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**Production d'énergie
(hydraulique, thermique
et nucléaire)**

**MODELE AUX ELEMENTS FINIS D'UNE GRAPPE DE
COMMANDE. ETUDE PARAMETRIQUE MENEES PAR LA
METHODE DES PLANS D'EXPERIENCE**

***FEM OF PWR'S CONTROL ROD CLUSTER, PARAMETRICAL
STUDY BY EXPERIMENT DESIGN METHOD***

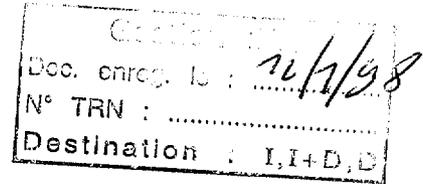
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**DIRECTION DES ÉTUDES ET
RECHERCHES**

SERVICE ENSEMBLES DE PRODUCTION
DÉPARTEMENT ACOUSTIQUE ET MÉCANIQUE
VIBRATOIRE



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SYNTHÈSE :

Ce rapport présente une étude paramétrique sur le comportement vibratoire non-linéaire des grappes de commande des réacteurs à eau pressurisée.

Dans une première partie, le modèle Eléments Finis et les excitations prises en compte sont présentés. Les grandeurs de sortie du calcul sont les déplacements des crayons dans leur guidage, les forces de choc contre le guidage et la puissance d'usure développée.

Dans une deuxième partie, l'étendue de l'étude paramétrique est détaillée. La méthode des Plans d'Expérience utilisée tente d'approcher une surface de réponse par un polynôme. La construction du plan d'expérience est brossée en regard des contraintes imposées sur les paramètres. Dans cette approche globale, le modèle retenu de degré est composé pour chacun des 6 paramètres de tous les termes linéaires, quadratiques et d'interaction (26 coefficients). L'étude des forces RMS de choc et des puissances d'usure sur chacun des 17 points de guidage du crayon conduit à 34 polynômes.

Dans la troisième partie, un tableau d'analyse des résultats (orientée plus spécialement sur les puissances d'usure), met en évidence les paramètres importants à chaque point du guidage et leur distribution le long du crayon. L'étude des surfaces de réponses des paramètres deux à deux, permet de visualiser les interactions.

L'intérêt de la méthode des Plans d'Expérience est soulignée. Sa rigueur et son systématisme permettent au spécialiste de déceler les paramètres influents. La simulation simplifiée par de simples polynômes est moins coûteuse en temps de calcul. Là l'ensemble des solutions permet de comparer les résultats au retour d'expérience.

EXECUTIVE SUMMARY :

of

Some finite element models have been performed at EDF to simulate the vibrations of rod cluster and to analyse the wear phenomenon of rods using parametrical studies. In the first part, one of the finite element models is presented. The location of excitation sources is described. The calculated values are : rod displacement in the guiding cards, shock forces on the guiding cards and wear power produced.

In the second part, a parametrical study is presented for a given computer experiment domain with an Experimental Design method. The building of the computer experiment design is described. The used polynomial model has all linear, quadratic and interactive terms for each of the 6 parameters (26 coefficients), 34 polynomials have been built to approach the effective shock forces and the mean wear power at each of the 17 guiding points.

In the last part, the influence of parameters on calculated mean wear power is shown along rods and some responses surfaces are visualized.

Systematism and closeness of experiment design technique is underlined. Easy simulation of all the response domain by polynomial approach, allows comparison with experiment feedback.

~~FINITE ELEMENT~~

PWR TYPE REACTORS

FINITE ELEMENT METHOD

CONTROL ELEMENTS

MECHANICAL VIBRATIONS

WEAR

PARAMETRIC ANALYSIS

~~DESIGN~~

63200

**F.E.M. of PWR's control rod cluster.
Parametrical study of vibrating behavior
by an Experiment Design method.**

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INTRODUCTION

Many damaging processes have to be taken into account to keep Pressurized Water Reactor (PWR) components in highly reliable operating conditions for more than forty years.

