



the

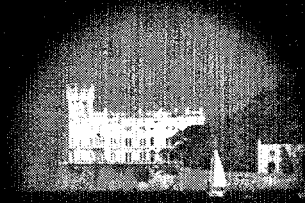
abdus salam
international
centre
for theoretical
physics



**IDENTITIES AND DERIVATIONS
FOR JACOBIAN ALGEBRAS**

A.S. Dzhumadil'daev

preprint



United Nations Educational Scientific and Cultural Organization
and
International Atomic Energy Agency
THE ABDUS SALAM INTERNATIONAL CENTRE FOR THEORETICAL PHYSICS

IDENTITIES AND DERIVATIONS FOR JACOBIAN ALGEBRAS

A.S. Dzhumadil'daev¹

*Institute of Mathematics, Academy of Sciences of Kazakhstan,
Pushkin Str.125, Almaty 480021, Kazakhstan*

and

The Abdus Salam International Centre for Theoretical Physics, Trieste, Italy.

Abstract

Constructions of n -Lie algebras by strong n -Lie-Poisson algebras are given. First cohomology groups of adjoint module of Jacobian algebras are calculated. Minimal identities of 3-Jacobian algebra are found.

MIRAMARE – TRIESTE

September 2001

¹E-mail: askar@math.kz

1. INTRODUCTION

Let U be an associative commutative algebra over a field K with commuting derivations $\partial_1, \dots, \partial_n$. Say, U is an algebra of differentiable functions on n -dimensional manifold or polynomial algebra $K_n^+ = K[x_1, \dots, x_n]$ or Laurent polynomial algebra $K_n = K[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$. In these examples, $\partial_i = \partial/\partial x_i$ are partial derivations. If not stated otherwise, the characteristic p of the field K is supposed to be 0.

Let $Jac_n^S : \wedge^n U \rightarrow U$ be Jacobian map:

$$Jac_n^S(u_1, \dots, u_n) = \det(\partial_i u_j) = \begin{vmatrix} \partial_1 u_1 & \cdots & \partial_1 u_n \\ \cdots & \cdots & \cdots \\ \partial_n u_1 & \cdots & \partial_n u_n \end{vmatrix}$$

Define $(n+1)$ -linear map $Jac_{n+1}^W : \wedge^{n+1} U \rightarrow U$ by

$$Jac_{n+1}^W(u_0, u_1, \dots, u_n) = \begin{vmatrix} u_0 & u_1 & \cdots & u_n \\ \partial_1 u_0 & \partial_1 u_1 & \cdots & \partial_1 u_n \\ \cdots & \cdots & \cdots & \cdots \\ \partial_n u_0 & \partial_n u_1 & \cdots & \partial_n u_n \end{vmatrix}$$

In terms of wedge products we see that

$$Jac_n^S = \partial_1 \wedge \cdots \wedge \partial_n,$$

$$Jac_{n+1}^W = id \wedge \partial_1 \cdots \wedge \partial_n,$$

where $id : U \rightarrow U, u \mapsto u$, is the identity map.

In [5], [6], [2] are proved that the n -ary multiplication $\omega = Jac_n^S$ satisfies the identity

$$g^\omega = 0, \tag{1}$$

where

$$g^\omega(u_1, \dots, u_{2n-1}) = \omega(u_1, \dots, u_{n-1}, \omega(u_n, \dots, u_{2n-1})) - \sum_{i=1}^n \omega(u_1, \dots, u_{i-1}, \omega(u_1, \dots, u_{n-1}, u_i), u_{i+1}, \dots, u_{2n-1}).$$

In [9] this identity is called a *Fundamental Identity*. We call it *Fundamental Identity of type I*.

We notice that the Jacobian $\omega = Jac_n^S$ satisfies one more identity, that we call a *Fundamental identity of type II*:

$$f^\omega = 0, \tag{2}$$

where

$$f^\omega(u_1, \dots, u_{n-1}, v_1, \dots, v_{n+1}) = \sum_{i=1}^{n+1} (-1)^i \omega(u_1, \dots, u_{n-1}, v_i) \cdot \omega(v_1, \dots, \hat{v}_i, \dots, v_{n+1}).$$

It is known that, the Jacobian $\omega = Jac_n^S$ satisfies the Leibniz identity for the multiplication \cdot :

$$\omega(u \cdot u', u_2, \dots, u_n) = u \cdot \omega(u', u_2, \dots, u_n) + u' \cdot \omega(u, u_2, \dots, u_n). \tag{3}$$

Here $u, u', u_1, \dots, u_{2n+1}, v_1, \dots, v_{n+1}$ are any elements of U .

In our paper we consider algebras with many operations. An operation or multiplication on algebra is a polylinear map. If $\omega : U \times \dots \times U \rightarrow U$ is a polylinear map with n arguments, then ω is called a n -ary multiplication on U . The space of n -ary polylinear maps on U is denoted by $T^n(U, U)$. If $n = 0$, then we set $T^0(U, U) = U$. The set of operations on U is called a signature of algebra [7]. The algebra with vector space U and signature $\Omega = \{\omega, \eta, \dots\}$ is denoted as (U, Ω) or (U, ω, η, \dots) or just U , when it is clear which multiplications are considered.

An algebra (U, ω) with skew-symmetric n -ary multiplication ω that satisfies (1) is called n -Lie [5]. An algebra (U, \cdot, ω) is called n -Lie-Poisson, if (U, \cdot) is an associative commutative algebra and it satisfies the identities (1) and (3). If it satisfies one more identity, namely the identity (2), then this algebra is called strong n -Lie-Poisson.

Sometimes n -Lie algebras are called Nambu [8], Filipov or Takhtajan algebras and n -Lie-Poisson algebras are called Nambu-Poisson algebras.

Question. Does the fundamental identity of type II follow from the fundamental identity of type I and from the Leibniz identity, if $n > 2$ and $p = 0$?

Here, we suppose that commutativity and associativity identities for the binary multiplication and skew-symmetric identity for n -multiplication are given. Otherwise, more likely, the answer to this question will be negative.

For some statement \mathcal{X} denote by $\delta(\mathcal{X})$ its Kroneker symbol: $\delta(\mathcal{X}) = 1$, if \mathcal{X} is true and $\delta(\mathcal{X}) = 0$, if \mathcal{X} is false. For some set of vectors Y denote by $\langle Y \rangle$ its linear span.

Let

$$\begin{aligned} r^\omega(u_1, \dots, u_{n-2}, u_{n-1}, u_n, \dots, u_{2n}) = \\ \sum_{i=n-1, n+1, \dots, 2n} (-1)^{i+n+\delta(i \leq n-1)} \omega(u_1, u_2, \dots, u_{n-2}, u_i) \omega(u_n, u_{n+1}, \dots, u_i, \dots, u_{2n}) + \\ \sum_{i=n-1, n+1, \dots, 2n} (-1)^{i+n+\delta(i \leq n-1)} \omega(u_n, u_2, \dots, u_{n-2}, u_i) \omega(u_1, u_{n+1}, \dots, u_i, \dots, u_{2n}). \end{aligned}$$

So, r^ω is the polynomial with n skew-symmetric arguments $u_{n-1}, u_{n+1}, \dots, u_{2n}$ and two symmetric arguments u_1 and u_n .

By theorem 6 [2] the answer to our question will be positive, if the inverse of this statement is true: the identity $f^\omega = 0$ follows from the identity $r^\omega = 0$ and Leibniz rule (3).

We give a positive answer to the last statement for $n = 3$ (theorem 5.1). If $p > 0$, it is more likely that the answer would be negative. For $n = 2$ the answer is also negative. There exist examples of Lie-Poisson algebras, that are not strong. For example, $(K[x_1, x_2, x_3, x_4], \partial_1 \wedge \partial_2 + \partial_3 \wedge \partial_4)$ is such an algebra.

Let (A, Ω) be an algebra with some vector space A and signature Ω . For $\Omega' \subseteq \Omega$ a linear map $D : A \rightarrow A$ is called Ω' -derivation, if

$$D(\omega(a_1, \dots, a_n)) = \sum_{i=1}^n \omega(a_1, \dots, a_{i-1}, D(a_i), \dots, a_n),$$

for any $a_1, \dots, a_n \in A$ and for all $\omega \in \Omega'$. Call Ω -derivation a derivation. Let $Der(A, \Omega')$ be a space of all derivations of (A, Ω') . Set $Der A = Der(A, \Omega)$.

In terms of operators $L_{a_1, \dots, a_{n-1}} : A \rightarrow A, a \mapsto \omega(a_1, \dots, a_{n-1}, a)$ we see that ω satisfies (1), if and only if

$$L_{a_1, \dots, a_{n-1}} \in \text{Der } A,$$

for any $a_1, \dots, a_{n-1} \in A$. Derivations of the form $L_{a_1, \dots, a_{n-1}}$ are called *interior* derivations. Let $\text{Int } A$ be a space of interior derivations. If A is n -Lie, then $\text{Int } A$ is a Lie algebra under commutator of operators. Moreover, $\text{Int } A$ is an ideal of $\text{Der } A$:

$$[D, L_{a_1, \dots, a_{n-1}}] = \sum_{i=1}^n L_{a_1, \dots, a_{i-1}, D(a_i), a_{i+1}, \dots, a_n},$$

for any $D \in \text{Der } A, a_1, \dots, a_n \in A$. In particular one can consider a factor-algebra, an algebra of outer derivations, $\text{Out } A = \text{Der } A / \text{Int } A$.

In [5] two examples of n -Lie algebras were constructed. The first one is vector products algebra and the second one is Jacobian algebra. In this paper it was established that any derivation of vector products algebra is interior. In [5] it was also noticed that, if (A, ω) is $(n+1)$ -Lie, then $(A, i(a)\omega)$ is n -Lie, where n -ary map $i(a)\omega$ is defined by

$$i(a)\omega(a_1, \dots, a_n) = \omega(a, a_1, \dots, a_n).$$

In our paper we give a generalisation of Jacobian algebras. Namely, we establish that the algebra (U, Jac_{n+1}^W) becomes a $(n+1)$ -Lie algebra. If U has unit element 1, then $\partial_i(1) = 1$, for any $i = 1, \dots, n$. If U has unit, then the $(n+1)$ -ary algebra (U, Jac_{n+1}^W) allows us to obtain the n -ary Jacobian algebra (U, Jac_n^S) by the restriction operation: $\text{Jac}_n^S = i(1)\text{Jac}_{n+1}^W$.

The theory of polynomial identities is well developed for ordinary algebras, i.e., for algebras with binary operations. The case of multi operation algebras needs some detailed information about n - or Ω -words and Ω -polynomials. Necessary definitions and descriptions of Ω -words are given in section 2 (theorem 2.3). We introduce a notion of Ω -degree for Ω -polynomial, that is, the number of operations. For example, Jacobian algebra considered as an n -Lie algebra, has only one n -ary operation, denoted by $\mu_n = \text{Jac}_n^S$, and it has only one identity of Ω -degree 1 (skew-symmetric identity for Jacobian) and only one identity of Ω -degree 2 (n -Lie identity). The identity $f^{\mu_n} = 0$ is not an n -Lie identity, since the construction of f^ω needs binary operation. Probably Jacobian algebra as n -Lie algebra has no any identity of Ω -degree 3. If we consider Jacobian algebras as n -Lie-Poisson algebras, i.e., as algebras with one binary operation $\mu_2 : (u, v) \mapsto u \cdot v$ and one n -ary operation $\mu_n = \text{Jac}_n^S$, then it has two identities of Ω -degree 1 (commutativity for μ_2 and skew-symmetry for μ_n) and three identities of Ω -degree 2 (n -Lie for μ_n , Leibniz rule between μ_2 and μ_n , and associativity identity for μ_2). As n -Lie-Poisson algebra, Jacobian algebra has one more identity of Ω -degree 3 (identity between two μ_n -s and one μ_2). It seems that both directions of studying Ω -identities of Jacobian algebras will be very interesting. In our paper we describe Ω -degree 2 identities for the Jacobian algebra (K_3, Jac_3^S) as 3-Lie algebra.

In cocycle and identity constructions we use two methods: a polynomial principle and \mathcal{D} -invariants method (section 7). The polynomial principle allows us to restrict our considerations by the case of polynomial algebras. As it turns out, almost all of our cocycles and polynomials are \mathcal{D} -invariant. To prove that \mathcal{D} -invariant polynomial is an identity it is sufficient to calculate these polynomials on their supports. In other words, the identity (cocyclicity) checking problem we reduce to the calculation problem whether a polynomial is equal to 0 on some concrete arguments. Here the use of computer calculations are very helpfull.

Let $U = K_n$. In section 8 we prove that the classes of the following linear maps consist of the basis of $Out(U, Jac_n^S)$:

$$\begin{aligned}\Delta &:= \sum_{i=1}^n x_i \partial_i + n(1-n)^{-1}, \\ D_{-\theta} &: x^\alpha \mapsto \delta_{\alpha, -\theta}, \\ D_i &:= x^{-\theta + \epsilon_i} \partial_i, \quad i = 1, \dots, n,\end{aligned}$$

where $\theta = (1, \dots, 1)$ and $\epsilon_i = (0, \dots, 1, \dots, 0)$. In section 9 we establish that all derivations of (U, Jac_{n+1}^W) are interior. In these sections we also prove that the algebras of interior derivations are isomorphic to Cartan Lie algebras of types W and S , namely, $Int(U, Jac_{n+1}^W) \cong W_n(U)$ and $Int(U, Jac_n^S) \cong S_n(U)$. These isomorphisms explain index notations on Jac_{n+1}^W and Jac_n^S .

In terms of n -Lie cohomology [1], [10], in sections 8 and 9 we calculate first cohomology groups of Jacobian algebras with coefficients in adjoint module. Derivations of Lie algebras appear in a natural way in considering central extensions of Lie algebras. Derivations of Lie algebras H_1 and W_n in this sense were described in [4]. Our results in the case $n = 2$ are compatible with the results of this paper.

2. Ω -WORDS

Let \mathbf{Z} be the ring of integers, $\mathbf{Z}_+ = \{i \in \mathbf{Z} : i \leq 0\}$ and $\mathbf{Z}^+ = \{i \in \mathbf{Z} : i > 0\}$. Let us given some alphabet \aleph with a map $\aleph \rightarrow \mathbf{Z}_+, \alpha \mapsto |\alpha|$, called *arity* map. Let

$$\begin{aligned}\aleph &= \{\alpha \in \aleph : |\alpha| = 0\}, \\ \Omega &= \{\omega \in \aleph : |\omega| > 0\}.\end{aligned}$$

Thus, $\aleph = \Omega \cup \aleph$. Denote elements of Ω by $\omega_1, \omega_2, \dots$ and elements of \aleph by x_1, x_2, \dots .

Define a *weight map*

$$\aleph \rightarrow \mathbf{Z}, \quad \alpha \mapsto \|\alpha\|,$$

by

$$\|\alpha\| = 1 - |\alpha|.$$

Lemma 2.1. *The following conditions are equivalent*

- $\|\alpha\| \geq 1$
- $\|\alpha\| = 1$
- $\alpha \in \aleph$

- $|\alpha| = 0$

Proof. Evident.

Let $\Gamma(\aleph) = \{a = \alpha_1\alpha_2\cdots\alpha_k\}$ be the set of sequences of elements of \aleph . If $a = \alpha_1\cdots\alpha_k, b = \beta_1\cdots\beta_s \in \Gamma(\aleph)$, then, by definition, $a = b$ if and only if $k = s$ and $\alpha_1 = \beta_1, \dots, \alpha_k = \beta_k$. Call the number of elements k of the sequence $\alpha = \alpha_1\cdots\alpha_k \in \Gamma(\aleph)$ a *length* of α and denote it by $l(\alpha)$. Prolong the weight map $\|\cdot\|$ to

$$\|\cdot\| : \Gamma(\aleph) \rightarrow \mathbf{Z},$$

by

$$\|\alpha_1\cdots\alpha_k\| = \|\alpha_1\| + \cdots + \|\alpha_k\|.$$

Let $\mathbf{Z}^\infty = \{(i_1, i_2, \dots) : i_1, i_2, \dots \in \mathbf{Z}\}$. Define a map $\mu : \Gamma(\aleph) \rightarrow \mathbf{Z}^\infty$ by

$$\mu(a) = (\mu_k(a), \mu_{k-1}(a), \dots, \mu_1(a)),$$

$$\mu_i(a) = \|\alpha_i\| + \cdots + \|\alpha_k\|, \quad i = 1, 2, \dots, k,$$

if $a = \alpha_1\cdots\alpha_k, \alpha_i \in \aleph, i = 1, 2, \dots, k$.

