I1 = I1 - 1
   IF(I1 .LT. L)I1 = I1 - 1
   COFAC = (-1.)**I1 * DETERM(B,M)
   RETURN
200 COFAC = 0.
   RETURN
210 COFAC = 1.0
   IF(I1 .NE. J)COFAC = -1.0
   RETURN
END

```

Fig. 2. Program listing of COFAC.


```

SUBROUTINE HELIPSNP,NS,X,B,E,X0)
C   WRITTEN BY E.A.WADLINGER 8-78
C   FIT A HYPERELLIPSE TO A SET OF PHASE SPACE POINTS
C   MINIMIZE THE SUM  $\sum_{I,J} |B(I,K)X(I,K) - E/K|^{2/NS}$ 
C   WITH  $DET(B) = 1$ 
C   MAXIMUM OF 6 DIMENSIONS IN HYPERSPACE AND 500 PARTICLES
C
C   INPUT PARAMETERS
C   NP - NO OF POINTS
C   NS - DIMENSION OF HYPERSPACE
C   X - COORDINATES OF POINTS; DIMENSION X(NS,NP)
C   OUTPUT PARAMETERS
C   B - ELLIPSE DEFINING MATRIX
C   E - VOLUME OF ELLIPSE
C   X0 - CENTROID OF THE DISTRIBUTION
C   SUBROUTINES REQUIRED
C   COFAC - PARTIAL DERIVATIVES OF A DETERMINANT
C   DETERM - DETERMINANT OF A MATRIX
C   MATINV - MATRIX INVERSION
C
C   DIMENSION X(6,500),B(6,6),X0(6)
C   DIMENSION X1J(6,6),AJ(21),BB(6,6)
C   DOUBLE PRECISION A(21,21)
C
C   DETERMINE THE CENTROID X0 OF THE DISTRIBUTION AND OTHER FIXED
C   CONSTANTS
C   DO 10 I = 1,NS
C   SUM = 0.
C   DO 20 J = 1,NP
C   20 SUM = SUM + X(I,J)
C   10 X0(I) = SUM / NP
C   DO 30 I = 1,NS
C   DO 30 J = 1,NS
C   SUM = 0.
C   DO 40 L = 1,NP
C   FX1 = X(I,L) - X0(I)
C   FX2 = X(J,L) - X0(J)
C   40 SUM = SUM + FX1*FX2
C   X1J(I,J) = SUM
C   30 X1J(J,I) = SUM
C
C   DETERMINE THE STARTING VALUES FOR THE ELLIPSE MATRIX
C   DO 110 I = 1,NS
C   DO 110 J = 1,NS
C   B(I,J) = 0.0
C   B(J,I) = 0.0
C   IF(I.EQ. J)B(I,I) = 1.0
C   110 CONTINUE
C   EOLD = 0.0
C
C   NOW FIT
C   200 IJ = 0
C   DO 210 I = 1,NS
C   DO 210 J = 1,NS
C   IF(IJ.NE. J) .EQ. 210 TO 210
C   IJ = IJ + 1
C   KL = 0
C   DO 220 K = 1,NS
C   DO 220 L = K,NS
C   KL = KL + 1
C   C1 = COFAC(NS,I,J,B,K,L,2)
C   IF(K.NE. L)C1 = 2.*C1
C   C2 = COFAC(NS,I,J,B,K,L,2)
C   IF(K.NE. L)C2 = C2 * COFAC(NS,I,J,B,L,K,2)
C   220 A(IJ,KL) = X1J(I,J) * C1 - X1J(I,I) * C2
C   210 CONTINUE
C   IJ = IJ + 1
C   KL = 0
C   TMP = COFAC(NS,I,I,B,0,0,1)
C   DO 230 K = 1,NS
C   DO 230 L = K,NS
C   KL = KL + 1
C   A(IJ,KL) = COFAC(NS,K,L,B,0,0,1)
C   A(JKL) = -X1J(I,I)*A(IJ,KL) + TMP*X1J(K,L)
C   IF(K.NE. L)A(IJ,KL) = 2. * A(IJ,KL)
C   230 CONTINUE
C   DO 235 I = 1,NS
C   DO 235 J = 1,NS
C   235 BB(I,J) = B(I,J)
C   J = IJ - 1
C   FIRST EQUATION WAS USED TO ELIMINATE LAMBDA
C   DO 237 I = 1,J
C   237 A(J,I) = A(I,I)
C   A(I,J) = DETERM(BB,NS) - 1.0
C   CALL MATINV(A,IJ,DETERM)
C   NEW ELLIPSE PARAMETER MATRIX
C   KL = 0
C   DO 240 I = 1,NS
C   DO 240 J = 1,NS
C   SUM = 0.
C   KL = KL + 1
C   DO 250 K = 1,IJ
C   250 SUM = SUM + A(KL,K) * A(JK)
C   B(I,J) = B(I,J) - SUM
C   240 B(J,I) = B(I,J)
C   CALCULATE THE NEW VOLUME
C   SUM = 0.
C   DO 310 I = 1,NS
C   DO 310 J = 1,NS
C   310 SUM = SUM + B(I,J) * X1J(I,J)
C   ENEW = SUM
C   IF(ENEW.LT. 0.0100 TO 200
C   TST = 1.0
C   IF(EOLD .EQ. 0.0100 TO 320
C   TST = (EOLD - ENEW) / ENEW
C   IF(ENEW.GT. EOLD)TST = (ENEW - EOLD) / EOLD
C   320 EOLD = ENEW
C   IF(TST.GT. .001100 TO 200
C   E = ENEW / NP
C   AN = NS / 2.0
C   E = E**AN
C   IF(NS.EQ. 2)E = 3.142 * E
C   IF(NS.EQ. 3)E = 4.189 * E
C   IF(NS.EQ. 4)E = 4.935 * E
C   IF(NS.EQ. 5)E = 5.264 * E
C   IF(NS.EQ. 6)E = 5.168 * E
C   RETURN
C   END

```

Fig. 3. Program Listing of HELIPS.