For example, systematic examinations on control rod cluster by ultrasonic method during maintenance shutdown show wear scars on stop clusters. These clusters always remain in the same "up" position. Their only goal is to quickly stop the nuclear reaction by falling down. The wear damage observed is sometimes strong enough to reject some of these clusters.

Rod cluster wear is due to impact-friction vibrations on loose support of guide tube. These vibrations are generated by primary coolant fluid circulation. The understanding of these problems is important because of reactor safety and replacement cost. It has motivated a great research and development program at EDF.

Finite element models (F.E.M.) developed using EDF mechanical computer code (*Code_Aster*) allow to simulate the non-linear behavior of this component.

1. MODEL DESCRIPTION

The mechanical model is a stick model without fluid meshing [1]. It is composed of a drive rod, a spider and a simplified cluster with only two rods instead of 24: one real rod (with realistic technical description) and an equivalent rod representing the 23 others (mass and stiffness calculated to keep an equal modal response). For both of them, lateral displacements are limited by 17 shock points (physical non-linearities) which simulate the three parts of the tube guide (discontinuous, continuous and fuel guides, fig. 1).

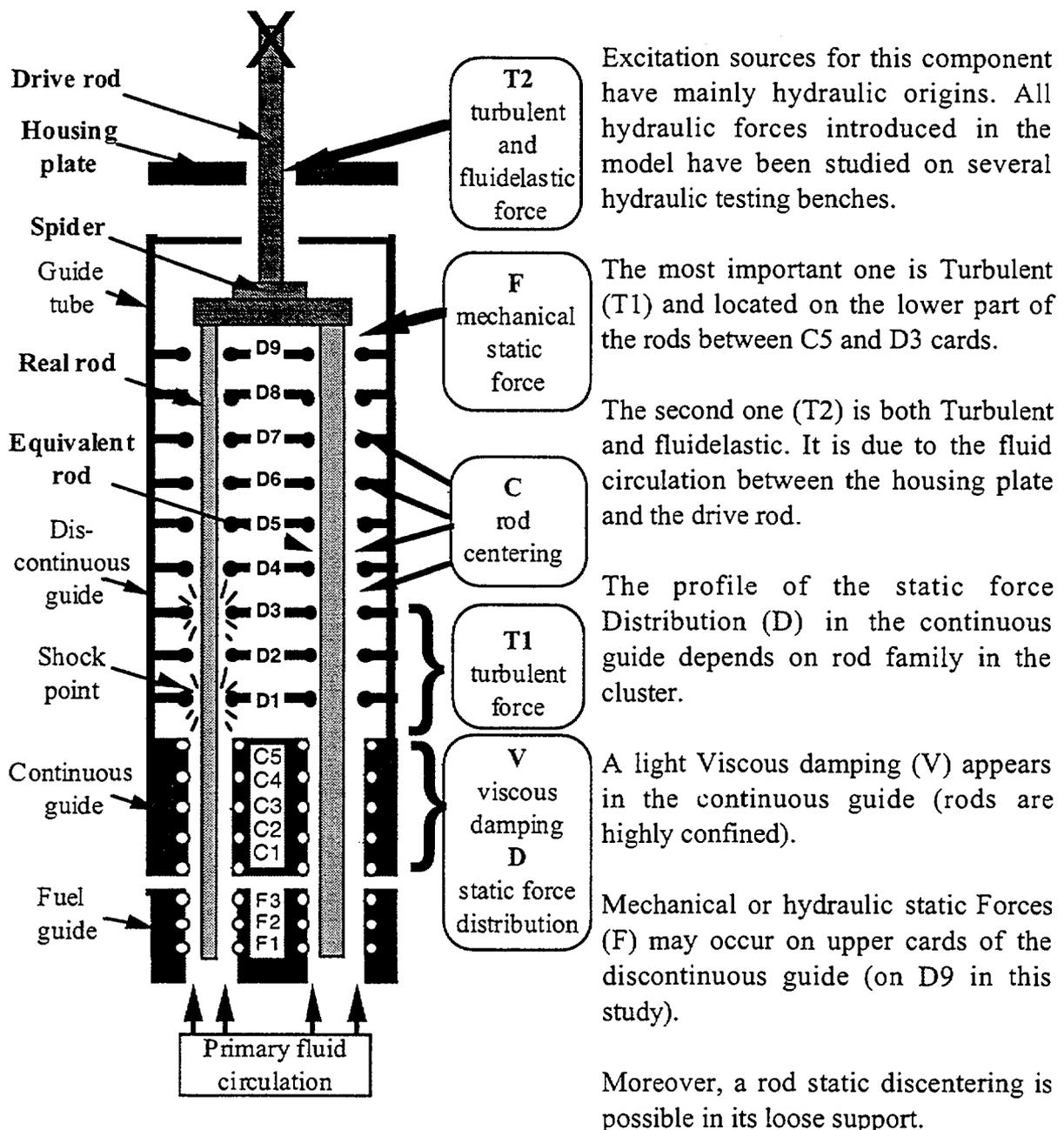
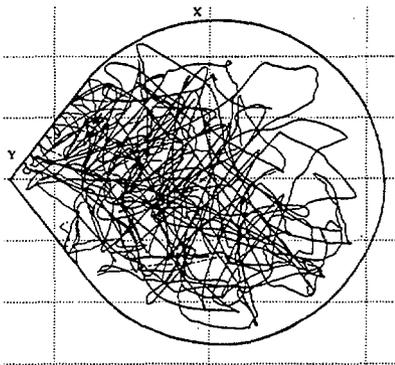