Definition. Let $\Gamma_1(\aleph)$ be the subset of $\Gamma(\aleph)$, that consists of elements $a \in \Gamma(\aleph)$, such that

- $\|a\| = 1$
- if $a = \alpha_1\cdots\alpha_k, \alpha_i \in \aleph, i = 1, 2, \dots, k$, then $\mu_i(a) \geq 1$, for any $i = 1, 2, \dots, k$.

Example. Let $\Omega = \{\omega_3, \omega_2, \omega'_2 : |\omega_3| = 3, |\omega_2| = |\omega'_2| = 2\}$. Let $a = \omega_3\omega_2x_1x_2x_3\omega'_2x_4x_5 \in \Gamma(\aleph)$, $b = \omega_3\omega_2x_1x_2\omega_3x_3x_4x_5 \in \Gamma(\aleph)$. Then $\mu(a) = (1, 2, 1, 2, 3, 4, 3, 1)$ and $\mu(b) = (1, 2, 3, 1, 2, 3, 2, 0)$. Therefore, $a \in \Gamma_1(\aleph)$ and $b \notin \Gamma_1(\aleph)$.

Lemma 2.2. *Elements of $\Gamma_1(\aleph)$ have the following properties*

- $\|\alpha\| = 1, \alpha \in \Gamma_1(\aleph) \Rightarrow \alpha \in \mathfrak{X}$,
- $\Omega \not\subset \Gamma_1(\aleph)$,
- any element of $\Gamma_1(\aleph)$ with length more than 1 begins with some element of Ω .
- any element of $\Gamma_1(\aleph)$ ends by some element of \mathfrak{X} .

Proof. Let $a = \alpha_1\cdots\alpha_k$ be the element of $\Gamma_1(\aleph)$ with length $k = l(a)$.

By definition,

$$\mu_k(a) = \|\alpha_k\| \geq 1$$

Thus, by lemma 2.1, $\alpha_k \in \mathfrak{X}$. So, we have proved that any element of $\Gamma_1(\aleph)$ ends by element of \mathfrak{X} . In particular, any element of $\Gamma_1(\aleph)$ with length 1 is an element of \mathfrak{X} .

Suppose that $l(a) = k > 1$. By definition,

$$\mu_1(a) = \|\alpha_1\cdots\alpha_k\| = 1, \quad \|\alpha_2\cdots\alpha_k\| \geq 1.$$

Therefore, $\|\alpha_1\| \leq 0$. In other words, $\alpha_1 \in \Omega$. So, we established that any element of $\Gamma_1(\aleph)$ with length > 1 begins with element of Ω .

Define a set of Ω -words [7].

Definition.

- i. Any element of \mathfrak{X} is an Ω -word.
- ii. If a_1, \dots, a_k are Ω -words, then $\omega a_1 \dots a_k$, where $|\omega| = k$, is also a Ω -word.
- iii. Any Ω -word is obtained by these two rules.

Let $a = \omega a_1 \dots a_k$ be some word and α is a word or element of Ω . We say that α enter to a or that α is a part of the word a and write $\alpha \in a$, if one of the following cases are fulfilled,

- α is a word and $\alpha = a$,
- α is a word and α is a part of a_s for some $s = 1, \dots, k$,
- $\alpha \in \Omega$ and $\alpha = \omega$,
- $\alpha \in \Omega$ and α is a part of a_s for some $s = 1, \dots, k$.

For the word $a = \omega a_1, \dots, a_k$ define $\omega deg a$ or Ω -degree of a , by

- $\omega deg a = \sum_{j=1}^k \omega deg a_j + 1$,
- $\omega deg x = 0, \quad x \in \mathfrak{X}$,
- $\omega deg \omega = 1, \quad \omega \in \Omega$.

So, Ω -degree of a is the number of elements of Ω that enter to a :

$$\omega deg a = |\{\omega \in \Omega \cap a\}|.$$

Let $a = \omega a_1 \dots a_k$ be some word. Call $x deg a$ or \mathfrak{X} -degree of a the number of elements of \mathfrak{X} that enter to a :

- $x deg a = \sum_{j=1}^k x deg a_j$,
- $x deg y = 1, \quad y \in \mathfrak{X}$,
- $x deg \omega = 0, \quad \omega \in \Omega$.

A degree of a is defined by $deg a = x deg a + \omega deg a$.

Theorem 2.3. *The set of Ω -words coincides with $\Gamma_1(\mathbb{N})$.*

Proof. Denote by $\bar{\Gamma}_1(\mathbb{N})$ the set of Ω -words.

Prove that $\bar{\Gamma}_1(\mathbb{N}) \subseteq \Gamma_1(\mathbb{N})$. Let $a \in \bar{\Gamma}_1(\mathbb{N})$. We use induction on $l(a)$. If $l(a) = 1$, then $a = x \in \mathfrak{X}$. Thus, $\|x\| = 1$, and $x \in \Gamma_1(\mathbb{N})$. Suppose that any element of $\bar{\Gamma}_1(\mathbb{N})$ with length $< l(a)$ belongs to $\Gamma_1(\mathbb{N})$. If $a = \omega a_1 \dots a_k$, then $l(a_1) < l(a), \dots, l(a_k) < l(a)$. Then by inductive suggestion $a_1, \dots, a_k \in \Gamma_1(\mathbb{N})$. In other words, if $a_i = \alpha_{i,1} \dots \alpha_{i,s_i}$, where $\alpha_{i,j} \in \mathbb{N}$, then $\sum_{j=1}^{s_i} \|\alpha_{i,j}\| = 1$. Thus,

$$a = \omega \alpha_{1,1} \dots \alpha_{1,s_1} \dots \alpha_{k,1} \dots \alpha_{k,s_k},$$

and

$$\mu_1(a) = \|a\| = \|\omega\| + \sum_{i=1}^k \sum_{j=1}^{s_i} \|\alpha_{i,j}\| = 1 - k + k = 1.$$

By lemma 2.2, $\alpha_{i,s_i} \in \mathfrak{X}$, for any $i = 1, \dots, k$. Therefore, $\mu_i(a) \geq 1$, for any $i \leq \sum_{j=1}^k s_j$. So, $a \in \Gamma_1(\mathbb{N})$.

Prove now $\Gamma_1(\mathbb{N}) \subseteq \bar{\Gamma}_1(\mathbb{N})$. By induction on $l(a)$ prove that any $a \in \Gamma_1(\mathbb{N})$ can be presented in the form $a = x \in \mathfrak{X}$, if $l(a) = 1$, or $a = \omega a_1 \dots a_r$, where $|\omega| = 1 - r, a_1, \dots, a_r \in \Gamma_1(\mathbb{N})$, if $l(a) > 1$.

If $l(a) = 1$, then the statement is trivial. Suppose that our statement is true for elements of $\Gamma_1(\mathbb{N})$ with length $< k$ and $a = \alpha_1 \dots \alpha_k, \alpha_i \in \mathbb{N}, i = 1, 2, \dots, k$. Let $\lambda_i = \mu_i(a)$.

Suppose that $\mu_k = 1 \leq \mu_{k-1} \leq \dots \leq \mu_{l+1}$, but $\mu_l < \mu_{l+1}$. This means that $\alpha_k, \dots, \alpha_{l+1} \in \mathfrak{X}$ and $\alpha_l \in \Omega$. Let $|\alpha_l| = q > 0$. Then $q \leq k - l$, since

$$\mu_l = 1 - q + \underbrace{1 + \dots + 1}_{k-l} \geq 1.$$

So, we can consider the element $c = \alpha_l \alpha_{l+1} \dots \alpha_{l+q} \in \Gamma(\mathbb{N})$. The word c is a subword of a . Moreover,

$$||c|| = ||\alpha_l|| + \dots + ||\alpha_{l+q}|| = 1 - q + \underbrace{1 + \dots + 1}_q = 1$$

and

$$||\alpha_s \alpha_{s+1} \dots \alpha_{l+q}|| \geq 1,$$

for any $s = l+q, l+q-1, \dots, l$. So, $c \in \Gamma_1(\mathbb{N})$. By inductive suggestion c is an Ω -word. Therefore, the word

$$b = \beta_1 \dots \beta_{k-q-1} \in \Gamma(\mathbb{N}),$$

where

$$\beta_1 = \alpha_1, \dots, \beta_{l-1} = \alpha_{l-1}, \beta_{l+1} = \alpha_{l+q+1}, \dots, \beta_{k-q-1} = \alpha_k,$$

and $\beta_l \in \mathfrak{X}$, has the following properties:

$$l(b) = (l-1) + 1 + (k-l-q) = k-q-1 < k,$$

$$||b|| = ||\alpha_1|| + \dots + ||\alpha_{l-1}|| + ||\beta_l|| + ||\alpha_{l+q+1}|| + \dots + ||\alpha_k|| = ||a||,$$

and

$$||\beta_s \dots \beta_{k-q-1}|| \geq 1,$$

for any $s = k-q-1, k-q-2, \dots, 1$. These mean that $b \in \Gamma_1(\mathbb{N})$ and $l(b) < l(a)$. By inductive suggestion, $b \in \bar{\Gamma}_1(\mathbb{N})$, and

$$b = \omega b_1 \dots b_r$$

for some $\omega \in \Omega$ and $b_1, \dots, b_r \in \bar{\Gamma}_1(\mathbb{N})$. Since $l(b_1), \dots, l(b_r) < k$, by inductive suggestion $b_1, \dots, b_r \in \Gamma_1(\mathbb{N})$. One of b_s , where $1 \leq s \leq r$, contains β_l . Instead of β_l we can take the Ω -word c and obtain the Ω -word that is equal to a . So, we established that $a \in \bar{\Gamma}_1(\mathbb{N})$.

Our theorem is proved.

Corollary 2.4. For any Ω -word a ,

$$\sum_{\omega \in \Omega \cap a} |\omega| = \omega \deg a + x \deg a - 1.$$

Proof. If $l(a) = 1$, then $a \in \mathfrak{X}$, and $\omega \deg a = 0$, $x \deg a = 1$. So, $\sum_{\omega \in \Omega \cap a} |\omega| = 0 = \omega \deg a + x \deg a - 1$.

Suppose that for a , with $l(a) < k$, the statement is true. Let $l(a) = k > 1$. By theorem 2.3, any Ω -word a with length $k > 1$ can be presented in the form $a = \eta a_1 \dots a_r$, for some Ω -words a_1, \dots, a_r with length $< k$ and some $\eta \in \Omega$ with $|\eta| = r$. Then

$$\Omega \cap a = \{\eta\} \cup \bigcup_{i=1}^r \{\Omega \cap a_i\}.$$

Thus,

$$\sum_{i=1}^r \omega \deg a_i = \omega \deg a - 1.$$

By inductive suggestion,

$$\sum_{\omega \in \Omega \cap a_i} |\omega| = \omega \deg a_i + x \deg a_i - 1,$$

for $i = 1, \dots, r$. Therefore,

$$\begin{aligned} \sum_{\omega \in \Omega \cap a} |\omega| &= \\ |\eta| + \sum_{i=1}^r \sum_{\omega \in \Omega \cap a_i} |\omega| &= \\ r + \sum_{i=1}^r (\omega \deg a_i + x \deg a_i - 1) &= \\ r + \sum_{i=1}^r \omega \deg a_i + \sum_{i=1}^r x \deg a_i - r &= \\ \omega \deg a + x \deg a - 1. & \end{aligned}$$

Corollary 2.5. Let $\omega \deg_i a$ be the number of entries of $\omega \in \Omega$ with $|\omega| = i$ in a . Then for any Ω -word a ,

$$x \deg a = \sum_{i \geq 1} (i - 1) \omega \deg_i a + 1.$$

Proof. This is another formulation of corollary 2.4.

Corollary 2.6. Assume that Ω consists of one element ω with $|\omega| = k$. Then for any Ω -word a ,

$$x \deg a = 1 + (k - 1) \omega \deg a.$$

Proof. It follows from corollary 2.5 and from the following facts: $\omega \deg_k a = \omega \deg a$, and $\omega \deg_i a = 0$, if $i \neq k$.

3. Ω -POLYNOMIALS, Ω -ALGEBRAS AND Ω -IDENTITIES

Definition. A linear combination of Ω -words is called Ω -polynomial. Polynomial of the form $\lambda_a a$, where a is a word and $\lambda_a \in K$, is called a monomial. The monomial is called nontrivial, if $\lambda_a \neq 0$. We say that $\lambda_a a$ is a part of f or $\lambda_a a$ is monomial of f , if $\lambda_a \neq 0$. A space of Ω -polynomials is denoted by $K[\Omega, \mathfrak{X}]$.

Let U and M be some vector spaces. Denote by $T^k(U, M)$ the space of polylinear maps $\psi : \underbrace{U \times \dots \times U}_k \rightarrow M$, if $k > 0$, $T^0(U, M) = M$, and $T^k(U, M) = 0$, if $k < 0$. Let $T^*(U, M) = \bigoplus_k T^k(U, M)$. If $\psi \in T^k(U, M)$, we will write $|\psi| = k$.

Let $\wedge^k(U, M)$ be the subspace of $T^k(U, M)$ consisting of skew-symmetric maps, $\wedge^0(U, M) = M$, $\wedge^k(U, M) = 0$, if $k < 0$ and $\wedge^*(U, M) = \bigoplus_k \wedge^k(U, M)$.

Let $\Omega = \{\omega_1, \omega_2, \dots\}$ be some alphabet with an arity map $|\cdot| : \Omega \rightarrow \mathbf{Z}^+$. Suppose that to each $\omega \in \Omega$ one corresponds some homogeneous map $\omega_U \in T^{|\omega|}(U, U)$. In this case we will say that U has a structure of Ω -algebra.

Notice that for any Ω -algebra U and for any Ω -word a one can make substitutions for its parameters $x_i \mapsto u_i \in U$ and $\omega_i \mapsto \omega_{iU}$. The easy way to see it is by presenting a in the form $a = \omega a_1 \dots a_k$, where $|\omega| = k$ and a_1, \dots, a_k are words of smaller degree than the $\deg a$. One can assume that in a_1, \dots, a_k our substitutions are correctly defined. Then a would be correctly defined also.

So, for any polynomial $f \in K[\Omega, \mathfrak{X}]$ we can make substitutions in its parameters by elements of U and operations on U . If f depends, say, from parameters $x_1, \dots, x_k, \omega_1, \dots, \omega_l$, then we obtain a correctly defined element $f_U = f(u_1, \dots, u_k, \omega_{1U}, \dots, \omega_{lU}) \in U$ for any $u_1, \dots, u_k \in U$.

Definition. The polynomial $f \in K[\Omega, \mathfrak{X}]$ is called an Ω -polynomial identity, or simply, Ω -identity on Ω -algebra U , if

$$f_U(u_1, \dots, u_k, \omega_{1U}, \dots, \omega_{lU}) = 0,$$

for any $u_1, \dots, u_k \in U$.

Let us given two Ω -polynomial identities $f = 0$ and $g = 0$. We say that the identity $f = 0$ follows from the identity $g = 0$, and denote $g = 0 \Rightarrow f = 0$, if $f_U = 0$ for any Ω -algebra U , such that $g_U = 0$. The identities $f = 0$ and $g = 0$ are called Ω -equivalent, or just equivalent, if $f = 0 \Rightarrow g = 0$ and $g = 0 \Rightarrow f = 0$.

Further, to simplify denotions we will often identify the polynomial $f = f(t_1, \dots, t_k, \omega_1, \dots, \omega_l)$ by the result of substitution $f_U = f(u_1, \dots, u_k, \omega_{1U}, \dots, \omega_{lU}) \in U$ and call $f(u_1, \dots, u_k, \omega_{1U}, \dots, \omega_{lU})$ shortly as a Ω -polynomial, or just a polynomial. Notice that a formal definition of Ω -words does not need any brackets and comma's, but for practical use it is more convenient to use brackets and comma's. We will use brackets keeping in mind that we will do it from the right to the left as in the proof of theorem 2.3.

