

122 PRESSURE TRANSIENTS RESULTING FROM SODIUM-WATER REACTION FOLLOWING A LARGE LEAK IN LMFBR STEAM GENERATOR

A.K. RAJPUT
Reactor Research Centre,
Kalpakkam
India

1.0 INTRODUCTION

Tube defects in Liquid Metal Fast Breeder Reactors(LMFBR) steam generator produces sodium water reaction. Defects of steam generator heat transfer tube containing high pressure steam or water can range from a pin hole crack to a full bore rupture. The major causes⁽¹⁾ of such defects have been singled out as flow induced vibrations and poor quality of welds.

In most cases an efficient leak detection system, monitoring the products of reaction in secondary circuit, can give an early warning of the leakage of water from a pin hole crack, before it itself develops into a full bore opening or causes adjacent tubes to develop similar rupture as a result of wastage phenomenon. However, a design basis accident is postulated as an instantaneous full bore rupture(guillotine failure) of a number of tubes or a single tube. The criterion for multiple tube failure relies on the phenomenon of adjacent tube wastage. Based on the experiments on sodium water reaction at different test facilities, Robin et.al.⁽²⁾ concluded that adjacent tube wastage can be kept to a minimum if pitch is approximately twice the tube outside diameter. Hence, failure of a single tube has been taken as the design basis accident.

The study of sodium water reaction, following a large leak, concerns primarily with the estimation of pressure/flow transients that are developed in the steam generator and the associated secondary circuit. This paper describes the mathematical formulations used in SWRT(Sodium Water Reaction Transients) code developed to estimate such

pressure transients for FBTR plant. The results, obtained using SWRT have been presented for a leak in economiser(20m from bottom water header) and for a leak in super heater portions. A time lag of 50 msec was considered for rupture disc takes to burst once the pressure experienced by it exceeds the set value.

Also described in annexure to this paper is the mathematical formulation for two phase transient flow for the better estimation of leak rate from the ruptured end of the damaged heat transfer tube. This leak model considers slip but assumes thermal equilibrium between the liquid and vapour phases.

2.0 SODIUM WATER REACTION ANALYSIS FOR FBTR⁽³⁾

Following guillotine failure of tube containing steam/water, pressures on the shell side of the steam generator(Fig.2) and associated secondary sodium circuit(Fig.3) exhibit a sudden increase. These pressure relief device, pressure and temperature of water, presence of secondary circuit components such as surge tank, pump etc., apart from the nature of chemical reaction. The task of predicting the functional relationships between these parameters produced the 'Sodium Water Reaction Transients' Computer Code 'SWRT' for the FBTR steam generator and associated secondary circuit.

2.1 Assumptions

The SWRT Code is an initial attempt to solve a complex problem. As in any computer code, idealisations have been made which depart from rigorous reality. Any departures from reality are believed conservative for the purpose of assessing the safety of steam generator shell and other crucial components. It is hoped that the analysis can be improved by reassessing some of those idealisations, such as,

1. Total guillotine failure of a single tube.
2. Chemical rate of sodium-water reaction much higher than the rate of steam/water influx, such that rate of energy influx is proportional to the later.
3. Reaction produces all oxides.

4. One dimensional, piston like, adiabatic growth of hydrogen bubble, since, shell diameter of FBTR steam generator is quite small (≈ 177 mm).
5. Hydrogen in bubble behaves like that of an ideal gas.
6. One dimensional transients flow of sodium in secondary circuit and steam generator.
7. Magnitude of the pressure waves is such that no appreciable changes in the physical properties of sodium are caused. Hence, the wave propagation velocity roughly remains constant.
8. Adiabatic compression or expansion of argon cover gas in surge tank and expansion tank cum pump, because, in a short duration transients, practically no heat can be exchanged between cover gas control volume and its surroundings.
9. Pump speed remains unchanged during the study period of the transients (~ 500 msec) because of high inertia of rotating parts.
10. Steam/water influx from both the ruptured ends of pipe.
11. Inertia controlled flow of water in water tube for leak in economiser/evaporator portion.
12. Fano flow model for steam leak for rupture in superheater portion.

2.2 Pressure Wave Propagation

Hydrogen generated as a result of sodium water reaction, fills, instantaneously and completely the cross-section of steam generator shell and starts pushing sodium upstream and downstream of the reaction site (Fig.4). Pressure waves emanating from sodium hydrogen interfaces of the bubble get transmitted throughout the secondary circuit and interact with its components like sodium headers on top/bottom of steam generator, surge tank, pump discharge point and expansion tank inlet etc. This

phenomenon of pressure wave propagation is described Mathematically⁽⁴⁾ by the simultaneous solution of one-dimensional transient equations of

mass balance:

$$\frac{\partial b}{\partial t} + v \cdot \frac{\partial b}{\partial x} + \frac{\rho a^2}{\rho_f} \frac{\partial v}{\partial x} = 0 \quad (1)$$

and momentum balance:

$$\frac{\partial v}{\partial t} + v \cdot \frac{\partial v}{\partial x} + \frac{g}{\rho} \frac{\partial b}{\partial x} + \frac{f \cdot v \cdot |v|}{2 D_i} = 0 \quad (2)$$

utilising the 'method of characteristics' with appropriate boundary conditions described by circuit components. The velocity of pressure wave propagation

$$\alpha = c \sqrt{1 + \frac{k}{E} \frac{D_i}{t}} \quad (3)$$

is lower than the sonic velocity 'C', because a part of its energy is expended in straining the pipe material.