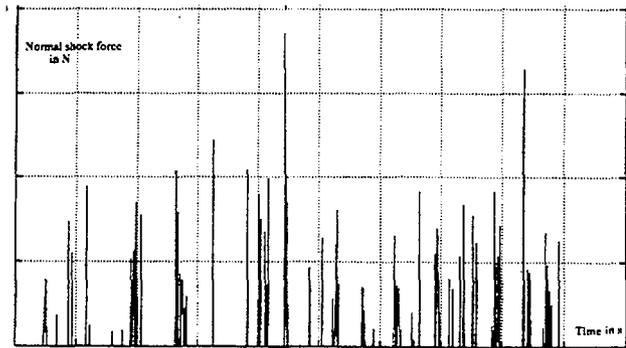
Fig. 1 - Description of the control rod cluster model

A calculation needs 700 s CPU on CRAY C98 because of the physical non linearities number. It gives two time-dependent outputs for each guiding cards (Fi, Ci, Di): rod

displacements and rod shock forces on the guide (fig. 2). A statistical treatment is made on these quantities. Wear power is the product of normal shock force and tangential speed.



XY Rod displacements in a guiding card



Shock forces against a guiding card

Fig. 2 - Example of the Finite Element Model outputs on D1 non-linearity

2. PARAMETRICAL STUDY

To analyse the mechanical behavior of the model and to understand the wear phenomenon, several parametrical studies have been performed. In the wide study presented here, the computational experiments have been defined by the variations of six parameters. The minimum and maximum levels of parameters which define the computational domain are given in table 1.

Parameter	D	F	T2	T1	V	C
Parameter type	qualitative criterion	force en D9	adimensional coefficient	adimensional coefficient	viscous damping	Y centering D9 to D1
Utmost values	A,B,E type of force distribution	0 to 6 (N)	1 to 3 times a known solicitation	0 to 0.25 times a known solicitation	0 to 30 (Ns/m)	-0.5 to 0.5 (mm)

Table 1 - Computer experiment domain

To know parameter contributions on the chosen responses for this study (effective normal force and mean wear power), and to have quickly a good view of the global response surfaces in the experimental domain, a numerical Experiment Design (E.D.) [2] [3] has been carried out.