Example. Let $\Omega = \{\omega_3, \omega_2, \omega'_2 : |\omega_3| = 3, |\omega_2| = |\omega'_2| = 2\}$. Let $a = \omega_3 \omega_2 x_1 x_2 x_3 \omega'_2 x_4 x_5 \in \Gamma_1(\aleph)$, Then for any Ω -algebra U and for any $u_1, \dots, u_5 \in U$,

$$a_U = \omega_{3U}(\omega_{2U}(u_1, u_2), u_3, \omega'_{2U}(u_4, u_5)) \in U,$$

or simply,

$$a = \omega_3(\omega_2(x_1, x_2), x_3, \omega'_2(x_4, x_5)).$$

4. 3-LIE ALGEBRAS

Theorem 4.1. *If $p = 0$ or $p > 3$, then any 3-Lie-Poisson algebra is strong.*

Proof. Let (U, \cdot, ω) be 3-Lie-Poisson. Recall that

$$\begin{aligned} r^\omega(u_1, \dots, u_6) = & \\ & \omega(u_1, u_2, u_3) \cdot \omega(u_4, u_5, u_6) - \omega(u_1, u_2, u_5) \cdot \omega(u_4, u_3, u_6) \\ & + \omega(u_1, u_2, u_6) \cdot \omega(u_4, u_3, u_5) + \omega(u_4, u_2, u_3) \cdot \omega(u_1, u_5, u_6) \\ & - \omega(u_4, u_2, u_5) \cdot \omega(u_1, u_3, u_6) + \omega(u_4, u_2, u_6) \cdot \omega(u_1, u_3, u_5) \end{aligned}$$

is symmetric in two arguments u_1 and u_4 and skew-symmetric in three arguments u_3, u_5, u_6 .

By theorem 6 [2], for 3-Lie-Poisson algebras, $r^\omega(u_1, \dots, u_6) = 0$, for any $u_1, \dots, u_6 \in U$. One can check that

$$\begin{aligned} 3f^\omega(u_1, u_2, u_3, u_4, u_5, u_6) = & \\ & 2r^\omega(u_1, u_2, u_3, u_4, u_5, u_6) + r^\omega(u_2, u_3, u_1, u_4, u_5, u_6) \\ & - r^\omega(u_2, u_4, u_1, u_3, u_5, u_6) + r^\omega(u_2, u_5, u_1, u_3, u_4, u_6) - r^\omega(u_2, u_6, u_1, u_3, u_4, u_5). \end{aligned}$$

So, $f^\omega = 0$ is also identity for (U, \cdot, ω) , if $p \neq 3$.

Proposition 4.2. $f^\omega = 0 \Rightarrow r^\omega = 0$.

Proof. One can check that:

$$\begin{aligned} -r^\omega(u_1, u_n, u_2, \dots, u_n, \dots, u_{2n}) = & \\ & f^\omega(u_1, u_2, \dots, u_n, \dots, u_{2n}) + (-1)^n f^\omega(u_2, \dots, u_n, u_1, u_n, \dots, u_{2n}). \end{aligned}$$

Therefore, the identity $r^\omega = 0$ follows from the identity $f^\omega = 0$.

Remark. Notice that for $n = 2$ the identities $r^\omega = 0$ and $f^\omega = 0$ are different. More exactly, the identity $r^\omega = 0$ does not appear, if $n = 2$. There exist 2-Lie-Poisson algebras that are not strong. Let us give an example of such algebras. Let $K_{2l} = K[x_1, \dots, x_{2l}]$ and $\omega = \sum_{i=1}^l \partial_i \wedge \partial_{i+l}$. Then (K_{2l}, \cdot, ω) is 2-Lie-Poisson. It is easy to check that $(K_2, \cdot, \partial_1 \wedge \partial_2)$ satisfies the identity $f^{\partial_1 \wedge \partial_2} = 0$. If $l > 1$, the polynomial

$$f^\omega(a, u, v, w) = \omega(a, u) \cdot \omega(v, w) + \omega(a, v) \cdot \omega(w, u) + \omega(a, w) \cdot \omega(u, v)$$

is not an identity. For instance,

$$f^\omega(x_1, x_2, x_3, x_4) = \omega(x_1, x_2) \cdot \omega(x_3, x_4) = 1 \neq 0.$$

So, the algebra (K_{2l}, \cdot, ω) is strong 2-Lie-Poisson, if and only if $l = 1$.

5. MINIMAL IDENTITIES FOR 3-JACOBIANS

Theorem 5.1. ($p \neq 2, 3$) Any polynomial identity of Ω -degree 2 of Jacobian algebra $(K[x_1, x_2, x_3], Jac_3^S)$ follows from 3-Lie and skew-symmetric identities for 3-multiplication Jac_3^S .

Proof. Let $\omega = Jac_3^S$. Define polynomials g^ω , h^ω and q^ω by

$$\begin{aligned} g^\omega &= g^\omega(t_1, \dots, t_5) = \\ &\omega t_1 t_2 \omega t_3 t_4 t_5 - \omega \omega t_1, t_2, t_3 t_4 t_5 + \\ &\omega \omega t_1 t_2 t_4 t_3 t_5 - \omega \omega t_1 t_2 t_5 t_3 t_4, \end{aligned}$$

$$\begin{aligned} h^\omega &= h^\omega(t_1, \dots, t_5) = \\ &\omega t_1 t_2 \omega t_3 t_4 t_5 - \omega t_1 t_3 \omega t_2 t_4 t_5 + \\ &\omega t_1 t_4 \omega t_2 t_3 t_5 - \omega t_1 t_5 \omega t_2 t_3 t_4, \end{aligned}$$

$$\begin{aligned} q^\omega &= q^\omega(t_1, \dots, t_5) = \\ &\sum_{i < j < 5} (-1)^{i+j} \omega t_i t_j \omega t_1 \dots \hat{t}_i \dots \hat{t}_j \dots t_5. \end{aligned}$$

Notice that

$$\begin{aligned} &3h^\omega(t_1, t_2, t_3, t_4, t_5) = \\ &\sum_{2 \leq i < j \leq 5} (-1)^{i+j} g^\omega(t_i, t_j, t_1, \dots, \hat{t}_i, \dots, \hat{t}_j, \dots, t_5). \end{aligned}$$

Further,

$$\begin{aligned} &\sum_{1 \leq i < j \leq 5} (-1)^{i+j} g^\omega(t_1, \dots, t_5) = \\ &2 \sum_{1 \leq i < j \leq 5} (-1)^{i+j} \omega t_i t_j \omega t_1 \dots \hat{t}_i \dots \hat{t}_j \dots t_5. \end{aligned}$$

Therefore,

$$2q^\omega(t_2, t_3, t_4, t_5, t_1) = \sum_{1 \leq i < j \leq 5} (-1)^{i+j} g^\omega(t_1, \dots, t_5) - 2h^\omega(t_1, \dots, t_5).$$

So, $h^\omega = 0$ and $q^\omega = 0$ are identities on (U, ω) , if $g^\omega = 0$ is an identity and $p \neq 2, 3$.

Let f be any polynomial of $wdeg f = 2$. Since $|\omega| = 3$, by corollary 2.5 we should prove that any polynomial of the form $f(t_1, \dots, t_5) = \sum_{i_1 < i_2, i_3 < i_4 < i_5} \lambda_{i_1 i_2} \omega(t_{i_1}, t_{i_2}, \omega(t_{i_3}, t_{i_4}, t_{i_5}))$, such that

$$f(u_1, \dots, u_5) = 0,$$

for any $u_1, \dots, u_5 \in U = K[x_1, x_2, x_3]$, is a linear combination of polynomials that can be obtained from the polynomial g^ω by permutation of variables t_1, \dots, t_5 .

We have

$$\begin{aligned} f(x_1, x_2, x_1, x_2, x_3^2) &= 0 \Rightarrow \lambda_{12} - \lambda_{14} + \lambda_{34} - \lambda_{23} = 0, \\ f(x_2, x_1, x_1, x_2, x_3^2) &= 0 \Rightarrow \lambda_{12} + \lambda_{13} + \lambda_{24} + \lambda_{34} = 0, \\ f(x_1, x_2, x_1, x_3^2, x_2) &= 0 \Rightarrow \lambda_{12} + \lambda_{15} - \lambda_{23} - \lambda_{35} = 0, \end{aligned}$$

$$\begin{aligned}
f(x_2, x_1, x_1, x_3^2, x_2) &= 0 \Rightarrow \lambda_{12} + \lambda_{13} - \lambda_{25} - \lambda_{35} = 0, \\
f(x_1, x_2, x_3^2, x_1, x_2) &= 0 \Rightarrow \lambda_{12} + \lambda_{15} + \lambda_{24} + \lambda_{45} = 0, \\
f(x_2, x_1, x_3^2, x_1, x_2) &= 0 \Rightarrow -\lambda_{12} + \lambda_{14} + \lambda_{25} - \lambda_{45} = 0.
\end{aligned}$$

The obtained system of linear equations has rank 5 and parameters $\lambda_{15}, \lambda_{25}, \lambda_{34}, \lambda_{35}, \lambda_{45}$ can be chosen as a free. So, any polynomial f , such that $xdeg f = 5$ and $f = 0$ is an identity on $(K[x_1, x_2, x_3], \omega)$, is a linear combination of the following five polynomials

$$\begin{aligned}
f_{45} &= -\omega t_1 t_2 \omega t_3 t_4 t_5 + \omega t_1 t_3 \omega t_2 t_4 t_5 - \omega t_2 t_3 \omega t_1 t_4 t_5 + \omega t_4 t_5 \omega t_1 t_2 t_3, \\
f_{35} &= \omega t_1 t_2 \omega t_3 t_4 t_5 + \omega t_1 t_4 \omega t_2 t_3 t_5 - \omega t_2 t_4 \omega t_1 t_3 t_5 + \omega t_3 t_5 \omega t_1 t_2 t_4, \\
f_{34} &= \omega t_1 t_2 \omega t_3 t_4 t_5 - \omega t_1 t_3 \omega t_2 t_4 t_5 + \omega t_1 t_4 \omega t_2 t_3 t_5 \\
&\quad + \omega t_2 t_3 \omega t_1 t_4 t_5 - \omega t_2 t_4 \omega t_1 t_3 t_5 + \omega t_3 t_4 \omega t_1 t_2 t_5, \\
f_{25} &= \omega t_1 t_2 \omega t_3 t_4 t_5 + \omega t_2 t_3 \omega t_1 t_4 t_5 - \omega t_2 t_4 \omega t_1 t_3 t_5 + \omega t_2 t_5 \omega t_1 t_3 t_4, \\
f_{15} &= -\omega t_1 t_2 \omega t_3 t_4 t_5 + \omega t_1 t_3 \omega t_2 t_4 t_5 - \omega t_1 t_4 \omega t_2 t_3 t_5 + \omega t_1 t_5 \omega t_2 t_3 t_4.
\end{aligned}$$

We see that

$$\begin{aligned}
f_{45} &= g^\omega(t_4, t_5, t_1, t_2, t_3), \\
f_{35} &= g^\omega(t_3, t_5, t_1, t_2, t_4), \\
f_{34} &= -q^\omega, \\
f_{25} &= -h^\omega(t_2, t_1, t_3, t_4, t_5), \\
f_{15} &= -h^\omega.
\end{aligned}$$

So, any identity of \mathfrak{X} -degree 5 follows from 3-Lie identity $g^\omega = 0$ and skew-symmetric identity.

Conjecture. Let $p = 0$ and $n > 2$. Any identity of Ω -degree ≤ 3 of n -Lie algebra $(K[x_1, \dots, x_n], Jac_n^S)$ follows from n -Lie and skew-symmetric identities. Any identity of Ω -degree ≤ 3 of n -Lie-Poisson algebra $(K[x_1, \dots, x_n], \cdot, Jac_n^S)$ follows from n -Lie and skew-symmetric identities for Jacobian, Leibniz rule for \cdot and the identity $f^{Jac_n^S} = 0$.

Here we suppose that commutativity and associativity identities for a binary operation are given. Definitions of n -Lie-Poisson algebras and the polynomial f^ω are given in the next section.

6. CONSTRUCTIONS OF n -LIE ALGEBRAS BY n -LIE-POISSON ALGEBRAS

Usually n -Lie algebras are considered for $n > 1$. Complete this definition by considering the case $n = 1$. Call any vector space U with a linear map $f : U \rightarrow U$, i.e., (U, f) a 1-Lie algebra.

Definition. Let $A = (U, \cdot, \omega)$ be an algebra with two operations: $(U, U) \rightarrow U$, $(u, v) \mapsto u \cdot v$ be a bilinear multiplication and $\omega : \wedge^n U \rightarrow U$ be a skew-symmetric n -linear multiplication. We say that A is *n -Lie-Poisson*, if

- (U, \cdot) is an associative commutative algebra
- (U, ω) is an n -Lie algebra.
- $\omega(u \cdot u', u_2, \dots, u_n) = \omega(u, u_2, \dots, u_n) \cdot u' + u \cdot \omega(u', u_2, \dots, u_n)$, for any $u, u', u_2, \dots, u_n \in U$.

Consider on U one more polynomial

$$f^\omega(u_1, \dots, u_{n-1}, v_1, \dots, v_n) = \sum_{i=1}^{n+1} (-1)^i \omega(u_1, \dots, u_{n-1}, v_i) \cdot \omega(v_1, \dots, \hat{v}_i, \dots, v_{n+1}).$$

Let us given an algebra (U, \cdot, ω) with one binary operation $(u, v \mapsto u \cdot v$ and one n -ary operation $\wedge^n U \rightarrow U, (u_1, \dots, u_n) \mapsto \omega(u_1, \dots, u_n)$.

Definition. An n -Lie-Poisson algebra is called *strong*, if it satisfies the identity $f^\omega = 0$.

Example. We will see below that the Jacobian algebra (U, \cdot, Jac_n^S) is strong n -Lie-Poisson and that the algebra (U, \cdot, Jac_{n+1}^W) satisfies the identity $f^\omega = 0$.

Let (U, \cdot, ω) be n -Lie-Poisson algebra. Recall that $D \in Der(U, \cdot, \omega)$, if

- $D \in Der(U, \cdot)$, i.e., $D(u \cdot v) = D(u) \cdot v + u \cdot D(v)$,
- $D \in Der(U, \omega)$, i.e.,

$$D(\omega(u_1, \dots, u_n)) = \sum_{i=1}^n \omega(u_1, \dots, u_{i-1}, Du_i, u_{i+1}, \dots, u_n).$$

Call in a such case D a n -Lie-Poisson derivation.

Example. Let $n = 1$. Then (U, \cdot, ω) is n -Lie-Poisson, if $\omega : U \rightarrow U$ is a derivation of (U, \cdot) . If D is an n -Lie-Poisson derivation of (U, \cdot, ω) , then $[D, \omega] = 0$.

Theorem 6.1. Let (U, \cdot, ω) be a strong n -Lie-Poisson algebra and $D \in Der(U, \cdot, \omega)$. Construct on U a new skew-symmetric $(n + 1)$ -multiplication $\bar{\omega} = D \wedge \omega$. Then $(U, \cdot, \bar{\omega})$ is strong $(n + 1)$ -Lie-Poisson.