2.3 Thermo-hydraulics of Reaction Site

The culprit responsible for the aforementioned pressure waves, is the growing high pressure hydrogen bubble and is analysed by a set of thermo-hydraulic relations describing its pressure, temperature and growth rate etc., together with leak rate models. Application of first Law of Thermodynamics and ideal gas equation of state to hydrogen in the bubble yields

$$\frac{dP}{dt} = \frac{1}{V} \left\{ \frac{R T_0}{M} \cdot RCF \cdot \frac{dm}{dt} - (1+x) \cdot P \cdot \frac{dV}{dt} \right\} \quad (4)$$

$$\frac{dT}{dt} = \frac{T_0 - T}{m} \frac{dm}{dt} - x \frac{T}{V} \frac{dV}{dt} \quad (5)$$

the relations describing its pressure and temperature behaviour at any time 't'. The rate of energy liberation in the hydrogen bubble depends on the rate of sodium water reaction which is proportional to the water leak rate. Of the total reaction generated heat, the energy that expends itself in generating pressure waves is represented by the bubble

expansion rate

$$\frac{dV}{dt} = S \left\{ \frac{dL}{dt} + \frac{dL_i}{dt} \right\} \quad (6)$$

dependent on sodium-hydrogen interface velocities,

$$\frac{dL}{dt} = -VNDI + \frac{g_c}{\rho a} (P - PNDI) + \frac{f \cdot \delta t}{2 \cdot D_i} * VNDI * |VNDI| \quad (7)$$

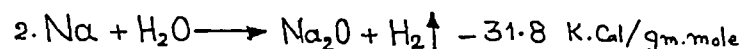
$$\frac{dL_i}{dt} = +VMDI + \frac{g_c}{\rho a} (P - PMDI) + \frac{f \cdot \delta t}{2 \cdot D_i} * VMDI * |VMDI| \quad (8)$$

which in turn are controlled by pressure differences inside and outside the bubble.

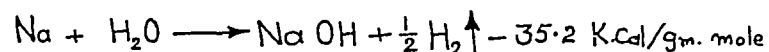
The effect of nature of reaction on bubble pressure is through 'Reaction Controlling Factor'.

$$RCF = \frac{\left(\frac{m'}{M'}\right)}{\left(\frac{m}{M}\right)} \quad (9)$$

which is the ratio of moles of hydrogen produced to the moles of water burnt. For reaction (in excess sodium and temperature > 320°C)



leading to oxide formation, RCF is unity. This gives more amount of hydrogen produced and hence the higher bubble pressure than the reaction



leading to hydroxide formation where RCF is one half. However, experiments⁽⁵⁾ done by Green show that RCF is 0.6 i.e. more towards reaction leading to hydroxide formation.

2.4 Leak Rates

Various leak rate models exist for leak rate of water and that of steam for rupture in economiser and superheater portions respectively.

2.4.1 Leak in Economiser

2.4.1.1 Water leak model

Analytical models exist that predict the maximum two phase flow of saturated steam/water through tubes. A critical velocity exists at which the flow chokes at minimum area, or the tube exist, limiting the mass flow rate through the ruptured ends. Provided the external pressure is less than some specific limit, the mass flow rate is a function of the source pressure, length of tube, and the area of rupture. Although the maximum flow rate of water is predictable for a given set of conditions, the manner of reaching this maximum flow rate is not. Three simple models for predicting the flow rates upto critical velocity have been shown in Fig.5.

1. 'Conservative' model: An ultra conservative estimate of the quantity of water injected over the initial period would be obtained by assuming choked flow exists instantaneously.
2. 'Suttering flow' model: When the tube fails, the water leaps to some velocity through the rupture. This velocity is maintained while an expansion wave travels along the tube, gets reflected from water header, and approximately doubles the rupture exit velocity every time the reflected wave returns to the rupture site.
3. 'Inertia Controlled' model: This model assumes the fluid to be incompressible and considers forces acting on an element of water in the tube. Water leaks from both the ruptured ends and accelerates upto critical velocity given by Zoludek's relation⁽⁶⁾.

The velocity of sound in water is 1200 m/sec, so the transit time for the expansion wave to return to the rupture site has a minimum of 0.833 m.sec/m run of the tube. For a break at 20 m from bottom water header, the transit time would be 33.3 msec. In two phase mixtures, sonic velocity reduces to a very low value. This would give even longer transit times, and the stuttering flow model would predict very low flow rates for a long period following the rupture.

The first model, assuming choked flow exists immediately following rupture, is ultra conservative and unrealistic in view of the expected transit times for the waves in the tube. The 'inertia controlled' flow model is a reasonable compromise between other two models and has been adopted in SMTT code. Balance of inertia forces with pressure forces, body forces, and frictional resistances,

$$\frac{dq_u}{dt} = \frac{g_c A}{L_u} \left\{ (P_{H_u} - P_{E_u}) + \frac{g}{g_c} \cdot \rho_u \cdot \Delta z_u - k_u q_u^2 \right\}$$

$$\frac{dq_d}{dt} = \frac{g_c A}{L_d} \left\{ (P_{H_d} - P_{E_d}) - \frac{g}{g_c} \cdot \rho_d \cdot \Delta z_d - k_d q_d^2 \right\}$$

describe the manner in which the water flow in upstream and downstream portions of the ruptured tube is accelerated upto choked flow limit. Flashing of water occurs at the broken ends if bubble pressure is less than the saturated pressure of water. Zoludel's relation⁽⁶⁾ gives the choked flow rate through the broken ends

$$q = A \sqrt{2 \cdot g_c \cdot \rho \cdot \left\{ P_E - (1 - c) P_{sat} \right\}}$$

$$c = 0.284 \frac{\sigma(T_w)}{\sigma(196)}$$

2.4.1.2 SMTT results for water leak

Results have been obtained by simultaneous solution of leak rate expressions and thermo hydraulic equations for reaction site together with equations describing pressure wave propagation in secondary circuit. Following a leak in the economizer portion, 20 m from bottom water header, water gushes out from both the ruptured ends. Shown in Fig.6 are the leak rates from upstream and downstream ends of the ruptured tube. Water flow accelerates upto a choked flow limit in a time of about 200msec and during initial periods water flow rate is lower than this limit, because of its inertia and the frictional resistance it experiences inside the tube. The choked flow limit of