and Eq. (18) for the derivatives becomes

$$\partial J_{jk} / \partial B_{rs} = \sum_i \left\{ (2 - \delta_{rs}) C_{11,rs} X_i^j X_i^k - [C_{jkrs} + (1 - \delta_{rs}) C_{jksr}] (X_i^1)^2 \right\} \quad (27)$$

Equations (20) through (24) still apply. Figure 3 contains the listing of the computer program that utilizes these formula. This program is significantly faster than that of Figure 1. In two dimensions, the equations in this section reduce to solving the rms ellipse equations.¹

II. RESULTS AND CONCLUSIONS

The appendix describes some tests of these computer routines. The routines in all cases perform as expected.

III. REFERENCES

1. "General Least-Squares Fitting Procedures to Minimize the Volume of a Hyperellipsoid," E. A. Wadlinger, 1979 Linear Accelerator Conf. Proc., Brookhaven.

APPENDIX

We made many tests to check the performance of the two different hyperellipsoid fitting routines. With one set of tests, we generated phase-space distributions with known shapes and then used the computer routines to fit hyperellipsoids to these distributions. The fitted hyperellipsoid shapes agreed with that expected within statistics. Figure A.1 lists the results for one particular case; Fig. A.2 lists the computer test routine. Various possible tests of the hyperellipsoid fitting routines are indicated in the listing.

The phase-space points were generated randomly in an n dimensional, rectangular volume with faces perpendicular to the axes of the hyperspace. The phase-space points were then rotated by an orthogonal matrix U to give the

rectangular volume an arbitrary orientation in space. The orthogonal matrix was generated by using a random number generator to produce arbitrary vectors that were then orthogonalized by the Schmidt procedure.

We generated 2000 phase-space points for the run shown in Fig. A.1. We required that $nm/2 = 2$. We show in the figure the orthogonal matrix \underline{U} that was used to generate the expected ellipse. The terms in the fitted ellipse shown in the figure should be compared to those of the expected ellipse. We multiplied the fitted ellipse by \underline{U}^T (the transpose of the orthogonal matrix \underline{U}) to obtain the transferred fitted ellipse. The matrix is diagonal for a perfect fit. The diagonal elements of the matrix can be compared with the list of expected diagonal terms. The off-diagonal elements are reasonably small compared to the diagonal terms. An estimate of the expected statistical accuracy can be inferred from the coordinates for the centroid of the distribution, which were expected to be zero.

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ORTHOGONAL MATRIX (U)
.395E+00 -.431E-01 .675E+00 .558E+00 -.895E-01 .258E+00
.648E+00 -.228E+00 -.855E-01 -.227E-01 .158E+00 -.704E+00
.536E+00 .281E+00 -.585E+00 .113E+00 -.356E+00 .390E+00
.203E+00 .238E+00 .430E+00 -.708E+00 -.464E+00 -.239E-01
.309E+00 -.123E+00 .473E-01 -.399E+00 .700E+00 .488E+00
.427E-02 .892E+00 .872E-01 .119E+00 .368E+00 -.217E+00

EXPECTED ELLIPSE (U * O)
.835E+00 .552E-01 -.121E+00 -.272E+00 .104E+00 .183E+00
.552E-01 .181E+01 .121E+00 .976E-01 .244E+00 -.282E+00
-.121E+00 .121E+00 .766E+00 -.356E+00 .325E-01 -.143E+00
-.272E+00 .976E-01 -.356E+00 .108E+01 .201E-02 -.252E+00
.104E+00 .244E+00 .325E-01 .201E-02 .152E+01 .205E+00
.183E+00 -.282E+00 -.143E+00 -.252E+00 .205E+00 .999E+00

FITTED ELLIPSE (EF)
.896E+00 .568E-01 -.128E+00 -.236E+00 .119E+00 .168E+00
.568E-01 .180E+01 .105E+00 .998E-01 .253E+00 -.304E+00
-.128E+00 .105E+00 .762E+00 -.374E+00 .427E-01 -.123E+00
-.236E+00 .998E-01 -.374E+00 .106E+01 -.424E-02 -.265E+00
.119E+00 .253E+00 .427E-01 -.424E-02 .148E+01 .183E+00
.168E+00 -.304E+00 -.123E+00 -.265E+00 .183E+00 .988E+00

EXPECTED DIAGONAL TERMS (D)
.3340E+00 .6680E+00 .1002E+01 .1336E+01 .1670E+01 .2004E+01

TRANSFORMED FITTED ELLIPSE (U-TRANSPOSE * EF)
.335E+00 .274E-01 .165E-01 .304E-02 .221E-01 -.127E-01
.274E-01 .701E+00 .394E-01 -.200E-01 .899E-02 .284E-01
.165E-01 .394E-01 .101E+01 -.197E-01 -.345E-02 .866E-02
.304E-02 -.200E-01 -.197E-01 .130E+01 .224E-01 -.125E-02
.221E-01 .899E-02 -.345E-02 .224E-01 .164E+01 -.115E-01
-.127E-01 .284E-01 .866E-02 -.125E-02 -.115E-01 .200E+01

CENTROID OF THE DISTRIBUTION
.3709E-02 -.3175E-02 .1874E-01 .1164E-01 -.4445E-02 -.1958E-01

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Fig. A-1. Results for fitting a hyperellipse to a set of phase space points.