Proof. We have

$$\begin{aligned} \bar{\omega}(u \cdot u', u_1, \dots, u_n) &= \\ D(u \cdot u') \cdot \omega(u_1, \dots, u_n) + \sum_{i=1}^n (-1)^i D(u_i) \cdot \omega(u \cdot u', u_1, \dots, \hat{u}_i, \dots, u_n) &= \\ (D(u) \cdot u') \cdot \omega(u_1, \dots, u_n) + u \cdot D(u') \cdot \omega(u_1, \dots, u_n) &+ \\ + \sum_{i=1}^n (-1)^i D(u_i) \cdot u \cdot \omega(u', u_1, \dots, \hat{u}_i, \dots, u_n) + & \\ \sum_{i=1}^n (-1)^i D(u_i) \cdot \omega(u, u_1, \dots, \hat{u}_i, \dots, u_n) \cdot u' = & \\ (D(u) \cdot \omega(u_1, \dots, u_n)) \cdot u' + \sum_{i=1}^n (-1)^i (D(u_i) \cdot \omega(u, u_1, \dots, \hat{u}_i, \dots, u_n)) \cdot u' + & \\ u \cdot (D(u') \cdot \omega(u_1, \dots, u_n)) + \sum_{i=1}^n (-1)^i u \cdot (D(u_i) \cdot \omega(u', u_1, \dots, \hat{u}_i, \dots, u_n)) = & \\ D \wedge \omega(u, u_1, \dots, u_n) \cdot u' + u \cdot \omega(u', u_1, \dots, u_n) & \end{aligned}$$

Further,

$$\sum_{i=1}^{n+2} (-1)^i D \wedge \omega(u_1, \dots, u_n, v_i) \cdot D \wedge \omega(v_1, \dots, \hat{v}_i, \dots, v_{n+2}) = X_1 + X_2,$$

where

$$X_1 = \sum_{i=1}^{n+2} \sum_{j=1}^n \sum_{1 \leq s \leq n+2, s \neq i} (-1)^{i+j+s+\delta(s>i)}. \\ D(u_j) \cdot D(v_s) \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_i) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}),$$

$$X_2 = \sum_{i=1}^{n+2} \sum_{1 \leq s \leq n+2, s \neq i} (-1)^{i+n+s+\delta(s>i)+1}. \\ D(v_i) \cdot D(v_s) \cdot \omega(u_1, \dots, u_n) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}).$$

Notice that, by identity $f^\omega = 0$,

$$X_1 = \sum_{j=1}^n \sum_{1 \leq s \leq n+2} (-1)^{j+s} D(u_j) \cdot D(v_s) \cdot \left(\sum_{1 \leq i \leq n+2, i \neq s} (-1)^{i+\delta(s>i)} \omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_i) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}) \right) = 0$$

and by commutativity of multiplication ,

$$X_2 = (-1)^n \omega(u_1, \dots, u_n) \cdot \left(\sum_{i=1}^{n+2} \sum_{i < s \leq n+2} (-1)^{i+s} D(v_i) \cdot D(v_s) \cdot \omega(v_1, \dots, \hat{v}_i, \dots, \hat{v}_s, \dots, v_{n+2}) - \sum_{i=1}^{n+2} \sum_{i < s \leq n+2} (-1)^{i+s} D(v_s) \cdot D(v_i) \cdot \omega(v_1, \dots, \hat{v}_i, \dots, \hat{v}_s, \dots, v_{n+2}) \right) = 0$$

So, $f^{\bar{\omega}} = 0$ is the identity.

Notice that

$$D \wedge \omega(u_1, \dots, u_n, D \wedge \omega(u_{n+1}, \dots, u_{2n+1})) \\ - \sum_{i=1}^{n+1} (-1)^{i+n+1} D \wedge \omega(D \wedge \omega(u_1, \dots, u_n, u_{n+i}), u_{n+1}, \dots, \widehat{u_{n+i}}, \dots, u_{2n+1}) = \\ \sum_{i=1}^{2n+1} D(D(u_i)) \cdot g_i(u_1, \dots, \hat{u}_i, \dots, u_{2n+1}) + \\ \sum_{1 \leq i, j \leq 2n+1, i \neq j} D(u_i) \cdot D(u_j) \cdot g_{i,j}(u_1, \dots, \hat{u}_i, \dots, \hat{u}_j, \dots, u_{2n+1}) + \\ \sum_{i=1}^{2n+1} \sum_{j=1}^{2n+1} D(u_i) \cdot h_{i,j}(u_1, \dots, \hat{u}_i, \dots, u_{j-1}, D(u_j), u_{j+1}, \dots, u_{2n+1}),$$

for some polynomials $g_i, g_{i,j}$ and $h_{i,j}$, that do not depend from D .

The following relations can be obtained by tedious calculations.

If $n < i \leq 2n + 1$, then $g_i = 0$. If $1 \leq i \leq n$, then by the identity $f^\omega = 0$,

$$\begin{aligned} g_i(u_1, \dots, \hat{u}_i, \dots, u_{2n+1}) &= \\ (-1)^{i+n+1} \sum_{j=n+1}^{2n+1} (-1)^j \omega(u_1, \dots, \hat{u}_i, \dots, u_n, u_j) \cdot \omega(u_{n+1}, \dots, \hat{u}_j, \dots, u_{2n+1}) &= \\ (-1)^{i+n+1} f^\omega(u_1, \dots, \hat{u}_i, \dots, u_{2n+1}) &= 0. \end{aligned}$$

If $1 \leq i, j \leq n$, or $n < i, j \leq 2n + 1$, then $g_{i,j} = 0$. If $1 \leq i \leq n$, $n < j \leq 2n + 1$, by n -Lie identity $g_{i,j} = 0$.

If $n < j \leq 2n + 1$, then $h_{i,j} = 0$. If $1 \leq j \leq n$, then

$$h_{i,j} = \pm f^\omega(u_1, \dots, \hat{u}_i, \dots, u_{j-1}, D(u_j), u_{j+1}, \dots, u_n, u_{n+1}, \dots, u_{2n+1}),$$

in the case of $1 \leq i \leq n$, and

$$h_{i,j} = \pm f^\omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_{n+1}, \dots, u_{i-1}, D(u_i), u_{i+1}, \dots, u_{2n+1}),$$

in the case of $n < i \leq 2n + 1$. Thus, in both cases, by the identity $f^\omega = 0$, we have $h_{i,j} = 0$.

So, the multiplication $\bar{\omega}$ satisfies $(n + 1)$ -Lie identity.

Corollary 6.2. *Let U be an associative commutative algebra with commuting derivations $\partial_1, \dots, \partial_n$. Let $\omega = \partial_1 \wedge \dots \wedge \partial_n$. Then (U, \cdot, ω) is strong n -Lie-Poisson.*

The algebra (U, \cdot, ω) constructed in corollary 6.2 is called n -Lie Jacobian algebra of type S .

Proof. We will argue by induction on n . If $n = 1$, then (U, \cdot, ∂_1) is 1-Lie-Poisson, if and only if $\partial_1 \in \text{Der}(U, \cdot)$. In this case the identity $f^\omega = 0$ follows from the commutativity law for the algebra (U, \cdot) .

Suppose that the algebra $(U, \cdot, \partial_1 \wedge \dots \wedge \partial_{n-1})$ is strong $(n - 1)$ -Lie-Poisson. By definition $\partial_n \in \text{Der}(U, \cdot)$. Since $[\partial_n, \partial_i] = 0$, for any $i = 1, \dots, n - 1$, then

$$\begin{aligned} \partial_n(\partial_1 \wedge \dots \wedge \partial_{n-1}(u_1, \dots, u_{n-1})) &= \\ \partial_n\left(\sum_{\sigma \in \text{Sym}_{n-1}} \text{sign } \sigma \partial_{\sigma(1)} u_1 \cdots \partial_{\sigma(n-1)} u_{n-1}\right) &= \\ \sum_{i=1}^{n-1} \sum_{\sigma \in \text{Sym}_{n-1}} \text{sign } \sigma \partial_{\sigma(1)} u_1 \cdots \partial_{\sigma(i-1)} u_{i-1} \partial_n(\partial_{\sigma(i)} u_i) \cdot \partial_{\sigma(i+1)} u_{i+1} \cdots \partial_{\sigma(n-1)} u_{n-1} &= \\ \sum_{i=1}^{n-1} \sum_{\sigma \in \text{Sym}_{n-1}} \text{sign } \sigma \partial_{\sigma(1)} u_1 \cdots \partial_{\sigma(i-1)} u_{i-1} \cdot \partial_{\sigma(i)} \partial_n(u_i) \cdot \partial_{\sigma(i+1)} u_{i+1} \cdots \partial_{\sigma(n-1)} u_{n-1} &= \\ \sum_{i=1}^{n-1} \partial_1 \wedge \dots \wedge \partial_{n-1}(u_1, \dots, u_{i-1}, \partial_n u_i, u_{i+1}, \dots, u_{n-1}). & \end{aligned}$$

So, $\partial_n \in \text{Der}(U, \partial_1 \wedge \dots \wedge \partial_{n-1})$. Thus we can apply theorem 6.1. By this theorem we obtain that $(U, \cdot, \partial_1 \wedge \dots \wedge \partial_n)$ is strong n -Lie-Poisson.

Theorem 6.3. Let (U, \cdot, ω) be strong n -Lie-Poisson. Endow U by a new skew-symmetric $(n+1)$ -multiplication $\tilde{\omega} = id \wedge \omega$, where $id : U \rightarrow U, u \mapsto u$, is the identity map. Then $(U, \tilde{\omega})$ is $(n+1)$ -Lie algebra. It satisfies the identity $f^{\tilde{\omega}} = 0$. If U has unit 1, then it satisfies one more identity

$$\begin{aligned} \tilde{\omega}(u \cdot u', u_1, \dots, u_n) - u \cdot \tilde{\omega}(u', u_1, \dots, u_n) - u' \cdot \tilde{\omega}(u, u_1, \dots, u_n) = \\ -(u \cdot u') \cdot i(1)\tilde{\omega}(u_1, \dots, u_n) \end{aligned} \quad (4)$$

Proof. Since $L_{u_2, \dots, u_n} \in Der(U, \cdot)$, and $1 \cdot 1 = 1$,

$$i(1)\omega = 0.$$

Therefore,

$$i(1)(id \wedge \omega) = \omega \quad (5)$$

So, for any $u, u', u_1, \dots, u_n \in U$,

$$\tilde{\omega}(u \cdot u', u_1, \dots, u_n) = Y_1 + Y_2,$$

$$u \cdot \tilde{\omega}(u', u_1, \dots, u_n) = Z_1 + Z_2,$$

$$u' \cdot \tilde{\omega}(u, u_1, \dots, u_n) = W_1 + W_2,$$

where

$$Y_1 = (u \cdot u') \cdot \omega(u_1, \dots, u_n),$$

$$Y_2 = \sum_{i=1}^n (-1)^i u_i \omega(u \cdot u', u_1, \dots, \hat{u}_i, \dots, u_n),$$

$$Z_1 = u \cdot (u' \cdot \omega(u_1, \dots, u_n)),$$

$$Z_2 = \sum_{i=1}^n (-1)^i u \cdot (u_i \cdot \omega(u', u_1, \dots, \hat{u}_i, \dots, u_n)),$$

$$W_1 = u' \cdot (u \cdot \omega(u_1, \dots, u_n)),$$

$$W_2 = \sum_{i=1}^n (-1)^i u' \cdot (u_i \cdot \omega(u, u_1, \dots, \hat{u}_i, \dots, u_n)).$$

Since $L_{u_1, \dots, \hat{u}_i, \dots, u_n} \in Der(U, \cdot)$,

$$Y_1 = Z_1 = W_1, \quad Y_2 = Z_2 + W_2.$$

Therefore, by (5), the identity (4) is true.

We have

$$\begin{aligned} f^{\tilde{\omega}}(u_1, \dots, u_n, v_1, \dots, v_{n+2}) = \\ \sum_{i=1}^{n+2} (-1)^i id \wedge \omega(u_1, \dots, u_n, v_i) \cdot \tilde{\omega}(v_1, \dots, \hat{v}_i, \dots, v_{n+2}) = \\ \sum_{i=1}^{n+2} \sum_{j=1}^n (-1)^{i+j} u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_i) \cdot \tilde{\omega}(v_1, \dots, \hat{v}_i, \dots, v_{n+2}) + \\ \sum_{i=1}^{n+2} (-1)^{i+n+1} v_i \cdot \omega(u_1, \dots, u_n) \cdot \tilde{\omega}(v_1, \dots, \hat{v}_i, \dots, v_{n+2}) = \\ T_1 + T_2, \end{aligned}$$

where

$$T_1 = \sum_{i=1}^{n+2} \sum_{j=1}^n \sum_{1 \leq s \leq n+2, s \neq i} (-1)^{i+j+s+\delta(s>i)} \cdot u_j \cdot v_s \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_i) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}),$$

$$T_2 = \sum_{i=1}^{n+2} \sum_{1 \leq s \leq n+2, s \neq i} (-1)^{i+s+\delta(s>i)+n+1} v_i \cdot v_s \cdot \omega(u_1, \dots, u_n) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}).$$

Since (U, \cdot) is commutative,

$$T_2 = (-1)^{n+1} \cdot \omega(u_1, \dots, u_n) \cdot \left(\sum_{i=1}^{n+2} \sum_{1 \leq s \leq n+2, s \neq i} (-1)^{i+s+\delta(s>i)} v_i \cdot v_s \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}) \right) = 0.$$

Notice that

$$T_1 = \sum_{j=1}^n \sum_{s=1}^{n+2} (-1)^{j+s} u_j \cdot v_s \cdot \left(\sum_{1 \leq i \leq n+2, i \neq s} (-1)^{i+\delta(s>i)} \omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_i) \cdot \omega(v_1, \dots, \hat{v}_s, \dots, \hat{v}_i, \dots, v_{n+2}) \right) = \sum_{j=1}^n \sum_{s=1}^{n+2} (-1)^{j+s} u_j \cdot v_s \cdot f^\omega(u_1, \dots, \hat{u}_j, \dots, u_n, v_1, \dots, \hat{v}_s, \dots, v_{n+2}).$$

Since $f^\omega = 0$ is identity on (U, \cdot, ω) , we have $T_1 = 0$. So, the algebra $(U, \cdot, \tilde{\omega})$ satisfies the identity $f^{\tilde{\omega}} = 0$.

We have

$$\begin{aligned} id \wedge \omega(u_1, \dots, u_n, id \wedge \omega(u_{n+1}, \dots, u_{2n+1})) &= \\ \sum_{i=n+1}^{2n+1} (-1)^{i+n+1} id \wedge \omega(u_1, \dots, u_n, u_i \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1})) &= \\ \sum_{j=1}^n \sum_{i=n+1}^{2n+1} (-1)^{i+j+n} u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1})) &+ \\ \sum_{i=n+1}^{2n+1} (-1)^{i+1} u_i \cdot \omega(u_1, \dots, u_n) \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}) &= \\ A_1 + A_2 + A_3, \end{aligned}$$

where

$$\begin{aligned} A_1 &= \sum_{j=1}^n \sum_{i=n+1}^{2n+1} (-1)^{i+j+n} u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i) \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}), \\ A_2 &= \sum_{j=1}^n \sum_{i=n+1}^{2n+1} (-1)^{i+j+n} u_j u_i \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1})), \\ A_3 &= \omega(u_1, \dots, u_n) \cdot \sum_{i=n+1}^{2n+1} (-1)^{i+1} u_i \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}). \end{aligned}$$

On the other hand,

$$\begin{aligned}
& \sum_{i=n+1}^{2n+1} (-1)^{i+n+1} (id \wedge \omega)(id \wedge \omega(u_1, \dots, u_n, u_i), u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}) = \\
& \sum_{i=n+1}^{2n+1} \sum_{j=1}^n (-1)^{i+j+n} (id \wedge \omega)(u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i), u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}) + \\
& \sum_{i=n+1}^{2n+1} (-1)^{i+1} (id \wedge \omega)(u_i \cdot \omega(u_1, \dots, u_n), u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}) = \\
& B_1 + B_2 + B_3 + B_4,
\end{aligned}$$

where

$$\begin{aligned}
B_1 &= \sum_{i=n+1}^{2n+1} \sum_{j=1}^n (-1)^{i+j+n} u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i) \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}), \\
B_2 &= \sum_{i=n+1}^{2n+1} \sum_{j=1}^n \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+j+s+1+\delta(s>i)} \\
& u_s \cdot \omega(u_j \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i), u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}), \\
B_3 &= \omega(u_1, \dots, u_n) \cdot \sum_{i=n+1}^{2n+1} (-1)^{i+1} u_i \cdot \omega(u_{n+1}, \dots, \hat{u}_i, \dots, u_{2n+1}), \\
B_4 &= \sum_{i=n+1}^{2n+1} \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+s+n+\delta(s>i)} \\
& u_s \cdot \omega(u_i \cdot \omega(u_1, \dots, u_n), u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}).
\end{aligned}$$