6.42 kg/sec for water flow rate in the downstream portion of the ruptured tube is higher as compared to the corresponding limit of 1.65 kg/sec in the upstream portion. The short tube length of the downstream portion of the ruptured tube, hence, lesser amount of friction and higher water header pressure are the parameters which can be held responsible for this difference in choked flow limits. The fast acceleration of water flow, in the relatively shorter downstream portion of the ruptured tube, can be attributed to lower inertia of water which is proportional to tube length.

One would expect the leak rate to go down as the hydrogen bubble pressure builds up with time. In this case it had no effect on the flow rates, since, the saturation pressure of 100 kgf/cm² corresponding to the water temperature of 310°C at the leak location was always higher than the bubble pressure and choked flow conditions existed throughout. Ofcourse, if, water temperature is low, the corresponding saturation pressure would go below the bubble pressure and flow rate will decrease as hydrogen pressure builds up. It is at this point that one can feel as to how the water side temperature affects the leak rate and hence, bubble pressure and the pressure transients felt by secondary circuit and its components.

The pressure and temperature behaviour of hydrogen bubble is depicted in Fig.7. The bubble pressure continues to rise; till the transit time of 20 msec, for the compression wave, emanating from downstream sodium hydrogen interface to be reflected back as an expansion wave causes bubble to experience a sudden increase in its growth rate; thus arresting the rate of pressure rise. In general compression waves emanating from sodium hydrogen interfaces are reflected back from sodium headers, surge tank, expansion tank as expansion waves, which are responsible for the decay of bubble pressure at later times.

The position of sodium-hydrogen interfaces with time is shown in Fig.8. It can be observed that upstream interface finds it difficult to push the incoming sodium since its momentum has got to be destroyed first before it can be accelerated in the opposite direction. The downstream interface moves fast since the sodium it has to accelerate was already flowing in the same direction.

The pressure transients experienced by the bottom sodium header is shown in Fig.9. The pressure remains constant till the compression wave, emanating from the downstream sodium-hydrogen interface is experienced by it following which the pressure starts rising. The expansion wave which was reflected to the reaction site arrives back to the header as another compression wave which is responsible for further sudden increase in the header pressure. The pressure reaches a maximum of 51 Kgf/cm² when the expansion wave reflected from pump tank inlet causes it to fall rapidly to 29 Kgf/cm². Another compression wave reaching the bottom header from upstream sodium hydrogen interface via clean steam generator module causes its pressure to increase to 35 kgf/cm² when the rupture disc suddenly breaks after a time lag of 50 m.sec counted from the instant it acquired the set pressure of 20 kgf/cm². This causes the pressure to fall very rapidly almost to the sodium vapour pressure limit. The transients observed after the rupture disc has ruptured are resulting from the multiple reflections between circuit components and the reaction site. The delay of the order of 50 m.sec counted from the instant the rupture disc acquired its set pressure is based on the experiments conducted by Lions⁽⁷⁾ et.al. The rupture discs do break at the set pressures during steady state experiments, but that does not guarantee that they will behave so during transients. We, therefore, plan to have test facility to study the rupture disc behaviour during short lived transient pressure pulses. Shown in Fig.10 is the pressure transient felt by top sodium header. The shape or the nature of transient pressure can be explained on the basis of interaction of pressure waves between circuit components and the reaction site. However, a maximum of 39 Kgf/cm² pressure is experienced by topsodium header.

Surge tank argon cover gas pressure and pressure at the bottom tube sheet of IHX has been shown in Fig.11. Argon cover gas pressure rises to 4.5 Kgf/cm² from its steady state value of 3.4 Kgf/cm². IHX bottom tube sheet pressure touches a maximum of 6.2 Kgf/cm² from its steady state value of 5.6 Kgf/cm² thanks to the rupture of rupture disc.

2.4.2 Leak in Super Heater

2.4.2.1 Steam leak model

Following a rupture in super heater portion steam flows towards both the broken ends in upstream and downstream portions of ruptured tube. Frictional adiabatic flow of steam has been assumed, since, during a period of few hundred m.sec. practically no heat gets transferred to steam flowing in the duct. Moreover, steam being lighter, the inertia effects caused by temporal acceleration are negligible in comparison to the inertia effects due to special acceleration, pressure and the frictional forces.

Above are the conditions required for a well known 'Fano Flow' in ducts⁽⁸⁾. Utilizing these Fano flow relations and techniques available for polynomial fitting, the steam flow rate

$$\frac{q - q_{max}}{q_{max}} = \sum_{n=1}^4 C_n \left(\frac{\phi - \phi_{cr}}{1 - \phi_{cr}} \right)^n$$

is obtained as a function of pressure ratio, the critical pressure ratio and the maximum choked flow, in the form of a fourth order polynomial.