2.1 Experiment design principle

Response surfaces [4] can be approximated by a polynomial model: by example the mean wear power for the card D1 with 4 parameters (1). This type of approximation is valid if the response surfaces are smooth enough, without discontinuities. We assume it is the case for the two responses in this study: effective normal force and mean wear power. Variables in

this model which represent the parameter variations and the interactions between parameters (linear and quadratic) are adimensioned (they vary between -1 and 1).

$$P_{wD1} = 2.1 - 0.4D - 0.1F - 0.13T_2 + 3.7T_1 + 0.25D^2 - 0.05F^2 + 0.17T_2^2 + 0.2T_1^2 + 2.2DT_2 + 0.14DF - 0.06FT_2 - 0.63FT_1 + 0.41FT_1 + 0.58T_1T_2 \quad (1)$$

The coefficients of the polynomial model are identified by linear regression from a set of calculations (equation 3). For an N-calculation sample, the experiment problem is written in the following matricial form :

$$Y = X \cdot A + E \quad (2)$$

where Y is the vector of the N calculated responses, A is the vector of k+1 coefficients to be estimated, X is a matrix of k+1 columns and N rows (constituted of 1 and k parameter values set for each calculation), and E denotes the modelling errors, called residuals (differences between the finite element model and the polynomial one). The coefficient vector A is estimated by a minimisation of the square residual sum :

$$\hat{A} = (X' X)^{-1} X' Y \quad \text{where } X' \text{ denotes } X \text{ transpose.} \quad (3)$$

Assuming that the residuals can be represented by a Gaussian law with a constant variance σ^2 in the computer experiment domain (hypothesis which can be a posteriori verified), the covariance matrix only depends on the choice of calculation points:

$$\text{cov}(\hat{A}) = (X' X)^{-1} \cdot \sigma^2 \quad (4)$$

The diagonal terms represent the variance of coefficients and the cross-coupling terms the correlations between coefficients. Precision and correlation between parameters do not depend on responses, so it is possible to define a priori a set of adequate calculations by minimising the terms of the covariance matrix. This is the basis of experiment design building.

2.2 Building of the calculation design

Several predefined experiment designs [4][5] have been defined and optimised to study response surfaces. One of the most well known designs is the composite design. To have the opportunity of easily adding parameters in the study, a Doehlert design [6] has been chosen.

Predefined experiment designs can be modified to integrate constraints by building D-optimal designs [7]. To take into account the qualitative parameter D with three levels, the Doehlert design has been modified: a five-level parameter has been changed into a three-level parameter. Two experiments in the original design (4 parameters - 21 experiments - table 2) were suppressed.

Experiment number	D	F	T2	T1	Experiment number	D	F	T2	T1
1	0	0	0	0	14	0.5	0.289	0.204	0.791
2	-1	0	0	0	15	-0.5	-0.289	-0.204	-0.791
3	1	0	0	0	16	0.5	-0.289	-0.204	-0.791
4	0.5	0.866	0	0	17	0	0.577	-0.204	-0.791
5	-0.5	-0.866	0	0	18	0	0	0.612	-0.791
6	0.5	-0.866	0	0	19	-0.5	0.289	0.204	0.791
7	-0.5	0.866	0	0	20	0	-0.577	0.204	0.791
8	0.5	0.289	0.816	0	21	0	0	-0.612	0.791
9	-0.5	-0.289	-0.816	0	a	-0.5	-0.866	-0.816	0.791
10	0.5	-0.289	-0.816	0	b	0.5	0.866	-0.816	0.791
11	0	0.577	-0.816	0	c	0.5	-0.866	0.816	0.791
12	-0.5	0.289	0.816	0	d	0	0.866	0.816	0.791
13	0	-0.577	0.816	0					



Suppressed experiments



Added experiments

Table 2 - Modified Doehlert design for four parameters (normalised parameters)

Four experiments were added to significantly decrease the correlations between parameters by maximising the determinant of the covariance matrix. NEMROD software [8] which is based on a Fedorov algorithm [9] has been used.

Several criteria can be used to estimate the quality of the experiment design [3][5]; for example the trace of $X'X$, which is proportional to the sum of the coefficient variances, has been divided by more than two by adding 4 adequate experiments to Doehlert design (table2).

The parametrical study has begun with four parameters (23 calculations) and then 22 calculations have been added to analyse two other parameter influences. Complete study with 6 parameters would need 21609 F.E.M. calculations.

3. ANALYSIS AND RESULTS

3.1 Domain of validity

Conclusions of such a study must be strictly limited to the computational experiment domain. As a consequence, extrapolations of polynomial model do not have any sense. Parameters effects are just valid in their variation range and a non significant parameter in the variation domain may become important with a wider range. In this paper, the validity of F.E.M. model is not discussed.