Notice that

$$\begin{aligned}
A_1 &= B_1, \\
A_3 &= B_3.
\end{aligned}$$

So, to check $(n+1)$ -Lie identity for $(n+1)$ -multiplication $\tilde{\omega}$ we must prove, that

$$A_2 = B_2 + B_4.$$

We have

$$\begin{aligned}
B_2 &= B_{2,1} + B_{2,2}, \\
B_4 &= B_{4,1} + B_{4,2},
\end{aligned}$$

where

$$\begin{aligned}
B_{2,1} &= \sum_{i=n+1}^{2n+1} \sum_{j=1}^n \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+j+s+1+\delta(s>i)} \\
& u_s \cdot u_j \cdot \omega(\omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i), u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}),
\end{aligned}$$

$$B_{2,2} = \sum_{i=n+1}^{2n+1} \sum_{j=1}^n \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+j+s+1+\delta(s>i)}.$$

$$u_s \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i) \cdot \omega(u_j, u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}),$$

$$B_{4,1} = \sum_{i=n+1}^{2n+1} \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+s+n+\delta(s>i)}.$$

$$u_s \cdot u_i \cdot \omega(\omega(u_1, \dots, u_n), u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}),$$

$$B_{4,2} = \sum_{i=n+1}^{2n+1} \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+s+n+\delta(s>i)}.$$

$$u_s \cdot \omega(u_1, \dots, u_n) \cdot \omega(u_i, u_{n+1}, \dots, \hat{u}_s, \dots, \hat{u}_i, \dots, u_{2n+1}).$$

We see that

$$B_{4,2} =$$

$$\omega(u_1, \dots, u_n) \cdot$$

$$\sum_{i=n+1}^{2n+1} \sum_{n < s \leq 2n+1} (-1)^s u_s \cdot \omega(u_{n+1}, \dots, \hat{u}_s, \dots, u_{2n+1}) =$$

$$n \omega(u_1, \dots, u_n) \cdot \sum_{n < s \leq 2n+1} (-1)^s u_s \cdot \omega(u_{n+1}, \dots, \hat{u}_s, \dots, u_{2n+1}).$$

Further,

$$B_{2,2} = \sum_{i=n+1}^{2n+1} \sum_{j=1}^n \sum_{n < s \leq 2n+1, s \neq i} (-1)^{i+j+n+1}.$$

$$u_s \cdot \omega(u_1, \dots, \hat{u}_j, \dots, u_n, u_i) \cdot \omega(u_{n+1}, \dots, u_{s-1}, u_j, u_{s+1}, \dots, \hat{u}_i, \dots, u_{2n+1}).$$

Therefore,

$$B_{2,2} + B_{4,2} =$$

$$\pm n \sum_{s=n+1}^{2n+1} u_s \cdot f^\omega(u_1, \dots, u_{n-1}, u_n, \dots, \hat{u}_s, \dots, u_{2n+1})$$

So, if $n \equiv 0 \pmod{p}$, or $f^\omega = 0$, then

$$B_{2,2} + B_{4,2} = 0.$$

Let

$$A_2 - B_{2,1} - B_{4,1} = \sum_{1 \leq i < s \leq 2n+1} u_i \cdot u_s \cdot g_{i,s},$$

where the polynomial $g_{i,s}$ does not depend from u_i and u_s . One can check that $g_{i,s} = 0$, if $1 \leq i, s \leq n$ or $n < i, s \leq 2n+1$ By n -Lie identity for ω we have $g_{i,s} = 0$, if $1 \leq i \leq n, n < s \leq 2n+1$.

So, $\tilde{\omega}$ satisfies $(n+1)$ -Lie identity.

Corollary 6.4. *Let U be an associative commutative algebra with commuting derivations $\partial_1, \dots, \partial_n$. Let $\tilde{\omega} = id \wedge \partial_1 \wedge \dots \wedge \partial_n$ Then $(U, \cdot, \tilde{\omega})$ is $(n+1)$ -Lie with identity $f^{\tilde{\omega}} = 0$. If U has unit 1, then the algebra $(U, \cdot, \tilde{\omega})$ satisfies the identity (4).*

The algebra $(U, \cdot, \tilde{\omega})$ constructed in corollary (6.4) is called n -Lie Jacobian algebra of type W .

Proof. Follows from corollary 6.2 and theorem 6.3.

7. POLYNOMIAL PRINCIPLE AND \mathcal{D} -INVARIANTS

In this section we discuss two methods used in our calculations.

Call the first method a *Polynomial principle*. It means the following. Let U be some associative commutative algebra over a field K with binary multiplication $U \times U \rightarrow U, (u, v) \mapsto u \cdot v$. Let $\partial_1, \dots, \partial_n$ be commuting derivations of U : $[\partial_i, \partial_j] = 0$, for any $i, j = 1, \dots, n$. Let us given a polylinear map $\omega : U \times \dots \times U \rightarrow U$ with n arguments, such that $\omega(u_1, \dots, u_n)$ is a linear combination of elements of the form $\partial_1^{i_1}(u_1) \dots \partial_n^{i_n} u_n$ for any $u_1, \dots, u_n \in U$.

Suppose that some statement concerning associative commutative algebra U , n -ary polylinear map $\omega : U \times \dots \times U \rightarrow U$ and derivations $\partial_1, \dots, \partial_n$ was obtained by using:

- Leibniz rule:

$$\partial_i(u_1 \cdot u_2) = \partial_i(u_1) \cdot u_2 + u_1 \cdot \partial_i(u_2),$$

for any $u_1, u_2 \in U$ and $i = 1, \dots, n$.

- linear properties of U
- associativity and commutativity properties of U .

Then this statement is true for any associative commutative algebra \tilde{U} with commuting derivations $\tilde{\partial}_1, \dots, \tilde{\partial}_n$. In particular, this statement is true for the polynomial algebra $U = K[x_1, \dots, x_n]$ with derivations $\partial_i = \partial/\partial x_i, i = 1, \dots, n$.

The second method is based on the study of \mathcal{D} -invariants [3]. Let \mathcal{D} be an abelian subalgebra of $Der U$ generated by commuting derivations $\partial_1, \dots, \partial_n$. Let $C^k(U, U) = \{\psi : U \times \dots \times U \rightarrow U\}$ be the space of skew-symmetric polylinear maps with k arguments and $C^*(U, U) = \bigoplus_k C^k(U, U)$.

Let $\rho : \mathcal{D} \rightarrow End C^*(U, U)$ be a representation of an abelian Lie algebra \mathcal{D} defined by

$$\begin{aligned} \rho(X)\psi(u_1, \dots, u_k) = \\ X(\psi(u_1, \dots, u_k)) - \sum_{l=1}^n \psi(u_1, \dots, u_{l-1}, X(u_l), u_{l+1}, \dots, u_k), \end{aligned}$$

for $\psi \in C^k(U, U)$. We say that $\psi \in C^*(U, U)$ is \mathcal{D} -invariant, if $\rho(X)\psi = 0$, for any $X \in \mathcal{D}$.

Define \wedge and \wedge' products on $C^*(U, U)$. For $\psi \in C^k(U, U)$ and $\phi \in C^l(U, U)$ set

$$\psi \smile \phi(u_1, \dots, u_{k+l}) = \psi(u_1, \dots, u_k) \cdot \phi(u_{k+1}, \dots, u_{k+l}),$$

$$\psi \smile' \phi(u_1, \dots, u_{k+l}) = \psi(\phi(u_1, \dots, u_l), u_{l+1}, \dots, u_{k+l}).$$

Define $\psi \wedge \phi \in C^{k+l}(U, U)$ and $\psi \wedge' \phi \in C^{k+l-1}(U, U)$ by

$$\begin{aligned} \psi \wedge \phi(u_1, \dots, u_{k+l}) = \\ \sum_{\sigma \in Sym_{k,l}} sign \sigma (\psi \smile \phi)(u_{\sigma(1)}, \dots, u_{\sigma(k)}, u_{\sigma(k+1)}, \dots, u_{\sigma(k+l)}), \\ \psi \wedge' \phi(u_1, \dots, u_{k+l}) = \\ \sum_{\sigma \in Sym_{l, k-1}} sign \sigma (\psi \smile' \phi)(u_{\sigma(1)}, \dots, u_{\sigma(l)}, u_{\sigma(l+1)}, \dots, u_{\sigma(k+l)}). \end{aligned}$$

Proposition 7.1. *If $\psi, \phi \in C^*(U, U)$, then*

$$\rho(X)(\psi + \phi) = \rho(X)\psi + \rho(X)\phi,$$

$$\rho(X)(\lambda\psi) = \lambda\rho(X)\psi,$$

$$\rho(X)(\psi \wedge \phi) = \rho(X)\psi \wedge \phi + \psi \wedge \rho(X)\phi,$$

$$\rho(X)(\psi \wedge' \phi) = \rho(X)\psi \wedge' \phi + \psi \wedge' \rho(X)\phi.$$

Corollary 7.2. *The subspace of \mathcal{D} -invariants $C^k(U, U)^{\mathcal{D}} = \{\psi \in C^k(U, U) : \rho(X)\psi = 0, \forall X \in \mathcal{D}\}$ is close under \wedge and \wedge' products.*

So, any polylinear map constructed by \mathcal{D} -invariant maps using \wedge and \wedge' products will be also \mathcal{D} -invariant. For example, $Jac_n^S \in C^n(U, U)^{\mathcal{D}}$ and $Jac_{n+1}^W \in C^{n+1}(U, U)^{\mathcal{D}}$.

Let $pr : U \rightarrow K$ be a projection map:

$$pr \sum_{\alpha \in \mathbb{Z}^n} \lambda_{\alpha} x^{\alpha} = \lambda_0.$$

Prolong this map to

$$pr : C^*(U, U) \rightarrow C^*(U, K),$$

$$(pr \psi)(u_1, \dots, u_n) = pr(\psi(u_1, \dots, u_n)).$$

Theorem 7.3. *Let $\psi \in C^k(U, U)^{\mathcal{D}}$. Then*

$$\psi(u_1, \dots, u_k) = \sum_{\alpha(1), \dots, \alpha(k) \in \mathbb{Z}_+^n} \frac{\partial^{\alpha(1)}(u_1)}{\alpha(1)!} \dots \frac{\partial^{\alpha(k)}(u_k)}{\alpha(k)!} pr \psi(x^{\alpha(1)}, \dots, x^{\alpha(k)}).$$

This theorem follows from the results of [3]. Call k -types $(x^{\alpha(1)}, \dots, x^{\alpha(k)})$, or simply $(\alpha(1), \dots, \alpha(k))$, such that $pr \psi(x^{\alpha(1)}, \dots, x^{\alpha(k)}) \neq 0$, as a *support* of ψ . So, by theorem 7.3 to prove $\psi = 0$ it is enough to establish that ψ does not have any support k -type.

8. DERIVATIONS OF JACOBIAN ALGEBRAS OF TYPE S

In this section $char K = 0$ and $U = K_n$ or K_n^+ and $n > 1$, if otherwise is not stated. Elements of U are denoted as $u, v, w, u_1, v_1, w_1, \dots$. Let $\theta = \sum_{i=1}^n \epsilon_i$, where $\epsilon_i = (0, \dots, 0, \frac{1}{i}, 0, \dots, 0) \in \mathbb{Z}^n$.

There are four Cartan Type Lie algebras of formal vector fields. One of them is called Special. This algebra is defined as an algebra of divergenceless vector fields

$$S_{n-1} = S_{n-1}(U) = \langle X = u_i \partial_i : Div X = \sum_{i=1}^n \partial_i(u_i) = 0 \rangle.$$

Recall that $S_n(K_n^+)$ is simple, but $L = S_{n-1}(K_n)$ is not simple: its commutant $[L, L]$ is generated by derivations $D_{ij} = \partial_i(u) \partial_j - \partial_j(u) \partial_i, u \in U$ and

$$L/[L, L] = \langle D_{ij} x^{-\theta}, x^{-\theta + \epsilon_i} \partial_i : i = 1, \dots, n \rangle \cong K^{n+1}.$$

Theorem 8.1. Let $U = K_n$.

i) The algebra (U, Jac_n^S) is not simple. It has 1-dimensional center $\langle 1 \rangle$ and the ideal of codimension 1: $\bar{U} = \langle x^\alpha : \alpha \neq -\theta \rangle$. The factor-algebra $(\bar{U} / \langle 1 \rangle, Jac_n^S)$ is simple n -Lie algebra.

ii) Takes place the exact sequence

$$0 \rightarrow Out(U, \cdot, Jac_n^S) \rightarrow Out(U, Jac_n^S) \rightarrow K^2 \rightarrow 0.$$

More exactly, the factor-algebra $Out(U, Jac_n^S) / Out(U, \cdot, Jac_n^S)$ is 2-dimensional and is generated by derivations Δ and $D_{-\theta}$, defined by

$$\Delta = \sum_{i=1}^n x_i \partial_i + n(1-n)^{-1} : x^\alpha \mapsto (|\alpha| + n(1-n)^{-1})x^\alpha,$$

$$D_{-\theta} : x^\alpha \mapsto \delta_{\alpha, -\theta}.$$

iii) The linear maps $D_i : U \rightarrow U, i = 1, \dots, n$, given by

$$D_i : u \mapsto x^{-\theta + \epsilon_i} \partial_i(u),$$

are outer derivations of (U, \cdot, Jac_n^S) . Their classes of derivations in

$Out(U, \cdot, Jac_n^S) = Der(U, Jac_n^S) / Int(U, Jac_n^S)$ form a base. In particular, $dim Out(U, \cdot, Jac_n^S) = n$ and $dim Out(U, Jac_n^S) = n + 2$.

iv) Classes of derivations Δ, D_1, \dots, D_n in $Out(\bar{U}, Jac_n^S) / \langle 1 \rangle$ form a base. In particular, $dim Out(\bar{U}, Jac_n^S) / \langle 1 \rangle = n + 1$.

Corollary 8.2. Let $U = K[x_1^{\pm \frac{1}{n-1}}, \dots, x_n^{\pm \frac{1}{n-1}}]$. Then eigenspaces of the derivation Δ endow the algebra (U, Jac_n^S) by grading. If

$$U_{[k]} = \{u \in U : \Delta(u) = k u\} = \{x^\alpha : |\alpha| = k + n(n-1)^{-1}\},$$

then

$$u_1 \in U_{[k_1]}, \dots, u_n \in U_{[k_n]} \Rightarrow Jac_n^S(u_1, \dots, u_n) \in U_{[k_1 + \dots + k_n]}.$$

Here $k \in (n-1)^{-1}\mathbf{Z}$.

Theorem 8.3. Let $U = K_n^+$. Then the algebra (U^+, Jac_n^S) has 1-dimensional center $\langle 1 \rangle$. Its factor-algebra $(U^+ / \langle 1 \rangle, Jac_n^S)$ is simple n -Lie. It has one outer derivation Δ . In particular, $dim Out(U, Jac_n^S) =$
 $dim Out(U / \langle 1 \rangle, Jac_n^S) = 1$.

Theorem 8.3 follows from theorem 8.1. Therefore, below we can consider only the case $U = K_n$.

Lemma 8.4. Any divergenceless derivation of U is a linear combination of derivations $D_{i,j}(u)$ and derivations $x^{-\theta + \epsilon_i} \partial_i$.

Lemma 8.5. Any derivation of the form $D_{i,j}(u)$, where $i < j, i, j = 1, \dots, n, u \in U$, can be presented as an interior derivation $L_{u_1, \dots, u_{n-1}}$ of the Jacobian algebra Jac_n^S .

Proof. It is easy to see that

$$\begin{aligned} \text{Jac}_n^S(x_1, \dots, x_{i-1}, u, x_{i+1}, \dots, x_{j-1}, v, x_{j+1}, \dots, x_n) = \\ \partial_i(u)\partial_j(v) - \partial_j(u)\partial_i(v). \end{aligned}$$

Therefore,

$$D_{i,j}(u) = (-1)^{n-j} \text{ad}(x_1, \dots, x_{i-1}, u, x_{i+1}, \dots, x_{j-1}, x_{j+1}, \dots, x_n).$$

Lemma 8.6. *The element $x^{-\theta}$ cannot be presented as a Jacobian $\text{Jac}_n^S(u_1, \dots, u_n)$. Any element x^β , where $\beta \in \mathbf{Z}^n, \beta \neq -\theta$, can be presented as a linear combination of elements $\text{Jac}_n^S(u_1, \dots, u_n)$, for some $u_1, \dots, u_n \in U$.*

In other words, the first cohomology group of (U, Jac_n^S) with coefficients in the trivial module is 1-dimensional.