2.4.2.2 SURT results for steam leak

Steam leak rates from upstream and downstream broken ends are shown in Fig.12. To begin with, since, the hydrogen bubble pressure is low, pressure ratios are less than the critical pressure ratio, and as a result steam issues from both the broken ends at critical velocity. This causes bubble pressure to shoot up immediately, thus reducing the steam flow rates to subcritical levels. Bubble pressure fluctuations are immediately felt up on the steam leak rates, unlike the water leak rate. If bubble pressure remains constant, steam leak rate also remain constant. Steam flow accelerates unto critical flow rates limits of 3.16 kg/sec and 5.45 kg/sec for upstream and downstream broken ends respectively, as bubble pressure falls.

The bubble pressure time history is shown in Fig.13. Bubble pressure remains constant till the compression wave emanating from upstream sodium hydrogen interface returns as expansion wave after experiencing reflection at top sodium header, following which it starts falling. Rupture of rupture disc and the presence of surge tank, and expansion tank causes the incident compression waves to be reflected back to reaction site as waves of expansion which are held responsible for further decay in bubble pressure as time lapses.

The positions of sodium hydrogen interfaces, with time is shown in Fig.14. The fast movement of upstream interface can be attributed to short sodium column between reaction site and top sodium header.

Pressure surges experienced by top sodium header has been shown in Fig.15. A maximum of 56.8 kg/cm^2 pressure is felt by top sodium header. The shape of this transient can be explained on the basis of interaction of pressure waves between reaction site and the circuit components.

Fig.16 shows pressure transient felt at bottom sodium header. Though this bottom header is located quite far away from the reaction site, the maximum pressure it experiences is more than that of top sodium header. Arrival of compression wave from downstream sodium hydrogen interface causes bottom header pressure to touch 55.2 kgf/cm^2 and remains constant for 15 msec or so when another compression wave emanating from upstream sodium hydrogen interface reaches via clean module. This causes another up surge and pressure reaches 75 kgf/cm^2 . Very shortly after this expansion waves from expansion tank and surge tank causes it to fall down and break in rupture disc further helps.

In Fig.17 one observes that argon cover gas pressure in surge tank rises to a maximum of 6.6 kgf/cm^2 from its steady state value of 3.4 kgf/cm^2 . This surge is higher than 4.52 kgf/cm^2 , what was observed in water leak case. IEX bottom tube sheet pressure rises to 7.2 kgf/cm^2 from its steady state value of 5.6 kgf/cm^2 . The corresponding maximum pressure in water leak case was 6.2 kgf/cm^2 . The proximity of IEX and

surge tank to the reaction site and higher bubble pressure can be attributed to these higher values.

3.0 SODIUM WATER REACTION ANALYSIS FOR PFBR

One would have adopted computer code 'SVRT' developed for FSTR to PFBR, but for the steam generator design differences of the two units. While the design of FSTR steam generator is a serpentine once through unit, the proposed PFBR steam generator is a vertical straight tube unit, though once through concept has been retained. Shown in Fig.1 is the design of PFBR steam generator. The optimised size of one of the sixteen units is 82.5 MW. The other relevant parameters have been shown in Table-1. Of the parameters listed in Table-1, the ones which render the calculation methodology for pressure transients in steam generator of PFBR, different than that for FSTR, are larger shell of 750 mm diameter and the presence of cover gas. Based on sodium water reaction experiments⁽⁵⁾ done inside small diameter vessels ($\sim 20 \text{ mm}$), which showed that hydrogen bubble immediately filled the cross-sectional area of the test section, one is justified with the assumption of one dimensional piston like growth of hydrogen bubble in the steam generator of FSTR which has a shell of only 177mm diameter. Since the PFBR steam generator unit has larger diameter cross-section, this type of piston like sodium ejection seems unrealistic; only part of the sodium flow cross-section will be filled by the hydrogen bubble. In fact over the initial period of growth, the shape of hydrogen bubble should almost be spherical. Detonation⁽⁵⁾ of small charges inside tube bundles, produced an initial spherical pressure pattern with almost no preferred directional effect due to presence of close packed tubes. At later times, for a leak in the centre of the steam generator shell, the bubble grows into elliptical and cylindrical patterns, since, hydrogen can only escape from the top of the vessel into argon cover gas space. Such a type of bubble growth results from a two-dimensional transient pressure field in the sodium surrounding the bubble. In this regard we have initiated studies on the application of the 'Method of characteristics'⁽⁹⁾, to transient two dimensional fluid flow problems in order to estimate pressures experienced by steam generator shell of PFBR.

NOEENCLATURE

a	- Pressure wave propagation velocity	q_u/q_d	- Water/steam leak rates from up/down stream portions of ruptured tube
A	- Area of cross-section of heat transfer	R	- Universal gas constant
c	- Sonic velocity in liquid sodium	S	- Cross-sectional area of steam generator
C_p	- Specific heat of sodium	t	- time
Di	- ID of pipe	t_h	- Pipe thickness
d	- ID of heat transfer tube	T	- Bubble temperature
E	- Youngs Modulus of Elasticity	T_0	- Adiabatic reaction temperature (which when multiplied by heat capacity of hydrogen produced gives heat of reaction)
f	- Friction factor	T_w	- Temperature of water at leak location
g	- Acceleration due to gravity	V	- Volume of bubble
gc	- Gravitational constant	v	- Transient flow velocity of sodium pipes etc.
J	- Joule's Mechanical Conversion factor	V_{ND1}/V_{LD1}	- Sodium velocity, Δx distances away from up/down stream sodium hydrogen interfaces at previous time step
K	- Bulk modulus of compressibility for sodium	x	- Distance along flow
k_u/k_d	- Friction factors for water flow in up/down stream portions of ruptured tube	X	- $R/(J C_p M)$
l_u/L_d	- Lengths of up/down stream portions of ruptured tube	δZ	- Elevation differences between leak location and steam/water headers
l_u/l_d	- Up/down stream positions of sodium hydrogen interfaces	ρ	- Density of sodium, and that of steam/water in ruptured heat transfer tube
m/m'	- Mass of water reacted and that of hydrogen produced	σ	- Surface tension of water
M/M'	- Molecular weights of water and that of hydrogen		
P	- Bubble pressure		
P_{ND1}/P_{LD1}	- Sodium pressures Δx distances away from up/down stream sodium hydrogen interfaces at previous time step		
P_{Nu}/P_{Ed}	- End pressures for up/down stream portions of ruptured tube		
P_{Nu}/P_{Ed}	-- Up/down stream header pressures (steam/water side)		
p	- Transient sodium pressure		