3.2 Results presentation

The amount of results is important: two responses (effective normal shock force and mean wear power) at each of the 17 guiding points means 34 polynomials to analyse. In the case of 6 parameters, each polynomial has 26 coefficients and a constant term. Coefficients analysis allows hierarchization of parameters. Table 3 presents polynomials coefficients obtained for mean wear power at the 17 guiding points.

Card	Linear terms						Quadratic terms				Interaction terms					
	D	F	T ₂	T ₁	V	C	D ²	F ²	T ₁ ²	C ²	DT ₁	FT ₁	T ₂ V	T ₁ V	FC	T ₁ C
D9		1.2		1.9		7.2				11.1					6.7	6.7
D8		0.9		0.6		0.4		0.5		-0.3		0.7			0.6	
D7		0.2		0.7		0.3		-0.3		-0.3			-0.6			0.5
D6				0.5		0.3		0.2	0.2	0.3			-0.5			0.6
D5				0.6		0.1			0.3	0.2			-0.3			
D4				0.8	0.2	0.2			0.6				-1.4			
D3			-0.1	0.7	0.2	0.2			0.5	0.3			-1.1			
D2	0.1	-0.1		0.3		0.1			0.1	0.2						
D1	0.5		-0.4	4.1		1.1			1.7	2.3			-3.4		2.1	1.9
C5				0.7	-0.3	0.2				0.9				-0.8	0.9	
C4	-1.3						1.6								-1.6	
C3	0.7						0.8		0.4		-0.2					
C2	0.5						0.6		0.3		-0.2					
C1				0.5	-0.2		-0.6									
F3	0.6			0.7			1.4		0.8		1.0					
F2	0.2			0.1			0.2				0.3					
F1	0.2			0.7	-0.2		-0.4				0.4		-0.6			

x	Highly significant parameter	Non significant columns are suppressed
x	Significant parameter	
	Less significant parameter	

Table 3 - Polynomial coefficients for mean wear power on guiding points.

Numbers indicated in each cell of the table 3 are the estimated polynomial coefficients. They represent the physical values of linear, quadratic or interactive effect of parameters.

For wear power at D1 card. complete polynomial form may be reduced to equation (5) which has only 10 terms:

$$P_{W_{D1}} = 2.3 - 0.5D - 0.4T_2 + 4.1T_1 + 1.1C + 1.7T_1^2 + 2.3C^2 - 3.4T_2V + 2.1FC + 1.9T_1C \quad (5)$$

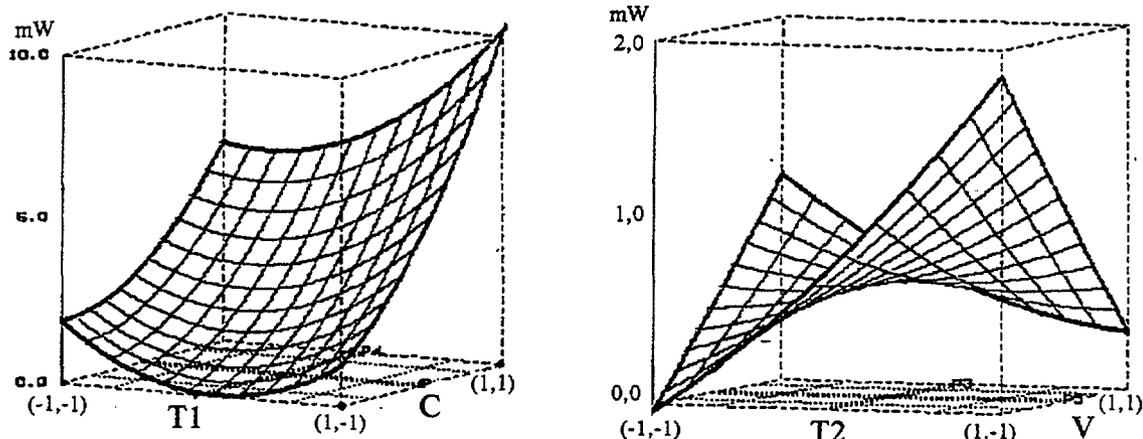
To evaluate if a coefficient is significant, its value is compared to the mean residual deviation between F.E.M. and polynomial calculations. Of course, this evaluation depends on the quality of regression analysis. It indicates the capability of the polynomial model to approach the surface response.