Proof. Since $\text{Jac}_n^S : \wedge^n U \rightarrow U$ is polylinear, if $x^{-\theta} = \text{Jac}_n^S(u_1, \dots, u_n)$, for some $u_1, \dots, u_n \in U$, then

$$\lambda x^{-\theta} = \text{Jac}_n^S(x^{\alpha_1}, \dots, x^{\alpha_n}),$$

for some $\lambda \in K, \alpha_1, \dots, \alpha_n \in \mathbf{Z}^n$. Thus,

$$\begin{aligned} \lambda &= x^\theta \text{Jac}_n^S(x^{\alpha_1}, \dots, x^{\alpha_n}) = \\ &= \sum_{\sigma \in \text{Sym}_n} \text{sign } \sigma x_{\sigma(1)} \partial_{\sigma(1)}(x^{\alpha_1}) \cdots x_{\sigma(n)} \partial_{\sigma(n)}(x^{\alpha_n}) = \\ &= \left(\sum_{\sigma \in \text{Sym}_n} \text{sign } \sigma \alpha_{1,\sigma(1)} \cdots \alpha_{n,\sigma(n)} \right) x^{\alpha_1 + \cdots + \alpha_n}, \end{aligned}$$

where $\alpha_i = (\alpha_{i,1}, \dots, \alpha_{i,n}) \in \mathbf{Z}^n$. Therefore, we come to two conclusions: the first

$$\alpha_1 + \cdots + \alpha_n = 0 \in \mathbf{Z}^n,$$

and the second,

$$\lambda = \det(\alpha_{i,j}).$$

The first relation means that the sum of rows of the matrix $(\alpha_{i,j})$ is 0. Therefore, its determinant is also 0 and by the second relation $\lambda = 0$.

Let $\beta \neq -\theta$. Then $\beta_i \neq -1$ for some i . Therefore, $\beta_i + 1 \neq 0$, and

$$x^\beta = \text{Jac}_n^S(x_1, \dots, x_{i-1}, (\beta_i + 1)^{-1} x^{\beta + \epsilon_i}, x_{i+1}, \dots, x_n).$$

Corollary 8.7. $D_{-\theta} \in \text{Der}(U, \text{Jac}_n^S)$.

Lemma 8.8. *The element $x^{-\theta}$ cannot be presented in the form $x^{-\theta + \epsilon_i} \partial_i(u)$, where $u \in U, i = 1, \dots, n$.*

Proof. Suppose that $\lambda x^{-\theta} = x^{-\theta + \epsilon_i} \partial_i(x^\alpha)$, for some $\alpha \in \mathbf{Z}^n$ and $\lambda \in K$. We have

$$x^{-\theta} = x^{-\theta + \epsilon_i} \partial_i(x^\alpha) = \alpha_i x^{-\theta + \alpha}.$$

Thus $\alpha = 0$, and in particular, $\alpha_i = 0$. So, $\lambda = 0$.

Lemma 8.9. *The linear maps $D_i = x^{-\theta+\epsilon_i}\partial_i : u \mapsto x^{-\theta+\epsilon_i}\partial_i(u)$ are derivations of (U, Jac_n^S) .*

Proof. Take $T_{i,j} = x^{-\theta+\epsilon_i+\epsilon_j} \ln x_j, i < j$. Then $T_{i,j} \notin U = K_n$, but $T_{i,j} \in \tilde{U}$, where $\tilde{U} = K[x_1^{\pm 1}, \dots, x_n^{\pm 1}, T_{i,j}]$ is an extension of U by $T_{i,j}$. We see that $D_i = -D_{i,j}(T_{i,j})$. So, by lemma 8.5, D_i is a derivation of $Jac_n^S(\tilde{U})$. In particular, D_i satisfies the Leibniz rule

$$D_i Jac_n^S(u_1, \dots, u_n) = \sum_{l=1}^n Jac_n^S(u_1, \dots, u_{l-1}, D_i(u_l), u_{l+1}, \dots, u_n),$$

for elements u_1, \dots, u_n of the subalgebra $(U, Jac_n^S) \subset (\tilde{U}, Jac_n^S)$. Since $D_i(u) \in U$, for any $u \in U$, this means that $D_i \in Der(U, J_n^S)$.

Lemma 8.10. *The linear map $\Delta : U \rightarrow U$ given by*

$$\Delta = \sum_{i=1}^n x_i \partial_i + n(1-n)^{-1}$$

is a derivation of the algebra (U, Jac_n^S) .

Proof. Define polynomial f by

$$f(u_1, \dots, u_n) = \Delta(Jac_n^S(u_1, \dots, u_n)) - \sum_{l=1}^n Jac_n^S(u_1, \dots, u_{l-1}, \Delta(u_l), u_{l+1}, \dots, u_n).$$

Notice that $[\partial_i, \Delta] = \partial_i$. Since Jac_n^S is \mathcal{D} -invariant,

$$\rho(\partial_i)f = \rho([\partial_i, \Delta])Jac_n^S = \rho(\partial_i)Jac_n^S = 0.$$

So, f is \mathcal{D} -invariant and by theorem 7.3,

$$f(u_1, \dots, u_n) = \sum_{\alpha(1), \dots, \alpha(n) \in \mathbb{Z}_+^n} \frac{\partial^{\alpha(1)}(u_1)}{\alpha(1)!} \dots \frac{\partial^{\alpha(n)}(u_n)}{\alpha(n)!} pr f(x^{\alpha(1)}, \dots, x^{\alpha(n)}),$$

where $|\alpha(1)| + \dots + |\alpha(n)| = n$.

We see that $pr f : \wedge^n U \rightarrow K$ is uniquely defined by $f(x_1, \dots, x_n)$. In other words,

$$Support(f) \subseteq C^n(R(\pi_1), K) \cong \langle x_1 \wedge \dots \wedge x_n \rangle \cong K.$$

We have,

$$\Delta(1) = n(1-n)^{-1}, \quad \Delta(x_i) = (1-n)^{-1}, \quad Jac_n^S(x_1, \dots, x_n) = 1.$$

Therefore,

$$f(x_1, \dots, x_n) = n(1-n)^{-1} - \sum_{l=1}^n (1-n)^{-1} = 0.$$

So, $Support(f) = \emptyset$, and $pr f = 0$. Thus, by theorem 7.3, $f = 0$. In other words, $\Delta \in Der(U, Jac_n^S)$.

Lemma 8.11. *Derivations $\Delta, D_1, \dots, D_n \in Der(U, Jac_n^S)$ are outer. Moreover, any non-trivial linear combination of derivations D_1, \dots, D_n and Δ is outer.*

Proof. Suppose that

$$\lambda_0 \Delta(v) + \sum_{i=1}^n \lambda_i D_i(v) = Jac_n^S(u_1, \dots, u_{n-1}, v),$$

for some $\lambda_0, \lambda_1, \dots, \lambda_n \in K, u_1, \dots, u_{n-1} \in U$ and for any $v \in U$.

For $v = 1$ we obtain that $n(1-n)^{-1}\lambda_0 = 0$, and $\lambda_0 = 0$.

For $v = x_i$ we have

$$\lambda_i x^{-\theta + \epsilon_i} = (-1)^{n-i} Jac_{n-1}^S(u_1, \dots, u_{n-1}).$$

By lemma 8.6, this is possible only for the case of $\lambda_i = 0$.

Lemma 8.12. *Suppose that $D_{i,j}(x^\beta)u = 0, u \in U$, for any $\beta \in \mathbf{Z}_+^n, |\beta| > 2$. Then $u \in \langle 1 \rangle$.*

Proof. Suppose that $u = \sum_{\alpha \in \mathbf{Z}^n, q \leq |\alpha| \leq s} \lambda_\alpha x^\alpha$ and $\lambda_{\bar{\alpha}} \neq 0$, for some $\bar{\alpha} \in \mathbf{Z}^n$, such that $|\bar{\alpha}| = s$ and $\bar{\alpha} \neq 0$. Then $\bar{\alpha}_i \neq 0$, for some i . Take $\beta = 3\epsilon_j$, for some $j \neq i$. Recall that we suppose that $n > 1$. Then $D_{i,j}(x^\beta) = -3x_j^2 \partial_i$ and

$$D_{i,j}(x^\beta)u = -3\lambda_{\bar{\alpha}} \bar{\alpha}_i x^{\bar{\alpha} + 2\epsilon_j} + w,$$

for some $w \in U$. Notice that w is a linear combination of x^γ , where $\gamma \in \mathbf{Z}^n, |\gamma| \leq s + 2$ and $\gamma \neq \bar{\alpha} + 2\epsilon_j$. Therefore, $-3\lambda_{\bar{\alpha}} \bar{\alpha}_i = 0$, i.e., $\lambda_{\bar{\alpha}} = 0$. The obtained contradiction shows that $s = 0$. By similar arguments it is easy to obtain that $q = 0$.

Lemma 8.13. *Let $D \in Der(U, Jac_n^S)$, and $D(u) = 0$, for any $u \in U^+$. Then $D = \lambda D_{-\theta}$, for some $\lambda \in K$.*

Proof. Suppose that $D(x^\alpha) \neq 0$, for some $\alpha \in \mathbf{Z}^n, \alpha \notin \mathbf{Z}_+^n$ and $D(x^\beta) = 0$, for any $\beta \in \mathbf{Z}^n, |\beta| > |\alpha|$. Notice that

$$Jac_n^S(x_1, \dots, x_{i-1}, u, x_{i+1}, \dots, x_{j-1}, v, x_{j+1}, \dots, x_n) = D_{i,j}(u)v = -D_{i,j}(v)u.$$

For any $\beta \in \mathbf{Z}^n, |\beta| > 2$,

$$|Jac_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_{j-1}, x^\beta, x_{j+1}, \dots, x_n)| > |x^\alpha|.$$

So,

$$D(Jac_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_{j-1}, x^\beta, x_{j+1}, \dots, x_n)) = 0,$$

if $\beta \in \mathbf{Z}_+^n, |\beta| > 2$. Since D is derivation, and $D(u) = 0$, for any $u \in U^+$,

$$\begin{aligned} D(Jac_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_{j-1}, x^\beta, x_{j+1}, \dots, x_n)) = \\ Jac_n^S(x_1, \dots, x_{i-1}, D(x^\alpha), x_{i+1}, \dots, x_{j-1}, x^\beta, x_{j+1}, \dots, x_n), \end{aligned}$$

Thus,

$$D_{i,j}(x^\beta)(D(x^\alpha)) = 0,$$

for any $\beta \in \mathbf{Z}_+^n, |\beta| > 2$. By lemma 8.12,

$$D(x^\alpha) \in \bigcap_{s=1}^n Ker \partial_s = \langle 1 \rangle.$$

So,

$$D(x^\alpha) = \lambda \cdot 1, \quad (6)$$

for some $\lambda \in K$.

Suppose that $\lambda \neq 0$.

Now take $\beta = \epsilon_j$. Then by the Leibniz rule

$$\begin{aligned} D(\partial_i(x^\alpha)) &= D(\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_n)) = \\ &\text{Jac}_n^S(x_1, \dots, x_{i-1}, D(x^\alpha), x_{i+1}, \dots, x_n) = \partial_i(D(x^\alpha)), \end{aligned}$$

and, according to (6),

$$D(\partial_i(x^\alpha)) = 0, \quad (7)$$

for any $i = 1, \dots, n$.

We have

$$\begin{aligned} \text{Jac}_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_{j-1}, x_i x_j, x_{j+1}, \dots, x_n) = \\ x_i \partial_i(x^\alpha) - x_j \partial_j(x^\alpha). \end{aligned}$$

Therefore, by (6) and the Leibniz rule,

$$\begin{aligned} (\alpha_i - \alpha_j) D(x^\alpha) = \\ D(\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^\alpha, x_{i+1}, \dots, x_{j-1}, x_i x_j, x_{j+1}, \dots, x_n)) = 0. \end{aligned}$$

So, if $\lambda \neq 0$, then

$$\alpha_i = t, \quad (8)$$

for some $0 \neq t \in \mathbf{Z}$ and for any $i = 1, \dots, n$.

Take $\beta = \epsilon_i + 2\epsilon_j$. We have

$$\text{Jac}_n^S(x_1, \dots, x_{i-1}, \partial_j(x^\alpha), x_{i+1}, \dots, x_{j-1}, x_i x_j^2, x_{j+1}, \dots, x_n) = (2\alpha_i - \alpha_j + 1)x^\alpha.$$

Then by (6), (8) we obtain that

$$\begin{aligned} (2\alpha_i - \alpha_j + 1) D(x^\alpha) = \\ D(\text{Jac}_n^S(x_1, \dots, x_{i-1}, \partial_j(x^\alpha), x_{i+1}, \dots, x_{j-1}, x_i x_j^2, x_{j+1}, \dots, x_n)) = 0. \end{aligned}$$

So, by (8), $t = -1$ and $D = \lambda D_{-\theta}$.

Lemma 8.14. *Any derivation of (U, Jac_n^S) is a linear combination of some interior derivation and derivations $\Delta, D_{-\theta}, D_1, \dots, D_n$.*

Proof. By lemma 8.13 any derivation D is defined by its restriction on U^+ up to $D_{-\theta}$. Any linear map $F : U^+ \rightarrow U$ is a linear combination of linear maps of the form $x^\alpha \partial^\beta : U \rightarrow U, v \mapsto x^\alpha (\partial^\beta(v))$, where $\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n$. Suppose that $F = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n} \lambda_{\alpha, \beta} x^\alpha \partial^\beta \in \text{Der}(U, J_n^S)$.

Step 1. Any derivation F is a linear combination of Δ and some derivation F' with the property $F'(1) = 0$. Let us prove it. Since 1 is central, $F(1)$ is also central for any derivation F .

The center of U is 1-dimensional and is generated by one element 1. Therefore, $F(1) = \lambda_{0,0}$. If $\lambda_{0,0} \neq 0$, we can take instead of F

$$F' = F - \lambda_{0,0}(1-n)n^{-1}\Delta.$$

Then $F' \in \text{Der}(U, \text{Jac}_n^S)$ and $\lambda'_{0,0} = 0$, if

$$F' = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n} \lambda'_{\alpha,\beta} x^\alpha \partial^\beta.$$

Step 2. Suppose that the derivation F' satisfies the following normalisation

$$F'(1) = 0 \tag{9}$$

Prove that F' can be presented as a linear combination of derivations D_1, \dots, D_n and some interior derivation and some differential operator of differential order > 1 .

Take

$$\bar{F}' = F' - \sum_{i=1}^n \lambda'_{-\theta+\epsilon_i, \epsilon_i} D_i.$$

Then $\bar{F}' \in \text{Der}(U, \text{Jac}_n^S)$ and

$$\bar{F}'(x_i) \in \langle x^\alpha : \alpha \neq -\theta + \epsilon_i \rangle,$$

for any $i = 1, \dots, n$. Let $\bar{F}' = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n} \bar{\lambda}'_{\alpha,\beta} x^\alpha \partial^\beta$. Then

$$\bar{\lambda}'_{\alpha, \epsilon_1} \neq 0 \Rightarrow \alpha_j \neq -1, \text{ for some } j.$$

Take

$$F'' = \bar{F}' + \bar{\lambda}'_{\alpha, \epsilon_1} (\alpha_j + 1)^{-1} D_{1,j}(x^{\alpha+\epsilon_j}).$$

It is easy to see that $F'' \in \text{Der}(U, \text{Jac}_n^S)$, and

$$\lambda''_{\alpha, \epsilon_1} = 0,$$

where $F'' = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n} \lambda''_{\alpha,\beta} x^\alpha \partial^\beta$.

Let us use induction on l and suppose that F'' some $l > 1$ has the following property: $\lambda''_{\alpha, \epsilon_i} = 0$, for any $\alpha \in \mathbf{Z}^n$, if $i < l$ and $\lambda''_{\alpha(l), \epsilon_l} \neq 0$ for some $\alpha(l) \in \mathbf{Z}^n$.

Let $(\tilde{U}, \text{Jac}_{n-l+1}^S)$ be Jacobian algebra of type S with vector space $\tilde{U} = K[x_l^{\pm 1}, \dots, x_n^{\pm 1}]$ and multiplication $\text{Jac}_{n-l+1}^S = \partial_l \wedge \dots \wedge \partial_n$.

Let G be the restriction of F'' to subalgebra $(\tilde{U}, \text{Jac}_{n-l+1}^S)$. Then

$$G(u) = \sum_{\alpha' = (\alpha_1, \dots, \alpha_{l-1}) \in \mathbf{Z}^{l-1}} x^{\alpha'} G_{\alpha'}(u),$$

for any $u \in \tilde{U}$, where $G_{\alpha'}$ is a linear map defined on \tilde{U} with coefficients in \tilde{U} .