ANNEXURE

MATHEMATICAL MODEL FOR TRANSIENT TWO PHASE FLOW IN RUPTURED
HEAT TRANSFER TUBE

The pressure of hydrogen bubble generated as a result of sodium-water reaction and the pressure transients experienced elsewhere in the secondary sodium circuit, depend on how precisely the steam/water leak rate from the ruptured heat transfer tube is estimated, apart from other parameters.

Described in this annexure are the mathematical formulations based on which a computer code is being developed to estimate the transient two phase flow behaviour in the ruptured heat transfer tube and to finally determine the leak rates from the broken ends.

The major assumption in the model is that of thermal equilibrium between liquid and vapour phases. The mechanical non-equilibrium in the model is considered through the use of slip-ratio of velocity of gas phase to that of liquid phase.

Mathematical Formulation

An instantaneous rupture of the heat transfer tube carrying high pressure steam/water, initiates expansion waves to travel along the length of the tube, upstream and downstream of reaction site. Liquid phase, following depressurisation caused by these expansion waves tend to flash into vapour phase. The analysis of transient two phase flow is performed by writing the basic conservation equations^(6,11) for 1-D slip model as,

mass conservation:

$$\frac{\partial}{\partial t} \{ \alpha \rho_g + (1-\alpha) \rho_l \} + \frac{\partial}{\partial z} \{ \alpha \rho_g S u + (1-\alpha) \rho_l u \} = 0 \quad (1)$$

momentum conservation:

$$\frac{\partial}{\partial t} \{ \alpha \rho_g S u + (1-\alpha) \rho_l u \} + \frac{\partial}{\partial z} \{ \alpha \rho_g S^2 u^2 + (1-\alpha) \rho_l u^2 \} + g_c \frac{\partial p}{\partial z} + \text{Sin} \theta \{ \rho_g \alpha + \rho_l (1-\alpha) \} = - \frac{L_w}{A} \quad (2)$$

energy conservation:

$$\frac{\partial}{\partial t} \{ \alpha \rho_g h_g^* + (1-\alpha) \rho_l h_l^* \} + \frac{\partial}{\partial z} \{ \alpha \rho_g S u h_g^* + (1-\alpha) \rho_l u h_l^* \} - \frac{1}{J} \frac{\partial p}{\partial z} = \frac{q_w}{A} \quad (3)$$

wherein stagnation enthalpies for liquid and gas phases, respectively, are

$$h_l^* = h_l + \frac{u^2}{2g_c J} \quad (4)$$

$$h_g^* = h_g + \frac{S^2 u^2}{2g_c J} \quad (5)$$

and slip ratio $S = u_g / u$ (6)

It is now assumed that vapour flashing rate is large enough so that liquid temperature instantaneously corresponds to the saturation temperature corresponding to the pressure at that location. Thus the thermal equilibrium between liquid and vapour phase is established and pressure alone is sufficient to define completely the thermo-dynamic state of each phase. Enthalpies and densities can, therefore, be expressed as functions of pressure alone and conservation equations (1)-(5) can be written, after rearrangement and simplification, as

mass conservation:

$$\begin{aligned} & (\alpha \rho_g') \frac{\partial p}{\partial t} + \alpha \frac{\partial u}{\partial z} + (\rho_g - \rho_l) \frac{\partial \alpha}{\partial z} + \\ & + (\alpha S u \rho_g') \frac{\partial p}{\partial z} + (\alpha \rho_g S + (1-\alpha) \rho_l) \frac{\partial u}{\partial z} + (\rho_g S u - \rho_l u) \frac{\partial \alpha}{\partial z} = 0 \end{aligned} \quad (7)$$

momentum conservation:

$$(\alpha S u \rho'_g) \frac{\partial p}{\partial t} + (\alpha \rho_g S + (1-\alpha) \rho_l) \frac{\partial u}{\partial t} + (\rho_g S u - \rho_l u) \frac{\partial \alpha}{\partial t} + (\rho_g + \alpha S^2 \rho'_g) \frac{\partial p}{\partial z} + (2\alpha \rho_g S^2 u + 2(1-\alpha) \rho_l u) \frac{\partial u}{\partial z} + (\rho_g S^2 u^2 - \rho_l u^2) \frac{\partial \alpha}{\partial z} = -\frac{\tau_w}{A} \quad (8)$$

energy conservation:

$$(\alpha h_g \rho'_g - \frac{1}{J} + \alpha \rho_g h_g + (1-\alpha) \rho_l h_l) \frac{\partial p}{\partial t} + (\alpha \rho_g S^2 u + (1-\alpha) \rho_l u) \frac{\partial u}{\partial t} + (\rho_g h_g - \rho_l h_l) \frac{\partial \alpha}{\partial t} + (\alpha u S h_g \rho'_g + \alpha \rho_g u S h_g + (1-\alpha) \rho_l u h_l) \frac{\partial p}{\partial z} + (\alpha \rho_g S h_g + \frac{\alpha \rho_g u^2 S^2 + (1-\alpha) \rho_l u^2}{g_c J} + (1-\alpha) \rho_l h_l) \frac{\partial u}{\partial z} + (\rho_g u S h_g - \rho_l u h_l) \frac{\partial \alpha}{\partial z} = \frac{q_w}{A} \quad (9)$$

with the assumption that partial derivatives of slip(S) are negligible as compared to those for the unknowns(p, u, α).