3.3 -Results analysis

A global analysis of parameters effects is possible using table 3. It shows the most important parameters and locates their effect along the cluster. Linear terms are the most significant (more than a half of highly significant terms). But the highest value is a quadratic effect of discentering. Global effect of one parameter is obtained by looking all linear, quadratic and interactive terms where it appears:

- static force distribution D has an effect located in continuous guide where it is applied and in fuel guide. It has no effect elsewhere.
- static force F applied at D9, has an effect from D9 to D6.
- excitation T2 has no large effect in this variation range excepted interaction with viscous damping from D1 to D7.
- excitation T1 is very important everywhere excepted in the continuous guide.
- viscous damping V has a light effect in the terminal low part and an interaction with T2 above the continuous guide.
- centering C is significant and important, particularly at D9. It interacts with F and T1.

It is also possible to plot response location surface of parameters by couple, the others being fixed at middle point. Figure 3a illustrates light interaction between excitation T1 and centering C on card D1 and Figure 3b strong interaction between excitation T2 and viscous damping V on card D3.



3a -Interaction of T1 and C on D1 card

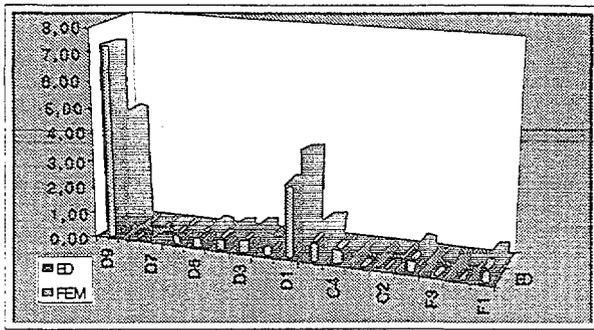
3b - Interaction of T2 and V on D3 card

Fig. 3 - Response surface of parameters by couple

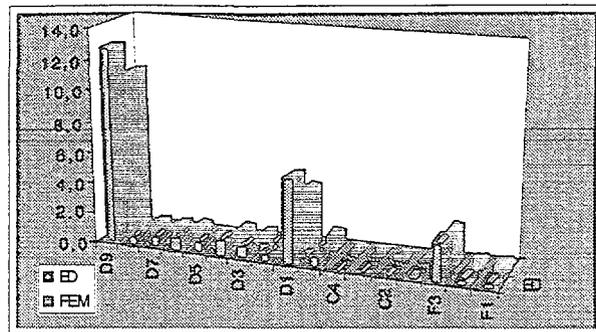
Mean residuals observation allows to say that polynomial approach is well adapted. On 16 of the 17 guiding points, less than 5% of response variations stay not fully explained by polynomial models. On D9, wear response is perhaps too non-linear for E.D. method.

Figure 4 shows comparison between E.D. expectation and F.E.M. calculation (done a posteriori) for two random examples out of prime design.

Some differences appear but globally the distribution along the cluster is well estimated. Nevertheless, these differences are included in the confidence interval defined by the mean residual deviation between F.E.M. and E.D. calculations.



Experiment n° 516



Experiment n° 3465

Fig. 4 - Comparison between E.D. expectation and F.E.M. calculation along the cluster

For an example of estimation quality, the local effect on F3 observed in F.E.M. experiment n° 3465 (figure 4) is well simulated by E.D. calculations.

CONCLUSION

This original use of Experiment Design method for numerical model analysis allows to perform computer experiments in a rational way with a minimum number of calculations; the benefit becomes greater as the number of parameters increases. Display of response surfaces and determination of parameter contribution to response (here effective normal force and mean wear power) can help specialists to have a global vision on simulated physical phenomenon in a defined experiment domain. This global vision is important to point out influent parameters and to compare numerical results to feedback.

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