Since $F''(x_i) = 0, i < l$ and $\text{Jac}_{n-l+1}^S = i(x_1) \cdots i(x_{l-1}) \text{Jac}_n^S$, then

$$\begin{aligned} G(\text{Jac}_{n-l+1}^S(u_1, \dots, u_n)) &= \\ F'' \text{Jac}_n^S(x_1, \dots, x_{l-1}, u_1, \dots, u_n) &= \\ \sum_{s=l}^n \text{Jac}_n^S(x_1, \dots, x_{l-1}, u_1, \dots, u_{s-1}, F''(u_s), u_{s+1}, \dots, u_n) &= \end{aligned}$$

$$\sum_{s=l}^n \text{Jac}_{n-l+1}(u_l, \dots, u_{s-1}, G(u_s), u_{s+1}, \dots, u_n),$$

for any $u_l, \dots, u_n \in \langle x^\alpha : \alpha \in \mathbf{Z}^n, \alpha_i = 0, i < l \rangle$. Therefore,

$$\begin{aligned} & \sum_{\alpha' \in \mathbf{Z}^{l-1}} x^{\alpha'} G_{\alpha'}(\text{Jac}_{n-l+1}(u_l, \dots, u_n)) = \\ & \sum_{s=1}^n \sum_{\alpha' \in \mathbf{Z}^{l-1}} x^{\alpha'} \text{Jac}_{n-l+1}(u_l, \dots, u_{s-1}, G_{\alpha'}(u_s), u_{s+1}, \dots, u_n) = \\ & \sum_{\alpha' \in \mathbf{Z}^{l-1}} x^{\alpha'} \sum_{s=1}^n \text{Jac}_{n-l+1}(u_l, \dots, u_{s-1}, G_{\alpha'}(u_s), u_{s+1}, \dots, u_n). \end{aligned}$$

In other words, $G_{\alpha'} \in \text{Der}(\tilde{U}, J_{n-l+1}^S)$, for any $\alpha' \in \mathbf{Z}^n, \alpha'_l = \dots = \alpha'_n = 0$. By an inductive suggestion $G_{\alpha'}$ is a linear combination of derivations of $(\tilde{U}, \text{Jac}_{n-l+1}^S)$ of the form $x^{-\sum_{s=l}^n \epsilon_s + \epsilon_j} \partial_j$, where $j = l, \dots, n$ and a derivation of the form $L_{u_l, \dots, u_{n-1}}$, for some $u_l, \dots, u_{n-1} \in \tilde{U}$. Here the derivation $\tilde{\Delta} = \sum_{s=1}^n x_s \partial_s + (n-l+1)/(l-n)$ does not appear because of normalisation (9). Thus, $x^{\alpha'} G_{\alpha'}$ is a linear combination of derivations $A_i := x^{\alpha' - \sum_{s=1}^n \epsilon_s + \epsilon_i} \partial_i, i \geq l$, and some linear operator $B_{\alpha'} := x^{\alpha'} L_{u_l, \dots, u_{n-1}}$. Notice that $\text{Div} A_i = 0, i \geq l$. Moreover, $A_i \in \text{Int}(U, \text{Jac}_n^S)$, because of $\lambda''_{-\theta + \epsilon_i, \epsilon_i} = 0$.

By an inductive suggestion and by lemma 8.4, the divergenceless derivation $L_{u_l, \dots, u_{n-1}}$ is a linear combination of derivations of the form $D_{i,j}(u), l \leq i < j, u \in \tilde{U}$. Therefore, $B_{\alpha'}$, where $\alpha' = (\alpha_1, \dots, \alpha_{l-1}, 0, \dots, 0) \in \mathbf{Z}^n$, is also a linear combination of derivations $D_{i,j}(x^{\alpha'} u), l \leq i < j$. In particular, $B_{\alpha'} \in \text{Int}(U, \text{Jac}_n^S)$.

So, we have proved that G is a linear combination of interior derivations. Therefore, we can add to F'' some linear combination of interior derivations and obtain a new derivation $F''' = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n} \lambda_{\alpha, \beta}''' x^\alpha \partial^\beta$, such that $\lambda_{\alpha, \epsilon_i}''' = 0$, for any $\alpha \in \mathbf{Z}^n$, if $i < l+1$.

Thus, induction on l is possible and finally we obtain that F'' is a sum of some interior derivation and some linear operator

$$H = \sum_{\alpha \in \mathbf{Z}^n, \beta \in \mathbf{Z}_+^n, |\beta| > 1} \mu_{\alpha, \beta} x^\alpha \partial^\beta.$$

Step 3. Prove that $H = 0$. Present H in the form $H = \sum_{\beta \in \mathbf{Z}_+^n, |\beta| > 1} H_\beta \partial^\beta$, where $H_\beta = \sum_{\alpha \in \mathbf{Z}^n} \lambda_{\alpha, \beta} x^\alpha$. Suppose that $H \neq 0$ and $H_{\bar{\beta}} \neq 0$, for some $\bar{\beta} \in \mathbf{Z}_+^n, |\bar{\beta}| = t > 1$ and $H_\beta = 0$, for any $\beta \in \mathbf{Z}_+^n, |\beta| < t$. We have

$$\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^{\bar{\beta}}, x_{i+1}, \dots, x_n) = \partial_i(x^{\bar{\beta}}),$$

$$H(x_i) = 0, \forall i = 1, \dots, n,$$

Thus,

$$H(\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^{\bar{\beta}}, x_{i+1}, \dots, x_n)) = H(\partial_i(x^{\bar{\beta}})) = 0.$$

On the other hand, by the Leibniz rule

$$\begin{aligned} & H(\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^{\bar{\beta}}, x_{i+1}, \dots, x_n)) = \\ & \text{Jac}_n^S(x_1, \dots, x_{i-1}, H(x^{\bar{\beta}}), x_{i+1}, \dots, x_n) = \partial_i(H(x^{\bar{\beta}})). \end{aligned}$$

So, $H(x^{\bar{\beta}}) \in \cap_{i=1}^n \text{Ker } \partial_i = \langle 1 \rangle$. Here $\bar{\beta}$ is any element of \mathbf{Z}_+^n , such that $H_{\bar{\beta}} \neq 0, |\bar{\beta}| > 1$. In particular, $H_{\epsilon_i + \epsilon_j} = 0$ or $H_{\epsilon_i + \epsilon_j} \in \langle 1 \rangle$. Therefore, in any case by the Leibniz rule

$$(\bar{\beta}_i - \bar{\beta}_j)H(x^{\bar{\beta}}) =$$

$$H(\text{Jac}_n^S(x_1, \dots, x_{i-1}, x^{\bar{\beta}}, x_{i+1}, \dots, x_{j-1}, x_i x_j, x_{j+1}, \dots, x_n)) = 0.$$

So, $\bar{\beta}_i = q, i = 1, \dots, n$, for some $0 < q \in \mathbf{Z}$. In other words, $\bar{\beta} = q\theta$. In particular, $t = |\bar{\beta}| = nq \geq n$, and, since $n > 1, t = |\bar{\beta}| = nq > q$. Thus $q+1 \leq t$, and $H(x_i^{q+1}) = 0$ or $H(x_i^{q+1}) \in \langle 1 \rangle$. We have $J_n^S(x_1^{q+1}, \dots, x_n^{q+1}) = (q+1)^n x^{q\theta}$, So, by the Leibniz rule,

$$(q+1)^n H(x^{q\theta}) =$$

$$H(\text{Jac}_n^S(x_1^{q+1}, \dots, x_n^{q+1})) = 0.$$

Hence, $H_{\bar{\beta}} = 0$. Contradiction.

Proof of theorem 8.1. Simplicity of (U, Jac_n^S) was established in [5]. Other statements follow from corollary 8.7 and lemmas 8.9, 8.13 8.10, 8.11 and 8.14.

9. DERIVATIONS OF JACOBIAN ALGEBRAS OF TYPE W

In this section K is the field of characteristic 0 and $U = K_n$ or K_n^+ . Let

$$W_n = W_n(U) = \langle u\partial_i : u \in U, i = 1, \dots, n \rangle$$

be General Cartan Type Lie algebra. This algebra is also called Witt algebra.

Theorem 9.1. *The n -Lie algebra (U, Jac_{n+1}^W) is simple. Any derivation of (U, Jac_{n+1}^W) is interior. Moreover, $\text{Int}(U, \text{Jac}_{n+1}^W)$ is isomorphic to Witt algebra W_n .*

On U we have two multiplications Jac_{n+1}^W and Jac_n^S . They are related by

$$\begin{aligned} \text{Jac}_{n+1}^W(u_1, \dots, u_{n+1}) = \\ (-1)^{n+1} \text{Jac}_n^S(u_1, \dots, u_n)u_{n+1} + \sum_{i=1}^n (-1)^{i+n-1} \text{Jac}_{n,i}^W(u_1, \dots, u_n) \partial_i(u_{n+1}), \end{aligned}$$

where

$$\text{Jac}_{n,i}^W = id \wedge \partial_1 \wedge \dots \wedge \hat{\partial}_i \wedge \dots \wedge \partial_n.$$

Let $W_n + U$ be a semidirect sum:

$$[X + u, Y + v] = [X, Y] + X(v) - Y(u),$$

for any $X, Y \in W_n, u, v \in U$.

Lemma 9.2. *The map $W_n \rightarrow W_n + U$ given by $X \mapsto X + \lambda \text{Div } X$ is a monomorphism for any $\lambda \in K$.*

Proof. The statement is evident, if $\lambda = 0$. Suppose that $\lambda \neq 0$.

The divergence map $X \mapsto Div X$ is 1-cocycle in $Z^1(W_n, U)$:

$$Div[X, Y] = X(Div Y) - Y(Div X).$$

Therefore, for $f = id + \lambda Div$,

$$\begin{aligned} f[X, Y] &= [X, Y] + \lambda Div[X, Y] = \\ &= [X, Y] + \lambda(X(Div(Y)) - Y(Div(X))) = \\ &= [X + \lambda Div X, Y + \lambda Div Y] = [f(X), f(Y)]. \end{aligned}$$

So, f is the homomorphism of Lie algebras.

Suppose that $X \in Ker f$. Then

$$X(u) + \lambda(Div X)u = 0,$$

for any $u \in U$. Take $u = 1$. Then $\lambda(Div X) = 0$. Thus, $X = \sum_{i=1}^n \mu_i \partial_i$. Take now $u = x_i$. We have $0 = X(u) = \lambda_i$. So, $X = 0$.

Lemma 9.3. For any associative commutative algebra U with commuting derivations $\partial_1, \dots, \partial_n$ the algebra (U, Jac_{n+1}^W) is $(n+1)$ -Lie and graded:

$$J_{n+1}^W(U_{[i_1]}, \dots, U_{[i_k]}) \subseteq U_{[i_1 + \dots + i_k]},$$

where

$$U_{[s]} = \langle x^\alpha : |\alpha| = s + 1 \rangle, s \in \mathbf{Z}.$$

Proof. By corollary 6.4 (U, Jac_{n+1}^W) is $(n+1)$ -Lie. It is graded:

$$Jac_{n+1}^W(x^{\alpha(0)}, \dots, x^{\alpha(n)}) \in \langle x^{\alpha(0) + \dots + \alpha(n) - \theta} \rangle,$$

and

$$|Jac_{n+1}^W(x^{\alpha(0)}, \dots, x^{\alpha(n)})| = |\alpha(0) + \dots + \alpha(n) - \theta| = (|\alpha(0)| - 1) + \dots + (|\alpha(n)| - 1) + 1.$$

Lemma 9.4. Any interior derivation of (U, Jac_{n+1}^W) has the form $X - n^{-1}Div X$, where $X \in W_n(U)$.

Proof. Any interior derivation

$$L_{u_1, \dots, u_n} : v \mapsto Jac_{n+1}^W(u_1, \dots, u_n, v)$$

can be presented as a sum of some differential operator of first order and the operator of multiplication to some element of U

$$L_{u_1, \dots, u_n} = X_{u_1, \dots, u_n} + R_{u_1, \dots, u_n},$$

where

$$X_{u_1, \dots, u_n} = \sum_{i=1}^n (-1)^{n+i-1} Jac_{n,i}^W(u_1, \dots, u_n) \partial_i,$$

$$R_{u_1, \dots, u_n} v = (-1)^{n+1} Jac_n^S(u_1, \dots, u_n) v,$$

satisfies the relation

$$\begin{aligned}
Div X_{u_1, \dots, u_n} &= \\
\sum_{i=1}^n (-1)^{n+i-1} \partial_i (id \wedge \partial_1 \wedge \dots \wedge \hat{\partial}_i \wedge \dots \wedge \partial_n)(u_1, \dots, u_n) &= \\
\sum_{i=1}^n (-1)^{n+i-1} (\partial_i \wedge \partial_1 \wedge \dots \wedge \hat{\partial}_i \wedge \dots \wedge \partial_n)(u_1, \dots, u_n) &= \\
(-1)^n \sum_{i=1}^n (\partial_1 \wedge \dots \wedge \partial_i \wedge \dots \wedge \partial_n)(u_1, \dots, u_n) &= \\
(-1)^n n Jac_n^S(u_1, \dots, u_n). &
\end{aligned}$$

In other words,

$$Div X_{u_1, \dots, u_{n-1}} + n R_{u_1, \dots, u_{n-1}} = 0.$$

So, any interior derivation is an element of the subspace $\{X - n^{-1} Div X : X \in W_n(U)\}$.

Lemma 9.5. *Let U be an associative commutative algebra with the space of commuting derivations $\mathcal{D} = \{\partial_1, \dots, \partial_n\}$. Then for any $X \in W_n$ the linear map $g = g_X : U \rightarrow U$ given by $g(u) = X(u) + \lambda Div X u$ is a derivation of the algebra (U, Jac_{n+1}^W) , if and only if $\lambda = -n^{-1}$.*

Proof. Consider the polynomial

$$\begin{aligned}
f(X, u_1, \dots, u_{n+1}) &= \\
g_X(Jac_{n+1}^W(u_1, \dots, u_{n+1})) - \sum_{i=1}^{n+1} Jac_{n+1}^W(u_1, \dots, u_{i-1}, g_X(u_i), u_{i+1}, \dots, u_n). &
\end{aligned}$$

We should prove that $f(u_1, \dots, u_{n+1}) = 0$ for any $u_1, \dots, u_{n+1} \in U$, if and only if $\lambda = -n^{-1}$.

Notice that $g = g_X$ is \mathcal{D} -invariant for any $X \in W_n$:

$$\begin{aligned}
(\rho(\partial_i)g)(u) &= \partial_i(g(u)) - g(\partial_i(u)) = \\
\partial_i(Xu) + \lambda \partial_i(Div X u) - X(\partial_i(u)) - \lambda Div X \partial_i(u) &= \\
\partial_i(X)u + \lambda \partial_i(X)u &= g(\partial_i X)u.
\end{aligned}$$

We know that Jac_{n+1}^S is \mathcal{D} -invariant:

$$\rho(\partial_i)(id \wedge \partial_1 \wedge \dots \wedge \partial_n) = 0.$$

Hence by corollary 7.2 f as a linear combination of compositions of \mathcal{D} -invariant polynomials, is also \mathcal{D} -invariant.

As we mentioned before Jac_{n+1}^W is graded. Notice that g has grade degree $|X|$:

$$g(U_{[s]}) \subseteq U_{[s]+|X|}.$$

Therefore, the polynomial f is also graded.

So, we can use theorem 7.3 to prove that $f = 0$.