Application of "Method of Characteristics" - MOC

It may be observed that the conservation equations(7)-(9) can be put concisely as

$$a_{ij} \frac{\partial u^j}{\partial t} + b_{ij} \frac{\partial u^j}{\partial z} + c_i = 0 \quad (i, j = 1, \dots, 3) \quad (10)$$

i-free ; j-dummy

Matrix components a_{ij} and b_{ij} are functions of a vector of unknowns

$$u^i = \begin{Bmatrix} p \\ u \\ \alpha \end{Bmatrix} \quad (11)$$

The solution of equation system(10) is affected by MOC. Application of MOC⁽¹²⁾ to equation system(10) results in compatibility relations,

$$(\sigma_i^k a_{ij}) du^j + \sigma_i^k c_i \Delta t = 0 \quad (i, j, k = 1, \dots, 3) \quad (12)$$

k-free ; i, j - dummy

valid along characteristics directions

$$\frac{dz}{dt} = \lambda_k \quad (13)$$

where, λ_k are the roots of the characteristics equation

$$|\lambda a_{ij} - b_{ij}| = 0 \quad (14)$$

and σ_i^k are the eigen vectors corresponding to each of eigen root λ_k

Nature of roots λ_k determine whether or not the equation system(10) is amenable to MOC. Tantner and Weisman⁽¹³⁾ have shown that with realistic slip ratios the characteristics roots are always real and distinct and hence equation system(10) is hyperbolic and is amenable to MOC.

Slip ratio computations are done using Hugmark's⁽¹⁴⁾ co-relation

$$\alpha = 1 / \left\{ 1 + (K/\alpha - 1) \frac{\rho_l}{\rho_g} \right\} \quad (15)$$

relating (α) to quality(x). The flow factor K is a function⁽¹⁴⁾ of

$$Z = \frac{R_0^{1/6} F^{1/8}}{\rho^{1/4}} \quad (16)$$

$$K = \text{Exp}\{-0.380263 Y^2 + 1.67795 Y - 2.104\} \quad Z \leq 10.0$$

$$= \text{Exp}\{0.09208 Y - 0.468443\} \quad 10.0 < Z < 130 \quad Y = \log_{10}(Z)$$

The values of slip are then computed using the conventional relation

$$S = \frac{1-\alpha}{\alpha} \frac{\rho_l}{1-\alpha} \frac{\rho_l}{\rho_g} \quad (17)$$

In what follows is described the application of MOC for analysis of two phase flow in ruptured heat transfer tube of steam generator.

Shown in Fig.1 is the finite difference grid to determine the solution at prescribed points

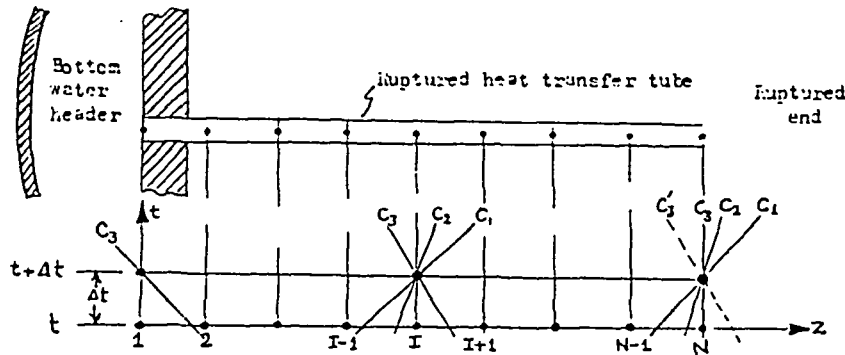


FIG.1

The mesh size Δz and time step Δt are related through Courant's (15) stability criterion i.e.

$$\Delta t \leq \frac{\Delta z}{\lambda_{kmax.}} \quad (18)$$

The compatibility relations (12) valid along characteristics lines defined by equation (13) are solved simultaneously for unknowns (p, u, α) at time $(t + \Delta t)$ for an interior node I using "inverse marching method". Euler's predictor-corrector method (12) is being used to obtain converged values of these unknowns at time $(t + \Delta t)$.

The upstream boundary point (1), which is the bottom water header of steam generator, is described by the conditions,

$$\left. \begin{aligned} p &= p_0 \\ \alpha &= 0 \end{aligned} \right\} \quad (19)$$

and the compatibility relation along C_3 characteristics is used to obtain the converged value of (u) .

The downstream boundary point (N), which is the ruptured end, is exposed to hydrogen bubble generated as a result of sodium water reaction. Therefore, as a first step, pressure at node (N) is taken to be

$$p = p_H \quad (20)$$

and the converged values of u and α are estimated from the

simultaneous solution of compatibility relations along C_1 and C_2 characteristics. Now if the characteristics direction C_3 at node N turns out to be negative, the calculations done in the first step are correct and flow is pressure controlled, otherwise, the calculations are redone and converged values of unknowns (p, u, α) are obtained from the simultaneous solution of compatibility relations along characteristics directions C_1, C_2, C_3 and the flow is checked at the outlet.