Notice that f is skew-symmetric in n parameters u_1, \dots, u_{n+1} . Therefore, for homogeneous $X \in W_n$ and $u_1, \dots, u_{n+1} \in U$,

$$f(X, u_1, \dots, u_{n+1}) \in U_{[0]},$$

if and only if

$$|X| = -1, |u_1| + \dots + |u_{n+1}| = 0$$

or

$$|X| = 0, |u_l| = -1 \text{ for some } l \text{ and } |u_1| + \dots + |\hat{u}_l| + \dots + |u_{n+1}| = 0$$

In other words, if

$$(x^{\alpha(0)} \partial_i, x^{\alpha(1)}, \dots, x^{\alpha(n+1)}) \in \text{Support}(f),$$

then

$$|\alpha(0)| = 0, |\alpha(1)| + \dots + |\alpha(n+1)| = n+1$$

or

$$|\alpha(0)| = 1, |\alpha(l)| = 0, \text{ for some } l \text{ and } |\alpha(1)| + \dots + |\widehat{\alpha(l)}| + \dots + |\alpha(n+1)| = n$$

So, we should check that

$$f(\partial_i, x^{\alpha(1)}, \dots, x^{\alpha(n+1)}) = 0,$$

if $|\alpha(1)| + \dots + |\alpha(n+1)| = n$, or

$$f(x_j \partial_i, x^{\alpha(1)}, \dots, x^{\alpha(n+1)}) = 0,$$

if $\alpha(l) = 0$, for some l and

$$|\alpha(1)| + \dots + |\alpha(\hat{l})| + \dots + |\alpha(n+1)| = n, |\alpha(s)| > 0, s \neq l.$$

The first statement is evident: since ∂_i is a derivation of U , $\text{Div } \partial_i = 0$, and $[\partial_i, \partial_j] = 0$ for all i and j , then $f(\partial_i, x^{\alpha(1)}, \dots, x^{\alpha(n+1)}) = 0$, for any $\alpha(1), \dots, \alpha(n+1)$. Since f is skew symmetric in u_i type parameters, in the second case we can take, say, $l = 1$. Then $|\alpha(2)| = \dots = |\alpha(n+1)| = 1$. So, in the second case we have

$$\begin{aligned} & f(x_j \partial_i, 1, x_1, \dots, x_n) = \\ & x_j \partial_i (\text{Jac}_{n+1}^W(1, x_1, \dots, x_n)) + \lambda \delta_{i,j} (\text{Jac}_{n+1}^W(1, x_1, \dots, x_n)) \\ & \quad - \text{Jac}_{n+1}^W(\lambda \delta_{i,j} 1, x_1, \dots, x_n) \\ & - \sum_{s=1}^n \text{Jac}_{n+1}^W(1, x_1, \dots, x_{s-1}, x_j \partial_i(x_s) + \lambda \delta_{i,j} x_s, x_{s+1}, \dots, x_n) = \\ & x_j \partial_i (\text{Jac}_n^S(x_1, \dots, x_n)) + \lambda \delta_{i,j} (\text{Jac}_n^S(x_1, \dots, x_n)) \\ & \quad - \lambda \delta_{i,j} \text{Jac}_n^S(x_1, \dots, x_n) \\ & - \sum_{s=1}^n \text{Jac}_n^S(x_1, \dots, x_{s-1}, x_j \partial_i(x_s) + \lambda \delta_{i,j} x_s, x_{s+1}, \dots, x_n) = \\ & \quad - \sum_{s=1}^n \delta_{i,s} \text{Jac}_n^S(x_1, \dots, x_{s-1}, x_j, x_{s+1}, \dots, x_n) \\ & - \sum_{s=1}^n \lambda \delta_{i,j} \text{Jac}_n^S(x_1, \dots, x_{s-1}, x_s, x_{s+1}, \dots, x_n) = \\ & - \text{Jac}_n^S(x_1, \dots, x_{i-1}, x_j, x_{i+1}, \dots, x_n) - \lambda n \delta_{i,j} = \end{aligned}$$

$$-\delta_{i,j}(1 + \lambda n).$$

Thus $f = 0$, iff $\lambda = -n^{-1}$.

Corollary 9.6. Any divergenceless derivation of U is also a derivation of (U, Jac_{n+1}^W) .

Lemma 9.7. Suppose that $D(1) = 0, D(x_i) = 0$ for any $i = 1, \dots, n$. Then $D(\partial_i(u)) = \partial_i(D(u))$ for any $u \in U$.

Proof. Since

$$Jac_{n+1}^W(u, 1, x_1, \dots, \hat{x}_i, \dots, x_n) = \partial_i(u),$$

then, by the Leibniz rule

$$\begin{aligned} D(\partial_i(u)) &= D(Jac_{n+1}^W(u, 1, x_1, \dots, \hat{x}_i, \dots, x_n)) = \\ &Jac_{n+1}^W(D(u), 1, x_1, \dots, \hat{x}_i, \dots, x_n) = \partial_i(D(u)), \end{aligned}$$

for any $u \in U$.

Lemma 9.8. Let $U = K[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$. Suppose that $D \in Der(U, Jac_{n+1}^W)$ and $D(u) = 0$, for any $u \in U^+$. Then $D(u) = 0$, for any $u \in U$.

Proof. Suppose that $D(x^\alpha) \neq 0$ for some $\alpha \in \mathbf{Z}^n \setminus \mathbf{Z}_+^n$ and $D(x^\beta) = 0$, for all $\beta \in \mathbf{Z}^n, |\beta| > |\alpha|$. If $\alpha_i + \epsilon_i < 0$, for some i , then we obtain a contradiction: by lemma 9.7 in this case

$$|\alpha + \epsilon_i| > |\alpha| \Rightarrow D(x^{\alpha + \epsilon_i}) = 0 \Rightarrow D(x^\alpha) = (\alpha_i + 1)^{-1} D(\partial_i(x^{\alpha + \epsilon_i})) = 0.$$

Thus, $\alpha_i = -1$, for all $i = 1, \dots, n$.

Notice that

$$Jac_{n+1}^W(u, x_1^2, \dots, x_n^2) = 2^{n-1} x^\theta (2 - \sum_{i=1}^n x_i \partial_i) u,$$

for any $u \in U$. In particular,

$$Jac_{n+1}^W(x^{-2\theta}, x_1^2, \dots, x_n^2) = 2^n (n+1) x^{-\theta}.$$

Thus,

$$\begin{aligned} D(x^{-\theta}) &= \\ &2^{-n} (n+1)^{-1} D(Jac_{n+1}^W(x^{-2\theta}, x_1^2, \dots, x_n^2)) = \\ &2^{-n} (n+1)^{-1} Jac_{n+1}^W(D(x^{-2\theta}), x_1^2, \dots, x_n^2) = \\ &2^{-1} (n+1)^{-1} x^\theta (2 - \sum_{i=1}^n x_i \partial_i) D(x^{-2\theta}). \end{aligned}$$

On the other hand,

$$\begin{aligned} |x_i^{-1}| > |x^{-\theta}| &\Rightarrow D(x_i^{-1}) = 0, i = 1, \dots, n, \\ Jac_{n+1}^W(1, x_1^{-1}, \dots, x_n^{-1}) &= (-1)^n x^{-2\theta}, \end{aligned}$$

and by the Leibniz rule

$$D(x^{-2\theta}) =$$

$$(-1)^n D(\text{Jac}_{n+1}^W(1, x_1^{-1}, \dots, x_n^{-1})) = 0.$$

Therefore, $D(x^{-\theta}) = 0$. Contradiction.

Lemma 9.9. *Any derivation of the algebra (U, Jac_{n+1}^W) has the form $X - n^{-1} \text{Div } X$ for some $X \in W_n(U)$.*

Proof. By lemma 9.8 any derivation of $F \in \text{Der}(U, \text{Jac}_{n+1}^W)$ is defined by its restriction on $U^+ = K[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$. Let D be the restriction of derivation F on U^+ .

Step 1. Prove that

$$D(1) \in \langle x^\alpha : \alpha \in \mathbf{Z}^n : \alpha \neq -\theta \rangle. \quad (10)$$

Notice that $|x^{-\theta}| = -2n \neq 0$. Therefore, if $\sum_{i=1}^n x_i \partial_i D(1) = 0$, then (10) is true.

Consider now the case $\sum_{i=1}^n x_i \partial_i D(1) \neq 0$. Since $1 = \text{Jac}_{n+1}^W(1, x_1, \dots, x_n)$, by the Leibniz rule we have

$$\begin{aligned} D(1) &= \\ \text{Jac}_{n+1}^W(D(1), x_1, \dots, x_n) &+ \sum_{i=1}^n \text{Jac}_{n+1}^W(1, x_1, \dots, x_{i-1}, D(x_i), x_{i+1}, \dots, x_n) = \\ (1 - \sum_{i=1}^n x_i \partial_i) D(1) &+ \sum_{i=1}^n \text{Jac}_n^S(x_1, \dots, x_{i-1}, D(x_i), x_{i+1}, \dots, x_n). \end{aligned}$$

Thus,

$$\sum_{i=1}^n \text{Jac}_n^S(x_1, \dots, x_{i-1}, D(x_i), x_{i+1}, \dots, x_n) = \sum_{i=1}^n x_i \partial_i D(1).$$

Therefore, $D(1)$ is a linear combination of elements of the form $\text{Jac}_n^S(u_1, \dots, u_n)$ and by lemma 8.6, (10) is true.

So, according to (10) $R = \sum_{\alpha \in \mathbf{Z}^n, \alpha \neq -\theta} \lambda_\alpha x^\alpha$, for some $\lambda_\alpha \in K$. If $\lambda_\alpha \neq 0$, then there exists some $i = i(\alpha)$, such that $\alpha_i \neq -1$. Therefore, by lemma 9.5 there exists a derivation of (U, Jac_{n+1}^W) of the form $G := \sum_{\alpha \in \mathbf{Z}^n} \lambda_\alpha (n(\alpha_i + 1)^{-1} x^{\alpha + \epsilon_i} \partial_i - x^\alpha)$. Take $D' = D + G$. It is easy to see that

$$D' \in \text{Der}(U, \text{Jac}_{n+1}^W)$$

and

$$D'(1) = 0.$$

Step 2. Suppose that $D(x^{\bar{\alpha}}) \neq 0$, for some $\bar{\alpha} \in \mathbf{Z}_+^n$, $|\bar{\alpha}| = t$, but $D(x^\beta) = 0$, for all $\beta \in \mathbf{Z}_+^n$, such that $|\beta| < t$. As we have shown above (step 1) we can assume that $t > 0$. Consider separately the cases $t = 1$ and $t > 1$.

The case $t = 1$. By the Leibniz rule for $D \in \text{Der}(U, \text{Jac}_{n+1}^W)$, we have

$$\begin{aligned} D(\text{Jac}_n^S(u_1, \dots, u_n)) &- \sum_{l=1}^n \text{Jac}_n^S(u_1, \dots, u_{l-1}, D(u_l), u_{l+1}, \dots, u_n) = \\ D(\text{Jac}_{n+1}^W(1, u_1, \dots, u_n)) &- \sum_{l=1}^n \text{Jac}_{n+1}^W(1, u_1, \dots, u_{l-1}, D(u_l), u_{l+1}, \dots, u_n) = \\ &\text{Jac}_{n+1}^W(D(1), u_1, \dots, u_n). \end{aligned}$$

Thus $D \in \text{Der}(U, \text{Jac}_n^S)$, if $D(1) = 0$. By theorem 8.1, D as a derivation of U under multiplication Jac_n^S can be presented in the form

$$D = \bar{D} + D_0 + \tilde{D},$$

where

$$\bar{D} = \lambda_{-\theta} D_{-\theta},$$

$$D_0 = \lambda_0 \Delta,$$

$$\tilde{D} = \sum_{i=1}^n \lambda_i x^{-\theta + \epsilon_i} \partial_i + \sum_{i < j, \alpha \in \mathbb{Z}^n} \lambda_{i,j}(\alpha) D_{i,j}(x^\alpha),$$

for some $\lambda_0, \lambda_{-\theta}, \lambda_i, \lambda_{i,j}$.

Notice that \bar{D} is a divergence-free differential operator of first order. By corollary 9.6 any divergence-free derivation D is a derivation of (U, Jac_{n+1}^W) . Since $D(1) = 0$, $\lambda_0 = 0$. So, $\bar{D} = D - \tilde{D}$ is also a derivation of (U, Jac_{n+1}^W) .

Prove that $\bar{D} = 0$. As we mentioned before,

$$\text{Jac}_{n+1}^W(x^{-\theta}, x_1, \dots, x_n) = (n+1)x^{-\theta}.$$

Therefore,

$$\bar{D}(x^{-\theta}) = (n+1)^{-1} \bar{D}(\text{Jac}_{n+1}^W(x^{-\theta}, x_1, \dots, x_n)). \quad (11)$$

Let $\pi : U \rightarrow \langle 1 \rangle$ be projection to $\langle 1 \rangle$. Notice that

$$\pi(\bar{D}(x^{-\theta})) = \lambda_{-\theta},$$

$$\pi(\text{Jac}_{n+1}^W(\bar{D}(x^{-\theta}), x_1, \dots, x_n)) = \lambda_{-\theta},$$

Take projections to $\langle 1 \rangle$ from the both parts of (11). We find that

$$\lambda_{-\theta} = (n+1)^{-1} \lambda_{-\theta}.$$

So, $n\lambda_{-\theta} = 0$, and $\lambda_{-\theta} = 0$, $\bar{D} = 0$.

The case $t > 1$. Prove that this case is not possible. By lemma 9.7 $\partial_i D(x^{\bar{\alpha}}) = 0$, for any $i = 1, \dots, n$. So, $D(x^{\bar{\alpha}}) = \lambda \cdot 1$, for some $0 \neq \lambda \in K$.

Notice that

$$\text{Jac}_{n+1}^W(u, x_1, \dots, x_n) = (1 - \sum_{i=1}^n x_i \partial_i)u,$$

for any $u \in U$. Therefore, by the Leibniz rule,

$$(1 - |\bar{\alpha}|)\lambda = (1 - |\bar{\alpha}|)D(x^{\bar{\alpha}}) =$$

$$D(\text{Jac}_{n+1}^W(x^{\bar{\alpha}}, x_1, \dots, x_n)) =$$

$$\text{Jac}_{n+1}^W(D(x^{\bar{\alpha}}), x_1, \dots, x_n) = \lambda.$$

So, $t\lambda = 0$, and $\lambda = 0$. Contradiction.

Summarize the results obtained in all these steps and cases. We see that any derivation of (U, Jac_{n+1}^W) can be presented as a linear combination of derivations of the form $X - n^{-1} \text{Div } X$, where $X \in W_n(U)$.

Proof of theorem 9.1. Suppose that J is an ideal of U under $(n + 1)$ -multiplication $\omega = Jac_{n+1}^W$. Then J is ideal of U under n -multiplication $i(1)\omega = Jac_n^S$. Since (U, Jac_n^S) is simple [5], $J = 0$ or $J = U$. So, (U, Jac_{n+1}^W) is simple.

Other statements of theorem 9.1 follow from lemma 9.9.

REFERENCES

- [1] P. Cauteron, *Some remarks concerning Nambu mechanics*, Lett. Math. Phys., **37**(1996), 103-116.
- [2] Y.L. Daletskii, L.A. Takhtajan, *Leibniz and Lie algebra structures for Nambu algebra*, Lett. Math. Phys., **39**(1997), 127-141.
- [3] A.S. Dzhumadil'daev, *A remark on spaces of invariant differential operators*, Vestnik Moskov.Univ, Ser1, mat.,mech., 1982, No.2, 49-54 = engl.transl. Moscow Univ. Math. Bull., **37**(1982), No.2, p.63-68.
- [4] A.S. Dzhumadil'daev, *Central extensions of infinite-dimensional Lie algebras*, Funct.Anal.Appl., **26**(1992), No.4, p.21-29 = engl.transl. 246-253.
- [5] V.T. Filippov, *n-Lie algebras*, Sib. Mat. J. **26**(1985), No.6, 126-140 = engl.transl. Siberian Math.J., **26**(1985), No.6, 879-891.
- [6] V.T. Filippov, *On n-Lie algebra of jacobians*, Sib.Mat.J., **39**(1998), No.3, 660-669 = engl.transl. Siberian Math. J., **39**(1998), No.3, 573-581.
- [7] A.G. Kurosh, *Multi-operator rings and algebras*, Uspechi Matem.Nauk, **24**(1969), No.1, 3-15.
- [8] Y.Nambu, *Generalized Hamiltonian mechanics*, Phys. Rev., D **7**, 2405-2412, 1973.
- [9] L.A. Takhtajan, *On the foundation of the generalized Nambu mechanics*, Commun. Math. Phys., **160**(1994), 295-315.
- [10] L.A. Takhtajan, *A higher order analog of the Chevalley-Eilenberg complex and the deformation theory of n-gebres*, Algebra i Analis, **61**(1994), No.2, 262-272 = engl.transl. St. Petersburg Math. J., **6**(1995), No.2, 429-438.