Based on the formulation, and methodology described in this annexure, a computer code is being developed at our end.

NOMENCLATURE FOR ANNEXURE

A	- flow area (m^2)
D_i	- internal dia of pipe (m)
$Fr = \frac{u^2}{g D_i} = \frac{G^2}{\rho^2 g D_i}$	- Froude's Number
g	- acceleration due to gravity (m/sec^2)
g_c	- gravitation conversion constant ($\frac{Kg-m}{Kg \cdot sec^2}$)
G	- mass flux ($Kg/m^2 \cdot sec$)
h_l/h_g	- Liquid/gas phase enthalpy (K-Cal/Kg)
$J = 427$	- Joule's constant (Kgf-m/K-Cal)
p	- pressure (Kgf/m^2)
q_w/A	- wall heat flux (K-Cal/sec m^2)
$Re = \frac{G D_i}{\mu_g \alpha + \mu_L (1-\alpha)}$	- Reynold's Number
$S = \frac{u_g}{u} = \frac{u_g}{u}$	- slip ratio
t	- time (sec)
$u \text{ or } u_L / u_g$	- Liquid/vapour phase velocities (m/sec)
x	- vapour quality

- z - distance along fluid flow (m)
 Z - A constant defined in text
 τ_w/A - shear stress
 ρ_L/ρ_g - liquid/gas phase densities (kg/m^3)
 μ_L/μ_g - liquid/gas phase viscosities (kg/m-sec)
 α - void fraction

$$\beta = \frac{Q_L}{Q_L + Q_g} = \frac{(1-\alpha)\rho_g}{(1-\alpha)\rho_g + \alpha\rho_L} - \text{liquid volumetric flow fraction}$$

Subscripts: L - Liquid phase; g - gas phase; h - homogeneous; w - wall

Superscripts: (\prime) derivative w.r. to pressure

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TABLE-1

	CONCEPT	CAPACITY	COVER GAS	SHELL DIA	TUBE ID/OD	No. OF TUBES	UNIT LENGTH	MATERIAL	SODIUM TEMP. (IN/OUT)	STEAM TEMP. & PRESSURE	FEED WATER TEMP.	
F.B.T.R.	ONCE THRO-UGH	12.5 (MW)	NO	177 (MM)	25.7/337 (MM)	7	90 (MT)	2 1/2 Cr. 1 Mo 1 Mb	510/280 (°C)	480 °C 125 Atm.	200 °C	
P.F.B.R.	DO	82.5 (MW)	YES	750 (MM)	10.3/15.8 (MM)	350	21 (MT)	2 1/2 Cr. 1 Mo	495/350 (°C)	480 °C 165 Atm.	250 °C	

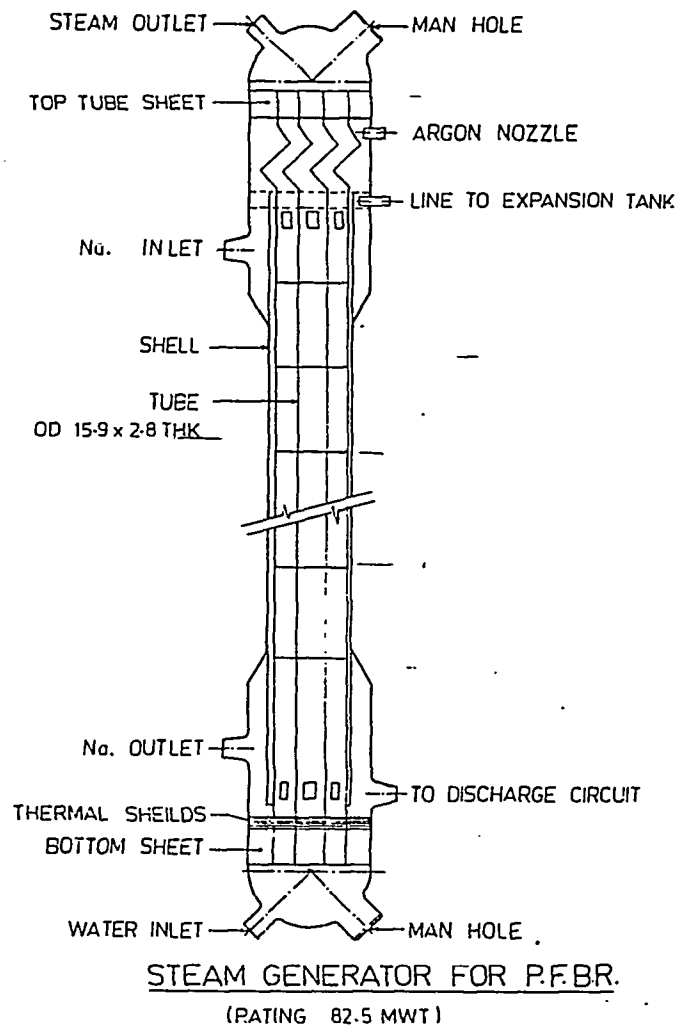


FIG: 1

F.B.T.R. STEAM GENERATOR

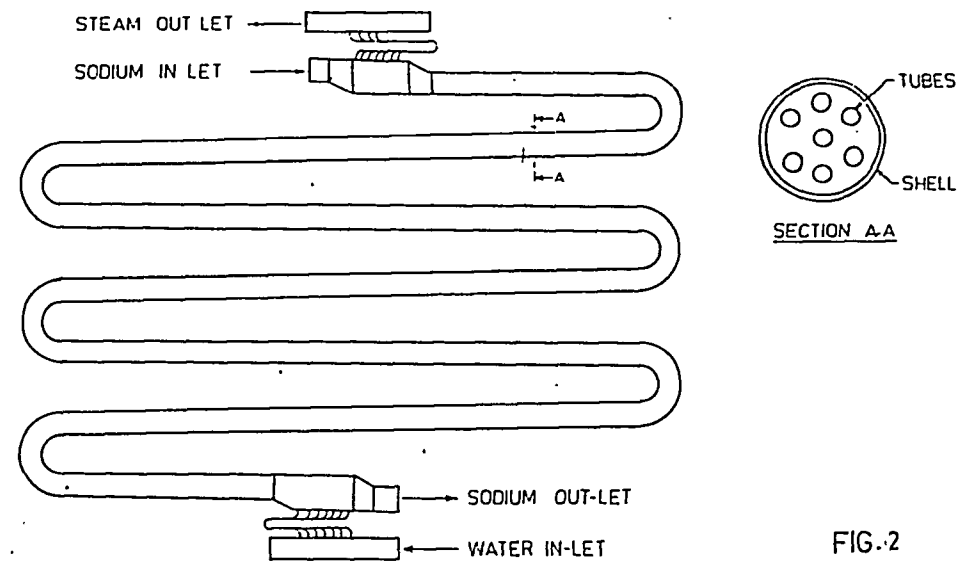


FIG.2

F.B.T.R. SECONDARY CIRCUIT

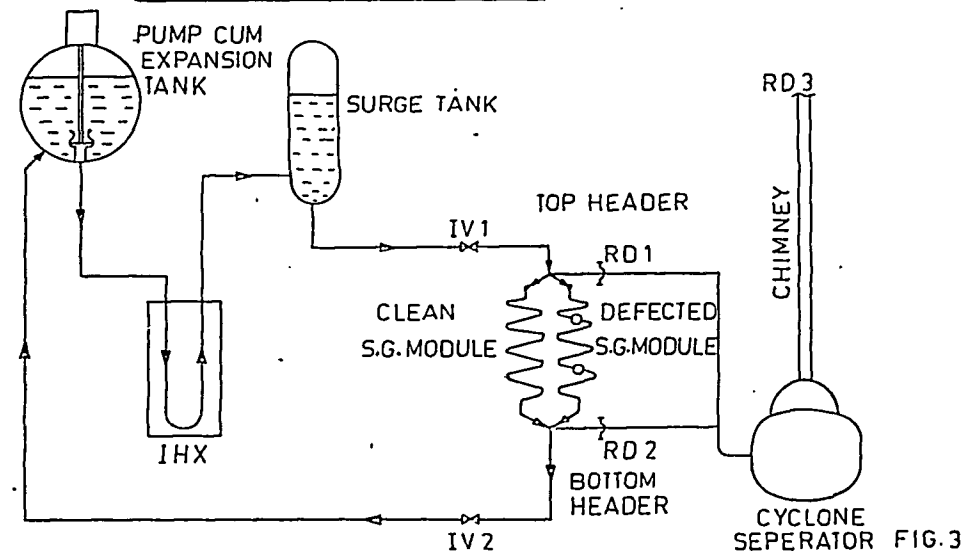


FIG.3

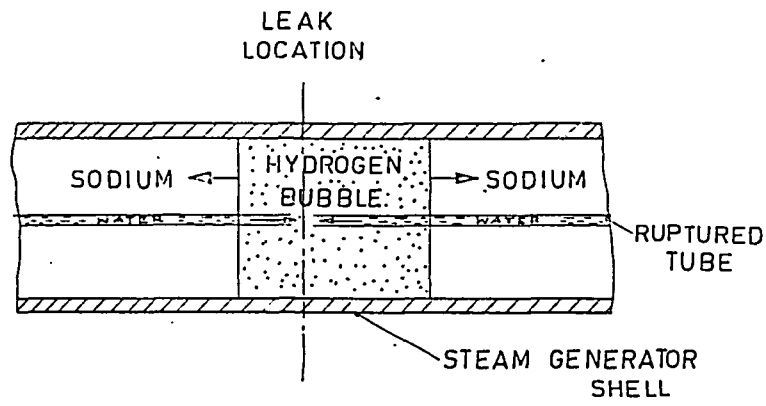


FIG. 4

WATER LEAK
MODELS

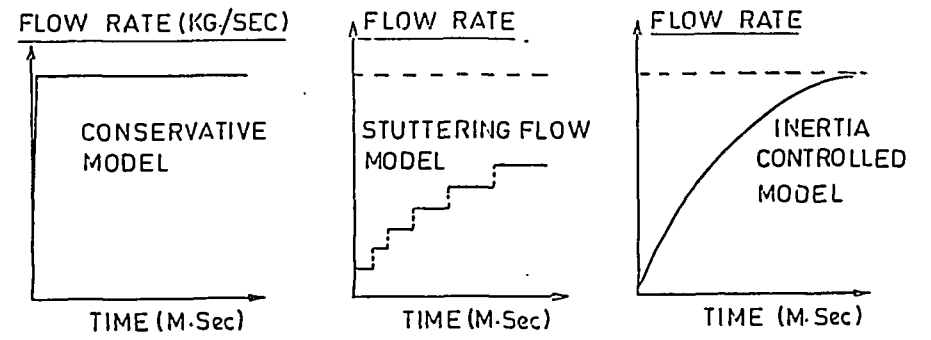


FIG. 5

